

HIGH ACCURACY AND HIGH RIGIDITY BALLSCREW ACTUATOR

SG, SE, SC SERIES



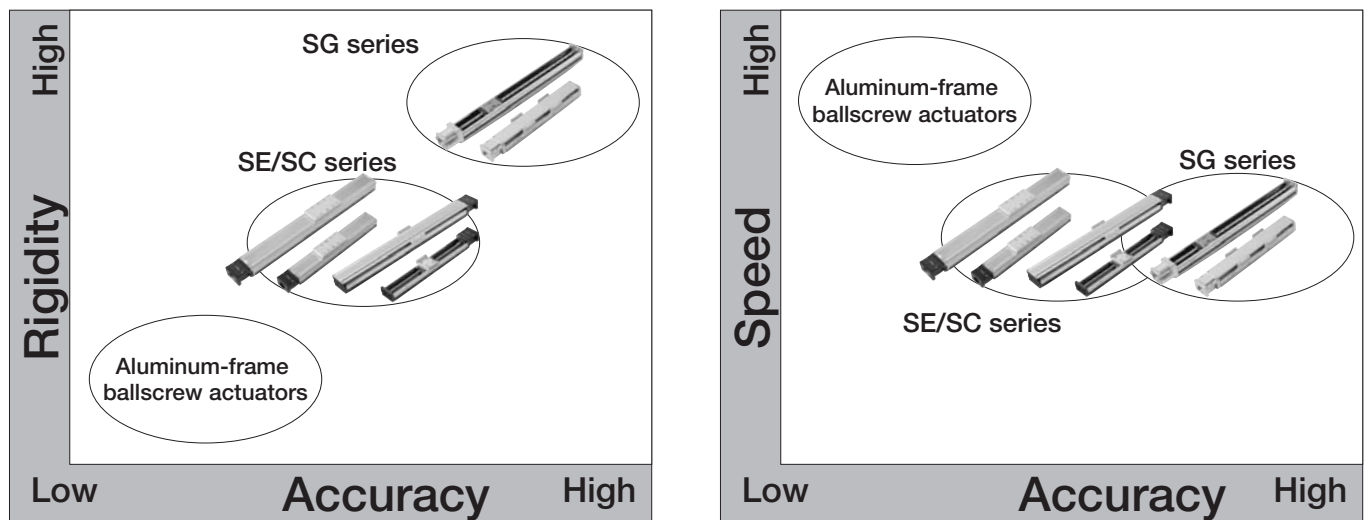
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BALLSCREW ACTUATORS

A ballscrew actuator of KURODA is a compact single-axis unit consisting of a ball screw and a slide guide. With its slide block set in U-guide rail, the actuator has achieved low-profile design and compact shape, making it possible to considerably reduce necessary space as compared with the usual table type structure. Despite of its compact structure, the actuator with U-guide rail shows high rigidity against bending moment and deflection, and it can be applied to a structure supported by one end. The linear motion unit, which is gothic arched and in 4 points-contact structure, makes it possible to deliver high precision and high rigidity.

POSITIONS OF BALLSCREW ACTUATORS



WIDE VARIATIONS

Model No.	SG series						SE series				SC series (Note 2)		
	SG20	SG26	SG33	SG3320	SG46	SG55	SE15	SE23	SE30	SE45	SC23	SC30	SC45
Performance grade (Note 1)	P: Repeated positioning accuracy $\pm 1 \mu\text{m}$ H: Repeated positioning accuracy $\pm 3 \mu\text{m}$						U: Repeated positioning accuracy $\pm 5 \mu\text{m}$ W: Repeated positioning accuracy $\pm 10 \mu\text{m}$						
Screw shaft dia. (mm)	6	8	10	12	15	20	6	8	10	15	8	10	15
Lead (mm)	1	○					○						
	2		○	●			○	○	●		○	●	
	4							●	○		●	○	
	5	○	○	○		●	●	○	○	○	○	○	○
	8							●			●		
	10			○		○	●			○	○	○	○
	20				○	○	○			○			○

○ : In-stock items ● : Manufactured by order

(Note 1) The above table shows precision information on repeated positioning accuracy in particular, as an example.

Performance of actuators may be different from the values shown above, depending on applied options and usage.

For other precision information, refer to description pages for each series.

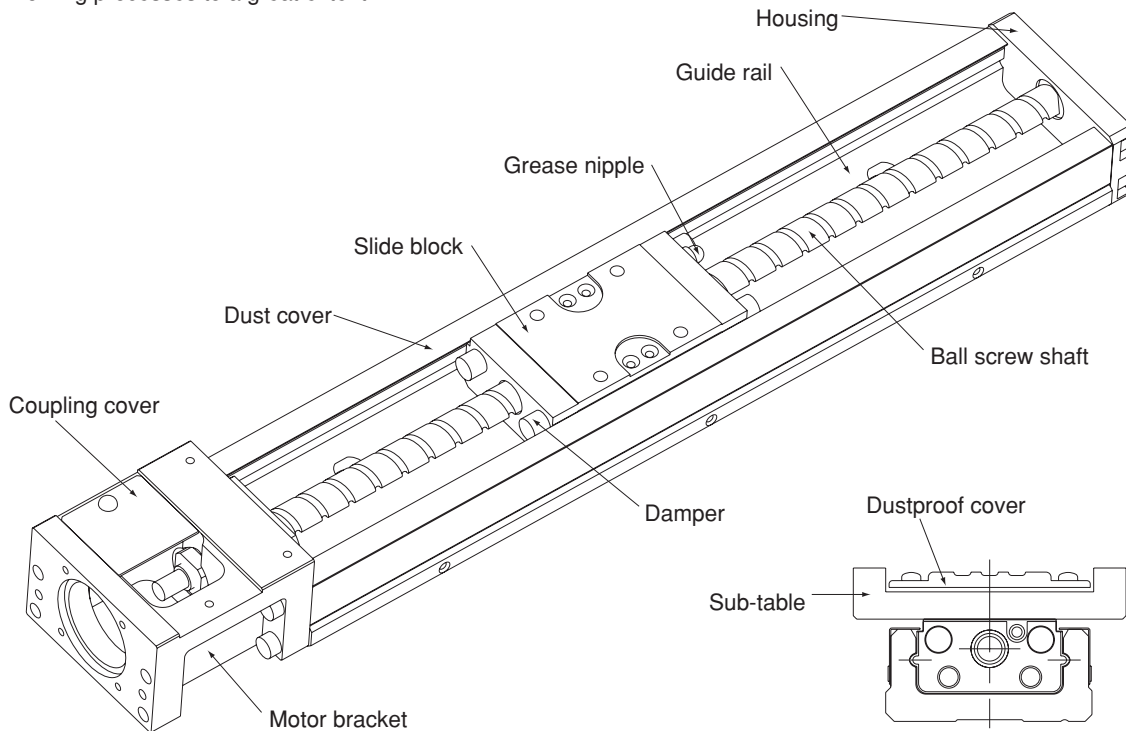
(Note 2) SC series is a full-cover version of SE series ballscrew actuators.

For more information, refer to front matter 5, pages 6 and 89 to 105.

FEATURES OF SG/SE SERIES

■ No necessity for adjustment

Ball screw and slide guide are integrated in ballscrew actuator, eliminating the need for complicated fine adjustment and reducing the number of working processes to a great extent.

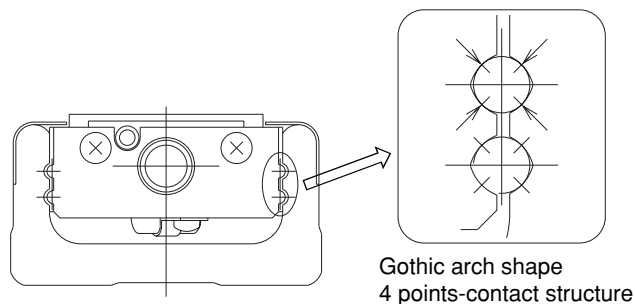


■ High rigidity

With U-guide rail, rigidity of ballscrew actuator has remarkably improved despite of its compact structure, making it possible to be applied even to a structure supported at only one end.

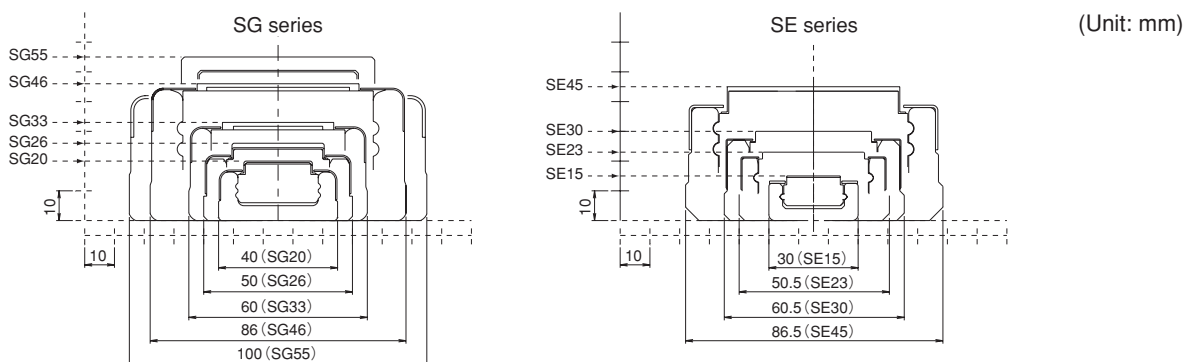
■ High accuracy

Linear motion unit uses "4 or 2 Ballway of 4 points-contact" structure to assure high rigidity. Guide rail, slide block and ball screw shaft are precisely worked, making accurate positioning possible.

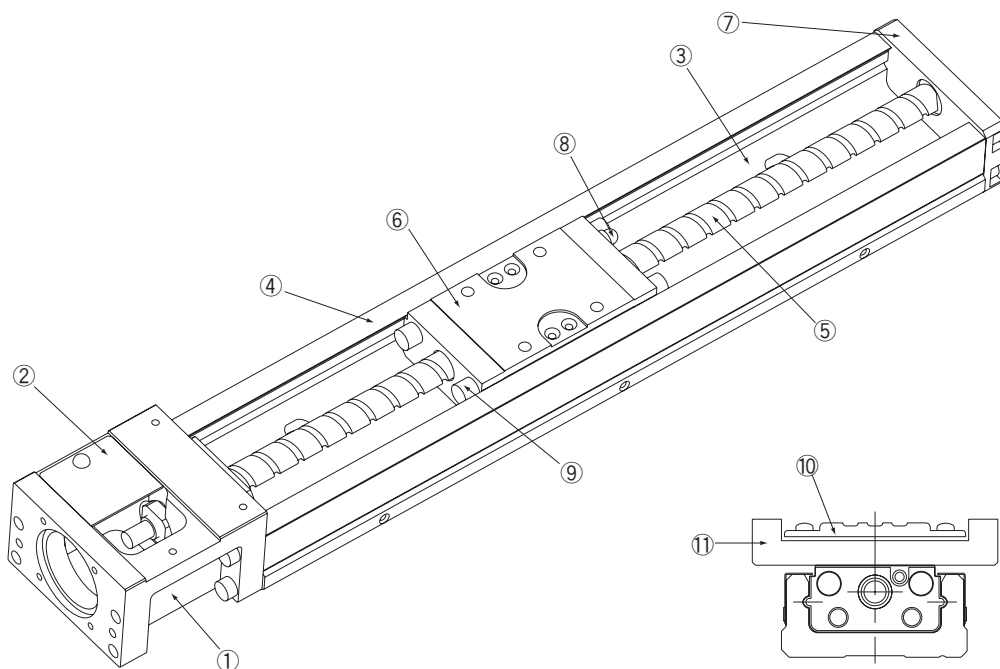


■ Space-saving

With its slide block set in U-guide rail, the actuator has achieved low-profile design and compact shape, making it possible to considerably reduce necessary space as compared with usual table type structure.



KEY COMPONENTS AND MATERIALS OF SG AND SE SERIES

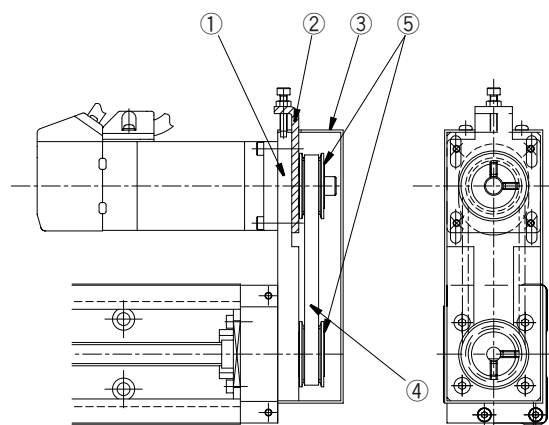


No.	Part name	Material	Remarks
①	Motor bracket	Aluminum alloy	Anodized treatment or baking finish
②	Coupling cover	Aluminum alloy	Anodized treatment
③	Guide rail	Stainless steel (SG20, SG26) Carbon steel(SG33, SG46, SG55, SE15, SE23, SE30, SE45)	Black coating (Note 1)
④	Dust cover	Aluminum alloy	Anodized treatment
⑤	Ball screw shaft	Chromium-molybdenum steel (SG series) Carbon steel (SE series)	
⑥	Slide block	Chromium-molybdenum steel	
⑦	Housing	Aluminum alloy	Anodized treatment or baking finish
⑧	Grease nipple	Stainless steel	
⑨	Damper (Note 2)	Synthetic rubber	
⑩	Dustproof cover	Aluminum alloy	Anodized treatment
⑪	Sub-table	Aluminum alloy	Anodized treatment

(Note 1) Guide rails made from stainless steel are not surface-treated.

(Note 2) Damper position of SG series is different from SE series. For more information, refer to dimensions of each series.

(Note 3) Stainless steel is used for bolts and machine screws to joint components of actuator.



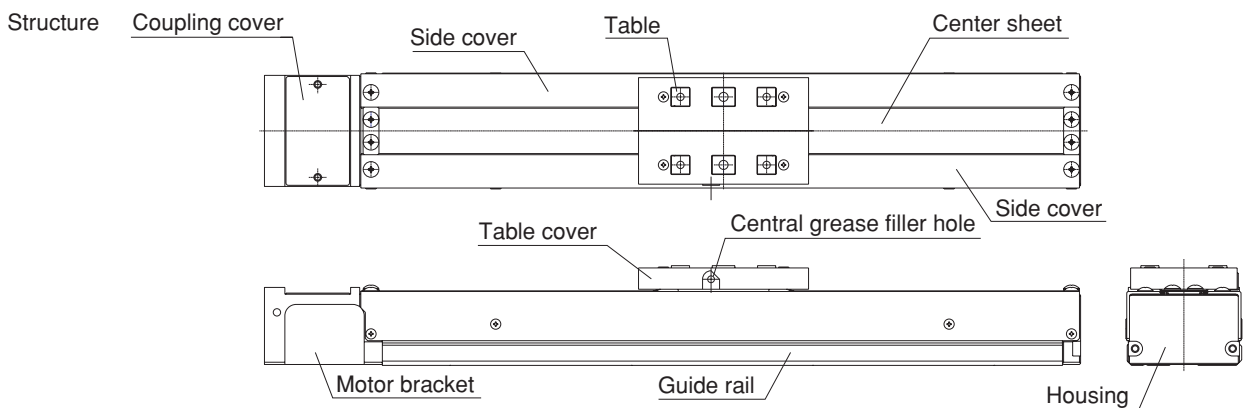
No.	Part name	Material	Remarks
①	Motor mounting plate	Rolled steel	Black coating
②	Tension plate	Stainless steel	
③	Pulley cover	Stainless steel (SG series) Cold-rolled steel plate (SE/SC series)	Anti corrosive black coating (Note 2)
④	Timing belt	Resin	
⑤	Timing pulley	Aluminum alloy	

(Note 1) Stainless steel is used for tension bolts and nuts.

(Note 2) Anti corrosive black coating of pulley cover applies to SE and SC series.

FEATURES OF SC SERIES (FULL-COVER TYPE)

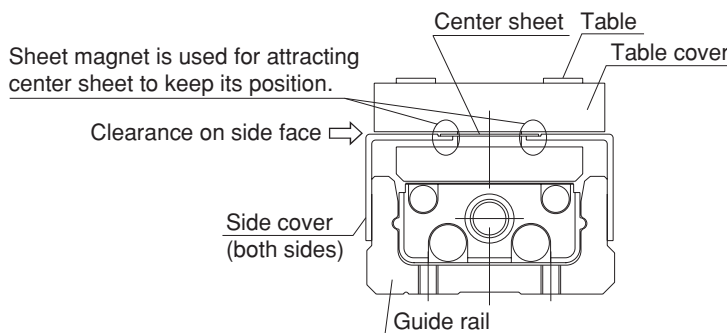
Full-cover type SC series, built on KURODA SE series, has remarkably improved its dust-preventive performance.



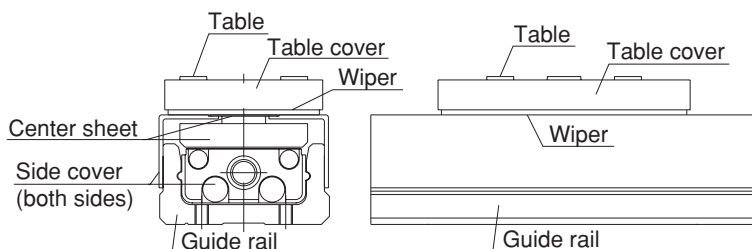
Remarkably improved dust prevention!

Compared to SE series with dustproof cover, dust prevention has been remarkably improved through making clearance on side face of actuator as narrow as it can be and effectively applying new center sheet designed to straddle the tables, so as to prevent entry of dust.

Center sheet is a flexible stainless sheet having a structure to keep its position and to prevent it from being lifted.



For further improved dust prevention, a wiper can be optionally equipped so that a gap between bottom of table cover and side cover/center sheet is filled.



Down-sized body meeting space-saving needs!

SC series has full-cover type body with the same width and dimensions as SE series' guide rail. Replacing SE series with the full-cover type SC series requires just the same mounting space (width) as SE series (Note that mounting height is different).

Easy maintenance!

In order for more efficient grease-up work, which is usually found cumbersome, a central grease filler hole is provided on the side face of the table, as standard equipment of SC series.

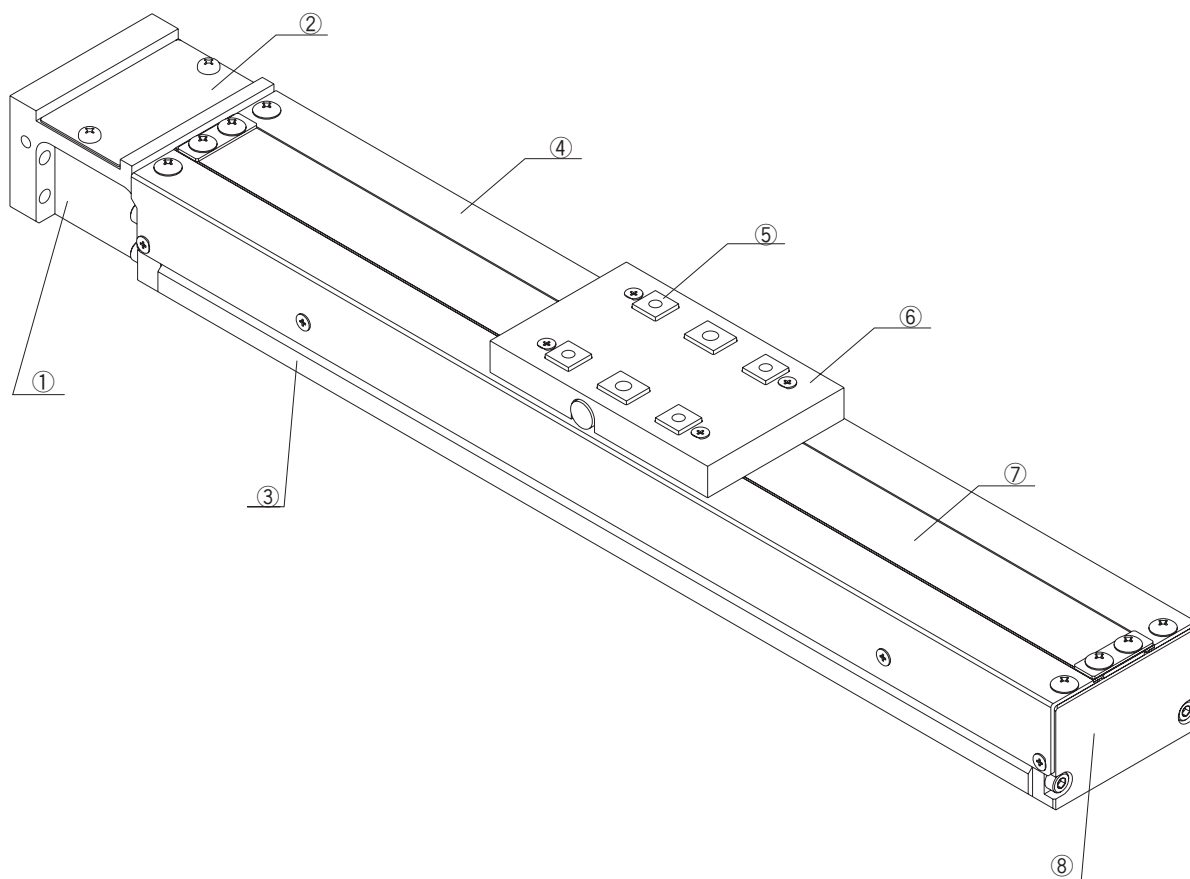
Supplying grease to ball screws and guide parts can be completed at a time through the central grease filler hole. (A plug is equipped with standard spec. model).

Grease nipple to be attached to grease filler hole is available as an option. (For more information, refer to pages 96, 100, and 104.)

Guide with remarkable rigidity!

Having steel U-guide rails similar to SG/SE series, SC series shows high rigidity despite of its compact structure, and it can be applied to a structure supported by one end. (For more information, refer to front matter 11.)

KEY COMPONENTS AND MATERIALS OF SC SERIES



No.	Part name	Material	Remarks
①	Motor bracket	Aluminum alloy	Anodized treatment
②	Coupling cover	Aluminum alloy	Anodized treatment
③	Guide rail	Carbon steel	Black coating
④	Side cover	Aluminum alloy	Anodized treatment
⑤	Table	Aluminum alloy	Anodized treatment
⑥	Table cover	Synthetic resin	
⑦	Center sheet	Stainless steel	
⑧	Housing	Aluminum alloy	Anodized treatment

(Note 1) Ball screws used for SC series have the same specifications as SE series.

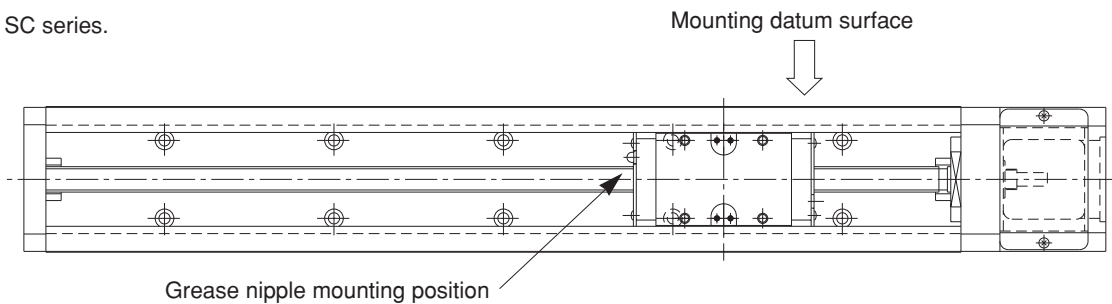
(Note 2) Stainless steel is used for bolts and screws to joint components of actuator.

VARIATIONS OF SLIDE BLOCK

Two types of actuator with long block and short block are available. Additional types with either 2 long blocks or 2 short blocks are also available. Appropriate type can be selected from the variations according to your purpose of use.

● With 1 long block: A

Applied to SG, SE, and SC series.

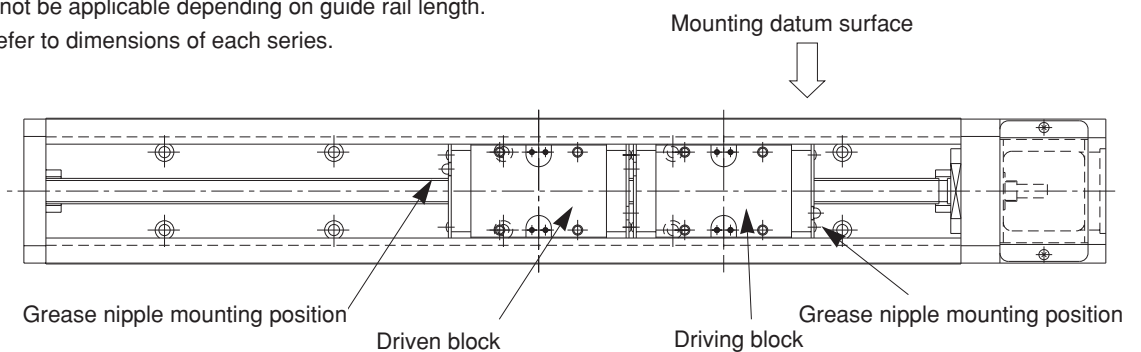


● With 2 long blocks: B

Applied to SG and SE series. (Not available for SC series.)

This configuration may not be applicable depending on guide rail length.

For more information, refer to dimensions of each series.

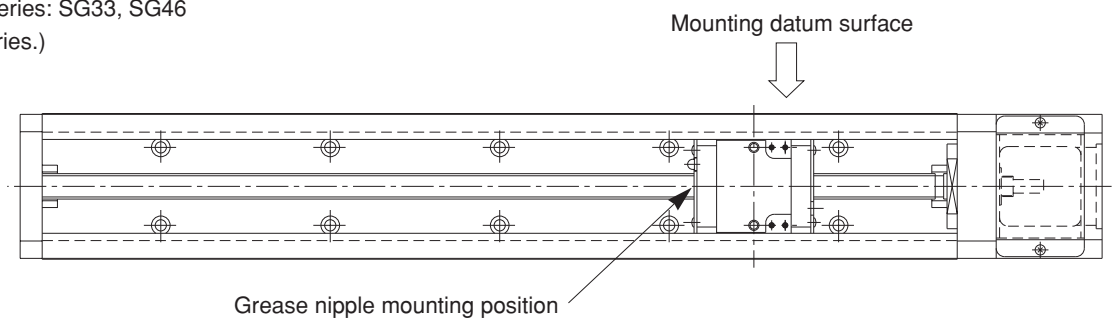


● With 1 short block: C

Applicable size in SE series: SE45

Applicable size in SG series: SG33, SG46

(Not available in SC series.)

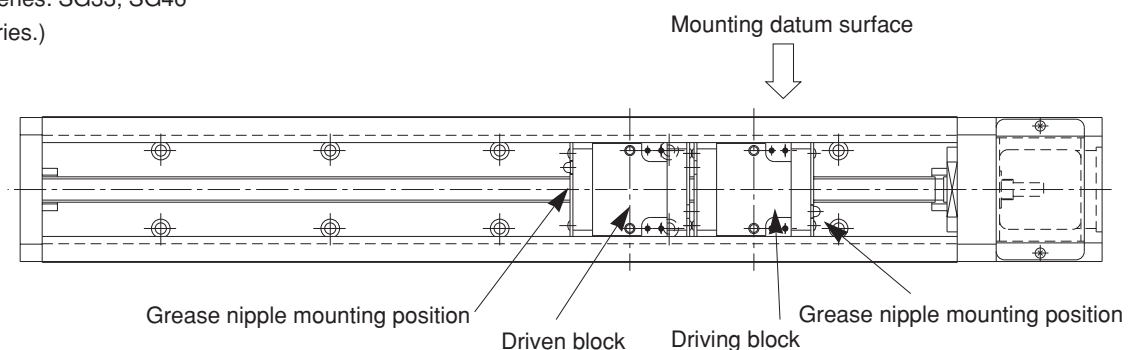


● With 2 short blocks: D

Applicable size in SE series: SE45

Applicable size in SG series: SG33, SG46

(Not available in SC series.)



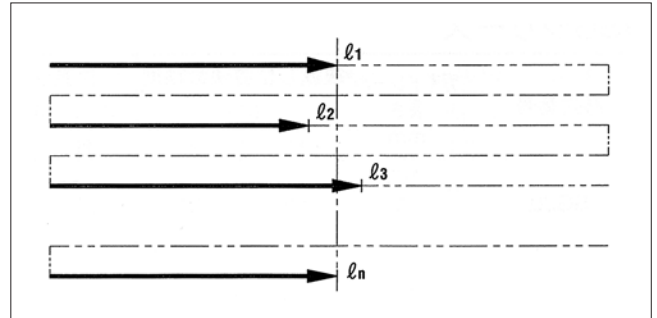
SUMMARY OF ACCURACY INDICATORS

Performance of ballscrew actuators are shown using various accuracy indicators described below.
 For details in tolerance of the accuracy indicators, refer to table of performance (accuracy) information for each series.

● Repeated positioning accuracy

Repeat positioning of slide block in the same direction 7 times, measure stop position of slide block and halve maximum difference between obtained readings. Perform this measurement at the center and both ends of travel distance. Maximum value among obtained value is used as measured value.

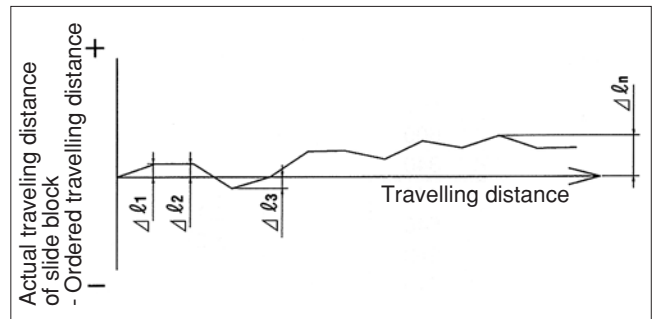
Repeated positioning accuracy
 $= \pm 1/2 ((\text{maximum value of } \varrho_n) - (\text{minimum value of } \varrho_n))$



● Positioning accuracy

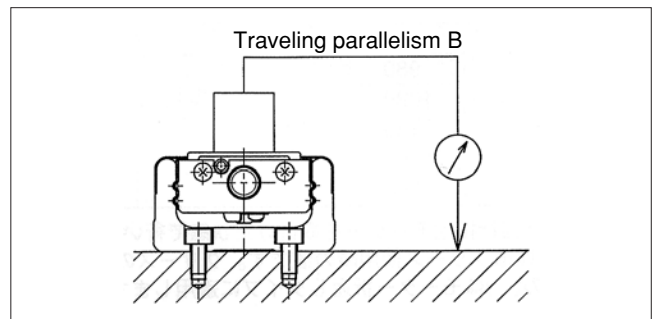
Position slide block properly in a fixed direction and use the obtained position as datum point. Perform positioning of slide block in the same direction and measure difference between actual travelling distance of slide block from datum point and distance ordered to be traveled from datum point. Perform this measurement throughout stroke range and use maximum value.

Positioning accuracy $= (\Delta \varrho_n)_{\text{max}}$



● Traveling parallelism B

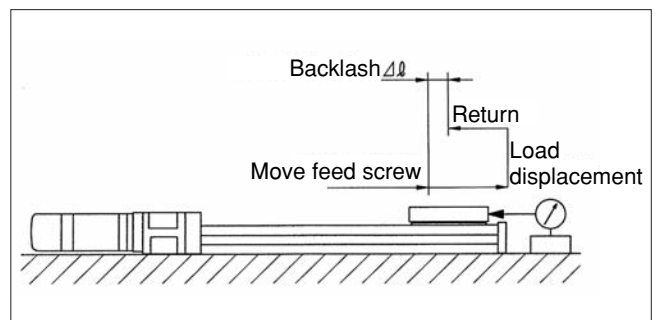
Fix indicator at the center of slide block and apply it to surface plate equipped with guide rail. Move slide block throughout traveling distance and use maximum distance among readings of test indicator as measured value.



● Backlash

Move slide block by rotating ball screw shaft and read test indicator when slide block is slightly moved and use its reading as reference value. Move slide block from this state in the same direction by pressuring prescribed load and measure difference between reading of test indicator with load removed and reference value. Perform this measurement at the center and both ends of traveling distance and use maximum value as a measured value.

Backlash $= \Delta \varrho$



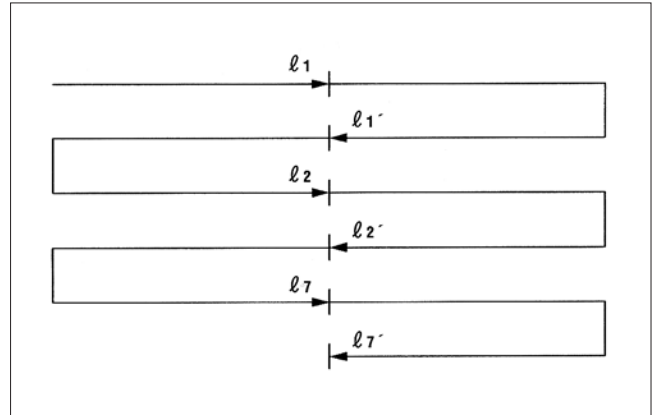
- Firmly tighten the fixed part and connection of the ballscrew actuator.
 Improper mounting of the body may adversely affect safety and accuracy depends on the circumstances.

REFERENCE DATA ON ACCURACY

ACCURACY OF UNIT PRODUCT

● Lost Motion

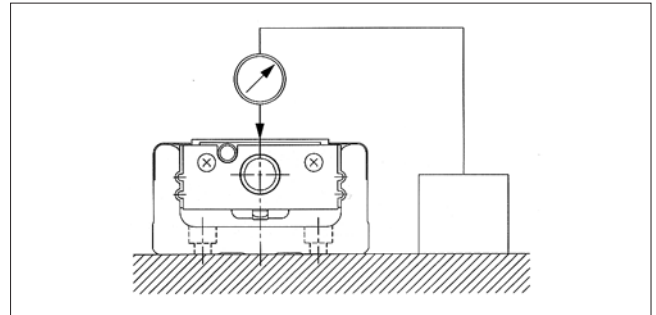
Perform positioning in a positive (or negative) direction and measure the position (l_1). Move the slide block in the same direction and perform positioning in a negative (or positive) direction and measure the position (l_1'). Move it further in the same direction and thereafter repeat the procedure in the positive and negative directions seven times each. Obtain the differences of the average values of the stop positions. Conduct this measurement for the entire moving range and use the obtained maximum value as a measured value.



● Traveling Parallelism A

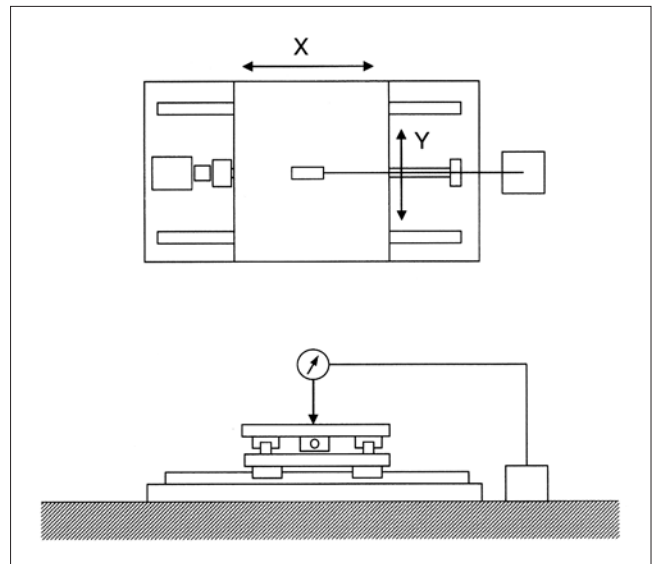
In the case of ballscrew actuators:

Set dial gauge on surface plate, fix indicator on top of slide block, obtain the maximum difference of dial gauge readings in measurable moving range in longitudinal direction of slide block. And use it as a measured value. Since the measurable range is small for ballscrew actuators, Traveling Parallelism B is used as the measurement method for all of the cases except for a few exceptions.



In the case of X-Y stages:

Set dial gauge on surface plate, fix indicator at the center of table, obtain the maximum difference of dial gauge readings in entire moving range in X-Y direction. The maximum difference is used as a measured value.



REFERENCE DATA ON ACCURACY

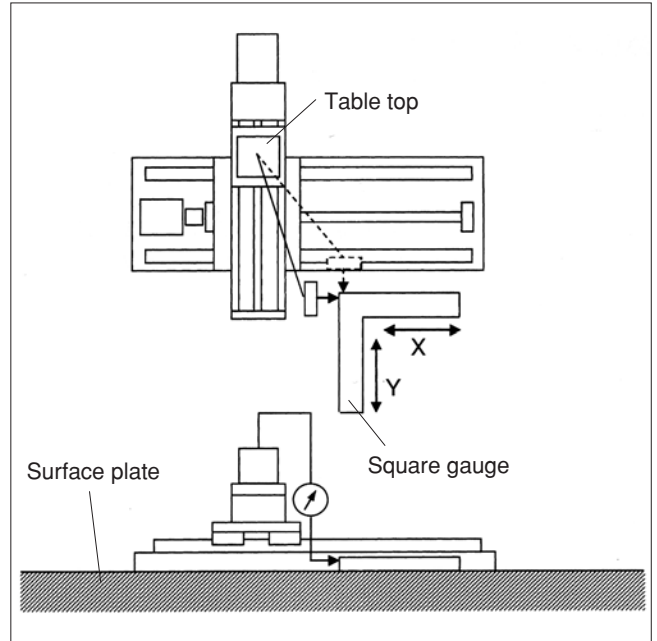
ACCURACY OF UNIT PRODUCT

● Squareness

In case squareness cannot be measured on the table top:

Set a dial gauge on the table top. On surface plate close to the table travel range, fix a square gauge in parallel to X (or Y) travel direction.

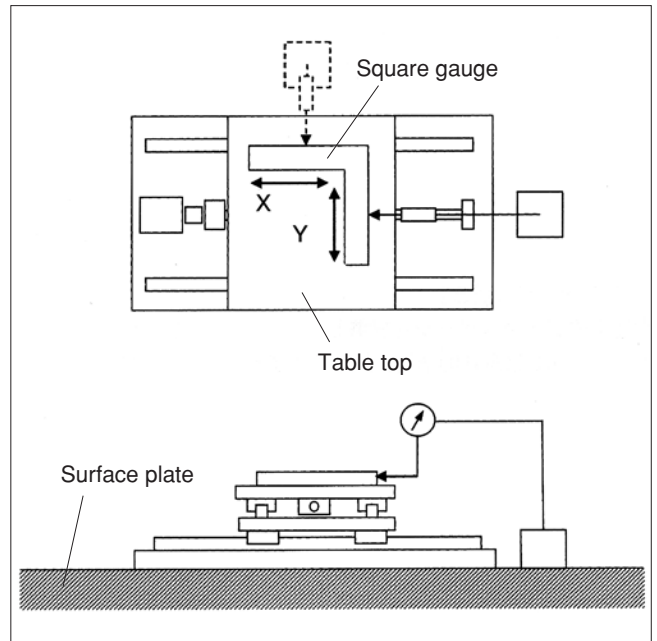
Place a fix indicator against the side of square gauge parallel to Y (or X) travel direction. The maximum reading value of the dial gauge in the entire travel range is a measured value of squareness.



In case squareness can be measured on the table top:

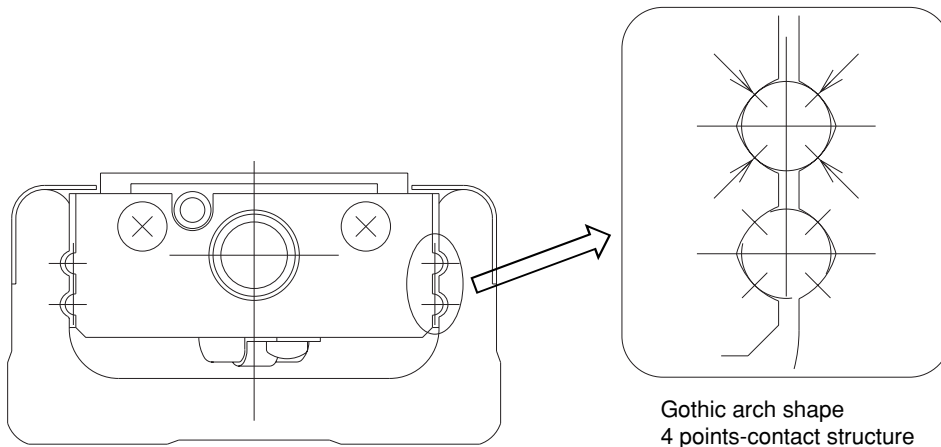
Set a dial gauge on surface plate. On the table top, fix a square gauge in parallel to X (or Y) travel direction.

Place a fix indicator against the side of square gauge parallel to Y (or X) travel direction. The maximum reading value of the dial gauge in the entire travel range is a measured value of squareness.



RIGIDITY

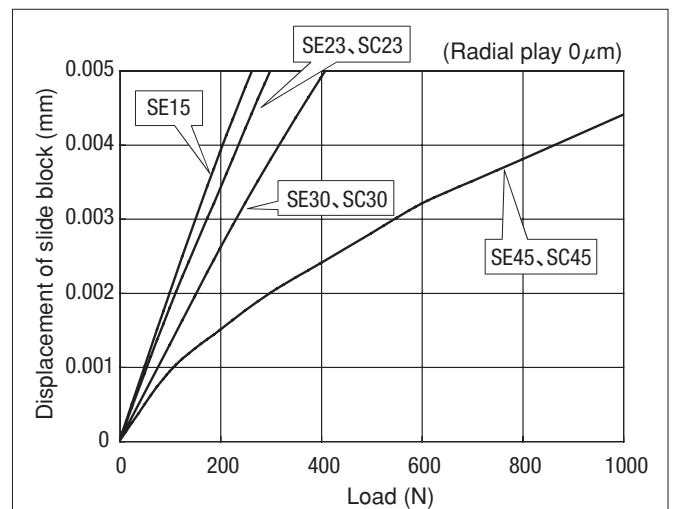
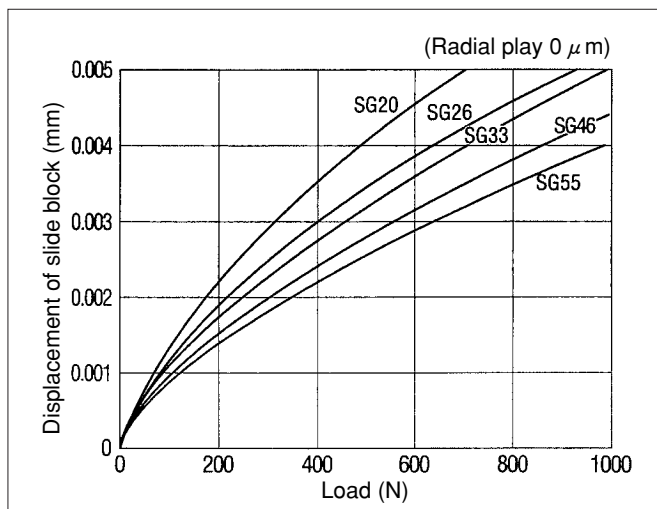
Linear motion units of SG, SE, and SC series, having gothic-arched grooves and 4 points-contact structure on guide rails and slide blocks, have attained high rigidity. Displacement by each radial load in each size with long block configuration is shown below as a reference.



● Displacement of Slide block by Radial Load

SG series

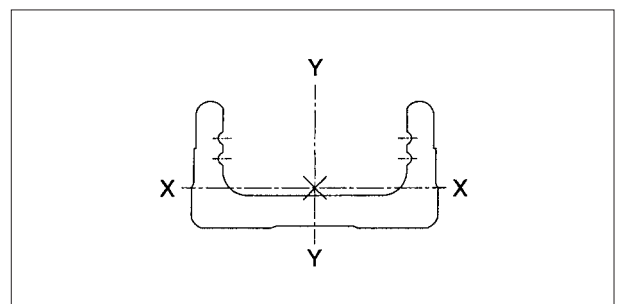
SE/SC series



● Sectional Secondary Moment of Guide Rail

The following table shows sectional secondary moments of guide rails in each size.

Model No.	Sectional secondary moments (mm ⁴)		Mass (kg/100mm)
	I _x (X axis)	I _y (Y axis)	
SG20	6.50×10 ³	6.00×10 ⁴	0.250
SG26	1.69×10 ⁴	1.47×10 ⁵	0.380
SG33	5.11×10 ⁴	3.42×10 ⁵	0.600
SG46	2.42×10 ⁴	1.49×10 ⁶	1.240
SG55	2.29×10 ⁵	2.28×10 ⁶	1.500
SE15	2.71×10 ³	2.36×10 ⁴	0.147
SE23, SC23	1.44×10 ⁴	1.37×10 ⁵	0.410
SE30, SC30	3.88×10 ⁴	3.14×10 ⁵	0.560
SE45, SC45	1.45×10 ⁵	1.26×10 ⁶	1.110



OPTION AND MANUFACTURING BY ORDER

Category	Item		SG series					SE series				SC series			
			SG20	SG26	SG33	SG46	SG55	SE15	SE23	SE30	SE45	SC23	SC30	SC45	
Option	Motor bracket configuration	Motor bracket	○	○	○	○	○	○	○	○	○	○	○	○	○
		Intermediate flange	○	○	○	○	○	○	○	○	○	○	○	○	○
		R0/RN type bracket (Note 1)	○	○	○	○	○	—	—	○	○	—	○	○	○
		Parallel motor mounting unit	—	—	○	○	—	—	—	○	○	—	○	○	○
	Type of cover	Without dustproof cover	○	○	○	○	○	○	○	○	○	—	—	—	—
		With dustproof cover	○	○	○	○	○	○	○	○	○	—	—	—	—
		Standard full-cover (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○	○
		Full-cover with grease nipple (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○	○
		Full-cover with wiper (Note 2)	—	—	—	—	—	—	—	—	—	○	○	○	○
	Sensor	Photo-microsensor	○	○	○	○	○	—	○	○	○	○	○	○	○
		Proximity sensor	○	○	○	○	○	○	○	—	—	○	—	—	—
	Surface treatment (Note 3)		○	○	○	○	○	○	○	○	○	○	○	○	○
	Dust preventive grease (KURODA C-grease)		○	○	○	○	○	○	○	○	○	○	○	○	○
	Dowel pin hole		○	○	○	○	○	—	○	○	○	—	—	—	—
	Manufactured by order (Note 8)	Intermediate stroke		●	●	●	●	●	●	●	●	●	●	●	●
Bellows		●	●	●	●	●	—	●	●	●	—	—	—		
Grease filler hole (Note 4)		●	●	●	●	●	—	●	●	●	—	—	—		
XY bracket		●	●	●	●	●	●	●	●	●	●	●	●		
Motor assembling		●	●	●	●	●	●	●	●	●	●	●	●		
Long rail configuration		●	●	●	●	—	●	●	●	●	●	●	●		
Grease (Note 5)		●	●	●	●	●	●	●	●	●	●	●	●		
Motor bracket configuration (Note 6)		●	●	●	●	●	●	●	●	●	●	●	●		
Sensor (Note 7)		●	●	●	●	●	●	●	●	●	●	●	●		

○: Option —: Not available ●: Manufactured by order

- (Note 1) R0 type bracket is applied to SG series and RN type is applied to SE and SC series.
- (Note 2) Full-cover type with wiper and with grease nipple is applied only to SC series.
- (Note 3) Anti corrosive black coating (film thickness 1-2 μ m) is provided as surface treatment. For other types of surface treatment, consult KURODA.
- (Note 4) Grease filler hole for SG and SE series is applied to the configuration with sub-table.
- (Note 5) Any grease application other than standard or option grease applications will be provided on a manufactured by order basis.
- (Note 6) Ballscrew actuator with motor bracket or intermediate flange configuration other than standard or option configuration will be provided on a manufactured by order basis.
- (Note 7) Ballscrew actuator requiring a sensor other than option configuration or two sensors attached on both ends will be provided on a manufactured by order basis.
- (Note 8) For ballscrew actuators to be provided on a manufactured by order basis, specifications will be determined after consultation with customers. Please consult KURODA after completing the Specification Data Sheet attached at the end of this catalogue.

HOW TO INTERPRET MODEL NO.

Model No.	Lead	Slide block	Guide rail length	Performance grade	Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
SG33	10	A	500	P	A1	C	C	N	N	PS
①	②	③	④	⑤	⑥	⑦	⑧	⑨	⑩	⑪
Model No. of Main Body					Model No. of Option					

① Model of ballscrew actuator

The 2-digits number represents height of mounting surface, from the bottom face of guide rail to top face of slide block. (For SG/SE series with dustproof cover and SC series, Model No. of the unit used as base of the body is shown.)

SG series	SG20	SG26	SG33	SG46	SG55
SE/SC series	SE15	SE/SC23	SE/SC30	SE/SC45	

② Lead of ball screw

Permissible speed varies depending on the lead. For more information, refer to dimensions of each series.

Lead	SG series					SE/SC series			
	SG20	SG26	SG33	SG46	SG55	SE15	SE/SC23	SE/SC30	SE/SC45
1mm	○					○			
2mm		○				○	○		
4mm								○	
5mm	○	○	○				○	○	○
10mm			○	○				○	○
20mm			○	○	○				○

③ Variation of slide blocks and number of blocks to be mounted

For configuration with 2 slide blocks, a driving block and driven block in combination is mounted. For more information, refer to dimensions of each series.

④ Guide rail length

For more information, refer to dimensions of each series. Please note that the guide rail length is different from overall length or maximum stroke length of actuator.

Model No.	Standard guide rail length									
SE15	100	150	200							
SE23, SC23	150	200	250	300						
SE30, SC30	150	200	300	400	500	600	700	750		
SE45, SC45	540	640	740	840	940					
SG20	100	150	200							
SG26	150	200	250	300						
SG33	150	200	300	400	500	600*				
SG46	340	440	540	640	740	840*	940*	1040*	1140*	1240*
SG55	980	1080	1180	1280*	1380*					

- Asterisk (*) item in the above table applies only to performance grade H.
- For long rail configurations, please consult KURODA.

⑤ Performance of ballscrew actuators, including various positioning accuracy indicators and traveling parallelism

For more information on accuracy, refer to a table of accuracy information for each series.

⑥ Motor bracket configuration

Intermediate flange may be used in combination with basic configuration. For more information, refer to a table of motor bracket configurations and motor option for each series.

⑦ Type of cover

For more information, refer to dimensions of each series.

⑧ With or without sensor / type of sensor

For more information, refer to dimensions of each series.

⑨ With or without surface treatment applied on guide rails and ball screws

With standard specifications (Symbol N), only guide rails are treated with black coating (except for guide rails made from stainless steel).

⑩ Type of grease applied on slide blocks and ball screws of ballscrew actuators

With standard specifications, Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) is contained.

⑪ With or without dowel pin holes




The column will be left blank (no symbol) if actuator is without dowel pin holes. For more information, refer to configuration drawings for each series.




FOR SAFETY USE

Be sure to read the following instructions before use.
For common instructions, refer to the text of this catalog.

The following safety precautions recommend the correct usage of our products to prevent an injury and a damage. These precautions are classified into 3 categories : "DANGER", "WARNING" and "CAUTION" according to the degree of possible injury or damage and the degree of impendence of such injury or damage.
Be sure to follow all these precautions, as they include important contents regarding safety.

 DANGER	 WARNING	 CAUTION
Indicates an impending hazardous situation that may arise due to improper handling or operation and could result in a serious injury or death.	Indicates a potentially hazardous situation that may arise due to improper handling or operation and could result in a serious injury or death.	Indicates a potentially hazardous situation that may arise due to improper handling or operation and could result in an injury or property damage only.

Be sure to obey "Labor Safety and Sanitation Law" and other safety rules and regulations in addition to these precautions. There is some situation that may lead to a serious result according to circumstances, even if it is mentioned in the category of "CAUTION". Be sure to follow these precautions, as they contain important matters.

 WARNING
<ul style="list-style-type: none"> • Select a ballscrew actuator properly. As operating conditions for products mentioned in this catalog are diversified, the applicability of ballscrew actuator to the intended system should be determined by the total system designer or the person who determined specifications for such system after conducting an analysis and testing as necessary. The person who determined the applicability of the system shall be responsible for assuring the intended system performance and safety. When configuring a system, the system designer should thoroughly examine all specifications for such a system by referring to the latest product catalog and data, and also take into consideration the possibility of equipment troubles. • The ballscrew actuator should be handled by persons who have sufficient knowledge and rich experience. Thoroughly read this catalog and operation manual before use. <ul style="list-style-type: none"> · Never disassemble the ballscrew actuator. Dust can enter the inside, degrading the accuracy of the module and causing an accident. When the ballscrew actuator has been disassembled from necessity, return it to our company for repair and reassembling. (In this case, repairing charges are required.) · When mounting a ballscrew actuator to a machine and dismantling it from machine, check that a fall prevention means has been taken and the moving part of the machine has been fixed beforehand. • When using the ballscrew actuator in the following conditions or environments, take the proper safety measures and consult KURODA beforehand. <ul style="list-style-type: none"> · Conditions and environments other than specified and outdoor use. · Applications to nuclear power equipment, railroads aircraft, vehicles, medical equipment, equipment connected with food and drink, and the likes. · Applications which require extreme safety and will also greatly affect men and property. • During operation, make sure to keep your hands away from either of stroke ends, where slide block moves, to prevent your finger from being caught. • During operation, make sure to keep your hands away from screws and axis terminals of ball screw shaft, which are rotating parts, to prevent your hands from being caught. • Pay adequate attention not to allow the actuators to be used for military purpose including for arms and weapons.



BALLSCREW ACTUATOR/COMMON INSTRUCTIONS

Be sure to read the following instructions before use.
Also refer to "FOR SAFETY USE".

DESIGN

WARNING

- Especially when there is the possibility that the ballscrew actuator is dangerous to the human body, provide it with a protective cover.

When there is the possibility that the load and the moving part of the ballscrew actuator are dangerous to the human body, design the structure to prevent the human body from touching such load and moving part directly.

- Firmly tighten the fixed part and connection of the ballscrew actuator. Improper mounting of the body may adversely affect safety and accuracy according to circumstances.
- Take into consideration the behavior of the ballscrew actuator in an emergency.

When the machine is immediately stopped in an emergency by a person or by a safety device in case of power failure or system trouble, the motion of the module can injure the human body and can damage the machine. So design the machine to prevent an injury to the human body and a damage to the machine.

SELECTION

WARNING

- Check specifications.
Be sure to use the ballscrew actuator within the given specifications.
- When selecting a rigid type as coupling for connecting a motor, consult KURODA.

MOUNTING

CAUTION

- Be careful not to dent and flow the body and the mounting surface of the table, side cover, and center sheet.

Such dent or flaw will degrade parallelism of mounting surface, resulting in rattling of the guide and increased slide resistance. Note that, since the center sheet of SC series are very thin, such dent or flaw may ruin its dust preventive capability or lead to damage of the sheet function.

- When connecting the ballscrew actuator to a load with an external support or guide, do so in accordance with a proper connecting method and perform centering satisfactorily.
- When mounting a load, do not apply an excessive shock or moment.

If the ballscrew actuator receives external force exceeding the permissible moment, the guide will loosen and sliding resistance will increase.

- Do not start the system until it is confirmed that the ballscrew actuator works properly.

After mounting the ballscrew actuator, perform an appropriate functional test and make sure that it is correctly mounted and works safely without fail before starting the system.

- Although corners of components, such as motor bracket, housing, side cover, and center sheet, are beveled, pay enough attention not to hurt yourself when handling them.

OPERATING ENVIRONMENT

DANGER

- Do not use the ballscrew actuator in a place where an explosive atmosphere exists.

WARNING

- Do not use the ballscrew actuator in an atmosphere containing corrosive gases, chemicals, seawater, water and vapor and in a place where it can be stained with such matters.
- When using the ballscrew actuator in a place where it is exposed to dust, cuttings, spatters, etc., fit a protective cover or other protector.
- Do not use the ballscrew actuator in a vibratory or shockable place ; otherwise causing a bad condition or breakdown.

When using the ballscrew actuator in such an environment, consult KURODA.

CAUTION

- Since the SC series is equipped with sheet magnet on side covers for attracting center sheet to keep its position, be careful not to have the magnet contaminated with iron power or metallic fragments.

LUBRICANTS

CAUTION

- Unless otherwise specified, the nut contains Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) as a lubricant.

Checking and supplying lubricant

Check the lubricant 2 to 3 months after the ball screw is used for the first time. If it is extremely dirty, wipe off old grease and apply new grease. Then, check and supply the lubricant once every year as a general rule. However, as the service life of lubricants varies according to operating conditions and environment, adjust the intervals properly.

When feeding additional grease (lubricant), use the same brand of grease as initially contained.

With SC series, a central grease filler hole (M3) is provided on side surface of table, making it possible for the grease to be supplied to ball screw and guide through the filler hole.

Supply additional grease as necessary, preferably with the interval indicated above. When adding grease, 2 dispenses by grease gun (approx. 1 to 2 cc) should be supplied.

After supplying additional grease, operate the table to the extent of full stroke to apply the grease over the component. Wipe off excess grease attached around the central grease filler hole.

- Do not use at high temperature over 60 celsius degree.

As resin is used in ballscrew actuator, use at lower temperature than 60 celsius degree. For ballscrew actuator with sensor, use at lower temperature than 55 celsius degree.

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VARIATIONS

Model No.	SG20	SG26	SG33	SG3320	SG46	SG55
Performance grade	P: Repeated positioning accuracy $\pm 1 \mu\text{m}^*$ (Ball screw - lead accuracy C3 grade, axial clearance) H: Repeated positioning accuracy $\pm 3 \mu\text{m}^*$ (Ball screw - lead accuracy C5 grade, axial clearance)					
Screw shaft dia. (mm)	6	8	10	12	15	20
lead (mm)	1	○				
	2		○	●		
	5	○	○	○	●	●
	10			○	○	●
	20				○	○



○: In-stock items ●: Manufactured by order

(Note 1) Asterisk (*) items may be different from the values shown above, depending on applied options and usage.

SG series

HOW TO INTERPRET MODEL NO.

Model	Lead	Slide block	Guide rail length (Note 4)	Performance grade
SG**	**	*	****	*
SG20	1, 5	A: With 1 long block B: With 2 long blocks	100, 150, 200	P grade • Repeated positioning accuracy $\pm 1 \mu\text{m}$ • Lead accuracy C3 • Axial clearance 0mm
SG26	2, 5	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	H grade • Repeated positioning accuracy $\pm 3 \mu\text{m}$ • Lead accuracy C5 • Axial clearance 0.005mm or less
SG33	5, 10, 20	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	150, 200, 300, 400, 500, 600*	
SG46	10, 20		340, 440, 540, 640, 740, 840*, 940*, 1040*, 1140, 1240*	
SG55	20	A: With 1 long block B: With 2 long blocks	980, 1080, 1180, 1280*, 1380*	

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	*
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease (KURODA C-grease)	PS: Dowel pin hole provided No symbol: Not provided
A0, A1, A3, A5, A6, A8, A9, AA, R0					
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□		N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor			
A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□					
A0, A1, A2, A3, A4, R0					

(Note 1) With standard surface treatment (Symbol: N), guide rails of SG20 and SG26 are not treated with anti corrosive coating. For SG33, SG46 and SG55, only guide rails are treated with black coating as the standard surface treatment.

(Note 2) With standard grease (Symbol: N), Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) is contained in slide block and ball screw components.

(Note 3) Asterisk (*) items in the table apply only to performance grade H.

(Note 4) For specifications of guide rail with long rails or intermediate stroke with non-standard length, consult KURODA.

SPECIFICATIONS

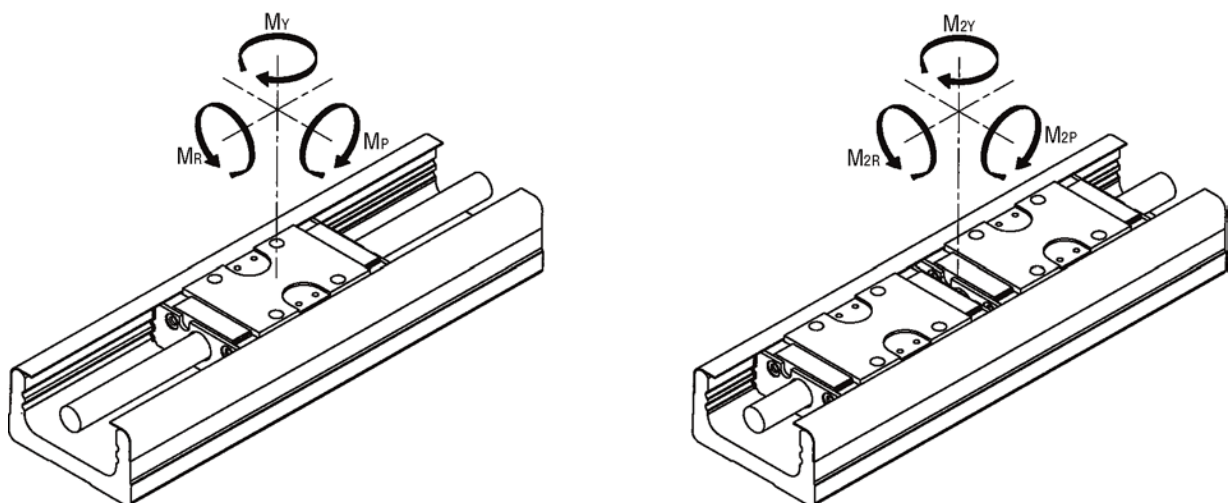
SG series

Model No.		SG2001		SG2005		SG2602		SG2605		SG3305		SG3310		SG3320		SG4610		SG4620		SG5520															
Performance grade		H	P	H	P	H	P	H	P	H	P	H	P	H	P	H	P	H	P	H	P														
Guide	Radial clearance	μm		-3~0	-6~-3	-3~0	-6~-3	-4~0	-8~-4	-4~0	-8~-4	-3~0	-7~-3	-3~0	-7~-3	-3~0	-7~-3	-5~0	-11~-5	-5~0	-11~-5	-6~0	-18~-6												
	Long block	Basic dynamic load rating	C	kN	4.27				7.78				12.6				29.8				43.2														
			Co	kN	7.89				14.98				22.7				51.2				74.0														
		Static permissible moment	M_P	N·m	35				99				181				610				1,088														
			M_{2P}	N·m	199				550				1,035				3,285				5,465														
			M_Y	N·m	42				118				215				727				1,297														
			M_{2Y}	N·m	237				656				1,233				3,914				6,513														
			M_R	N·m	101				255				500				1,612				2,701														
	M_{2R}	N·m	201				509				1,000				3,224				5,402																
	Short block	Basic dynamic load rating	C	kN	Not available				Not available				7.8				19.9				Not available														
			Co	kN	Not available				Not available				11.4				28.8				Not available														
		Static permissible moment	M_P	N·m	Not available				Not available				49				207				Not available														
			M_{2P}	N·m	Not available				Not available				368				1,336				Not available														
			M_Y	N·m	Not available				Not available				59				246				Not available														
			M_{2Y}	N·m	Not available				Not available				439				1,593				Not available														
M_R			N·m	Not available				Not available				250				907				Not available															
M_{2R}	N·m	Not available				Not available				500				1,814				Not available																	
Ball screw	Shaft diameter	mm		6				8				10				12				15				20											
	Lead	mm		1		5		2		5		5		10		20		10		20		20													
	Spacer to ball ratio			—		—		—		1:1		—		1:1		—		1:1		—		2:1		—		2:1									
	Basic dynamic load rating	Ca	kN	0.63		0.65		2.60		2.35		3.35		2.11		2.20		1.39		2.32		1.46		4.40		2.77		4.40		3.36		5.40		4.12	
	Basic static load rating	Coa	kN	1.34		0.92		3.64		3.30		5.90		2.95		3.50		1.75		4.05		2.03		7.90		3.95		7.90		5.27		10.50		7.00	
	Precision grade			C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3	C5	C3				
	Axial clearance	mm		~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0	~0.005	0				
Fixed side bearing	Model No. of bearing	AC5-14DF or equivalent				AC6-16DF or equivalent				708ADFP5 or equivalent				7001ADFP5 or equivalent				7002ADFP5 or equivalent																	
	Basic dynamic load rating	Cb	kN	1.31				1.79				4.40				6.77				7.74															
	Basic static load rating	Cob	kN	1.25				1.76				4.36				7.45				9.50															

(Note 1) Static permissible moment, M_{2P} and M_{2Y} , means the values for when 2 slide blocks are used in close contact with each other.

(Note 2) For your use of P grade model of SG20 and SG26 at small stroke (SG2001: 7mm or less, SG2005: 25mm or less, SG2602: 14mm or less, SG2605: 25mm or less) and at high-frequency reciprocation, consult KURODA.

DIRECTION OF MOMENT



ACCURACY

SG series

Model No.	Guide rail length (mm)	Repeated positioning accuracy (μm)		Positioning accuracy (μm)		Travelling parallelism B (μm)		Backlash (μm)		Starting torque ($\text{N}\cdot\text{m}$)	
		H	P	H	P	H	P	H	P	H	P
SG20	100	± 3	± 1	50	20	25	10	5	2	0.01	0.012
	150										
	200										
SG26	150	± 3	± 1	50	20	25	10	5	2	0.015	0.04
	200										
	250										
	300										
SG33	150	± 3 (± 5)	± 1 (± 3)	30	15	25	10	5	2	0.07	0.15
	200			35	20						
	300			40	25						
	400			70	—	35	15				
	500					—	—				
	600			—	—	—	—				
SG46	340	± 3 (± 5)	± 1 (± 3)	35	20	35	15	5	2	0.10	0.15
	440			40	25						
	540			50	30						
	640			80	—	50	—				
	740		—								—
	840		100	—	—	—					
	940										
	1040										
	1140										
	1240		—	—	—	—					
SG55	980	± 3	± 1	80	35	50	25	5	2	0.12	0.17
	1080			40	30		0.20				
	1180			100	—		—				—
	1280		—	—	—	—					
	1380										

(Note 1) Measurement is to be performed with KURODA's specified motor mounted.

(Note 2) Above starting torque value is applied when the standard grease is used. The value may change depending on the properties of the grease.

(Note 3) The values enclosed in brackets in the table are applied to a parallel motor mounting.

INERTIA

Inertia for slide block and ball screw of ballscrew actuator is shown in the following table.

(Unit : $\times 10^{-5} \text{kg}\cdot\text{m}^2$)

Model No.	Guide rail length (mm)	Without dustproof cover				With dustproof cover			
		Long block		Short block		Long block		Short block	
		1 block	2 blocks	1 block	2 blocks	1 block	2 blocks	1 block	2 blocks
		A	B	C	D	A	B	C	D
SG2001	100	0.0134	—	—		0.0135	—	—	
	150	0.0183	0.0185			0.0184	0.0187		
	200	0.0233	0.0235			0.0234	0.0237		
SG2005	100	0.0176	—	—		0.0200	—	—	
	150	0.0226	0.0270			0.0250	0.0318		
	200	0.0276	0.0320			0.0300	0.0368		
SG2602	150	0.0608	—	—		0.0616	—	—	
	200	0.0765	0.0783			0.0773	0.0797		
	250	0.0922	0.0939			0.0929	0.0954		
	300	0.1080	0.110			0.1090	0.1110		
SG2605	150	0.0699	—	—		0.0744	—	—	
	200	0.0856	0.0963			0.0901	0.1050		
	250	0.1010	0.1120			0.1060	0.1210		
	300	0.1170	0.1280			0.1210	0.1370		
SG3305	150	0.164	—	0.156	0.164	0.171	—	0.16	0.171
	200	0.202	—	0.194	0.203	0.209	—	0.198	0.21
	300	0.279	0.299	0.271	0.279	0.286	0.313	0.275	0.286
	400	0.355	0.375	0.348	0.356	0.362	0.389	0.351	0.363
	500	0.432	0.452	0.424	0.432	0.439	0.466	0.428	0.439
	600	0.508	0.528	0.501	0.509	0.515	0.542	0.504	0.516
SG3310	150	0.219	—	0.188	0.221	0.247	—	0.202	0.249
	200	0.257	—	0.227	0.259	0.285	—	0.24	0.287
	300	0.334	0.414	0.303	0.336	0.361	0.469	0.317	0.364
	400	0.410	0.490	0.380	0.412	0.438	0.546	0.394	0.44
	500	0.487	0.567	0.456	0.489	0.515	0.622	0.47	0.517
	600	0.563	0.643	0.533	0.565	0.591	0.699	0.547	0.593
SG3320	150	0.594	—	—	—	0.706	—	—	—
	200	0.674	—	—	—	0.875	—	—	—
	300	0.833	1.150	—	—	0.944	1.380	—	—
	400	0.991	1.310	—	—	1.100	1.530	—	—
	500	1.150	1.470	—	—	1.260	1.690	—	—
	600	1.310	1.630	—	—	1.420	1.850	—	—
SG4610	340	1.79	2.02	1.69	1.82	1.87	2.17	1.74	1.92
	440	2.18	2.41	2.08	2.20	2.25	2.56	2.13	2.31
	540	2.57	2.79	2.46	2.59	2.64	2.95	2.52	2.69
	640	2.95	3.18	2.85	2.98	3.03	3.33	2.9	3.08
	740	3.34	3.57	3.24	3.37	3.42	3.72	3.29	3.47
	840	3.73	3.96	3.63	3.75	3.8	4.11	3.67	3.83
	940	4.12	4.35	4.02	4.14	4.19	4.5	4.06	4.22
	1040	4.50	4.74	4.41	4.53	4.58	4.88	4.44	4.61
	1140	4.89	5.12	4.79	4.92	4.97	5.27	4.83	4.99
SG4620	340	2.47	3.39	2.07	2.58	2.78	3.99	2.27	2.98
	440	2.86	3.77	2.46	2.96	3.17	4.38	2.66	3.37
	540	3.25	4.16	2.84	3.35	3.55	4.77	3.05	3.76
	640	3.64	4.55	3.23	3.74	3.94	5.16	3.44	4.14
	740	4.03	4.94	3.62	4.13	4.33	5.55	3.82	4.53
	840	4.41	5.34	4.02	4.51	4.71	5.93	4.17	4.82
	940	4.80	5.72	4.41	4.90	5.09	6.32	4.56	5.21
	1040	5.19	6.11	4.80	5.29	5.48	6.71	4.95	5.59
	1140	5.57	6.50	5.18	5.68	5.87	7.09	5.34	5.98
SG5520	980	14.6	16.4	—		15.2	17.6	—	
	1080	15.9	17.6			16.5	18.8		
	1180	17.1	18.8			17.7	20		
	1280	18.3	20			18.9	21.2		
	1380	19.5	21.3			20.1	22.5		

(Note 1) Dash (-) in the above table means the configuration is not available.

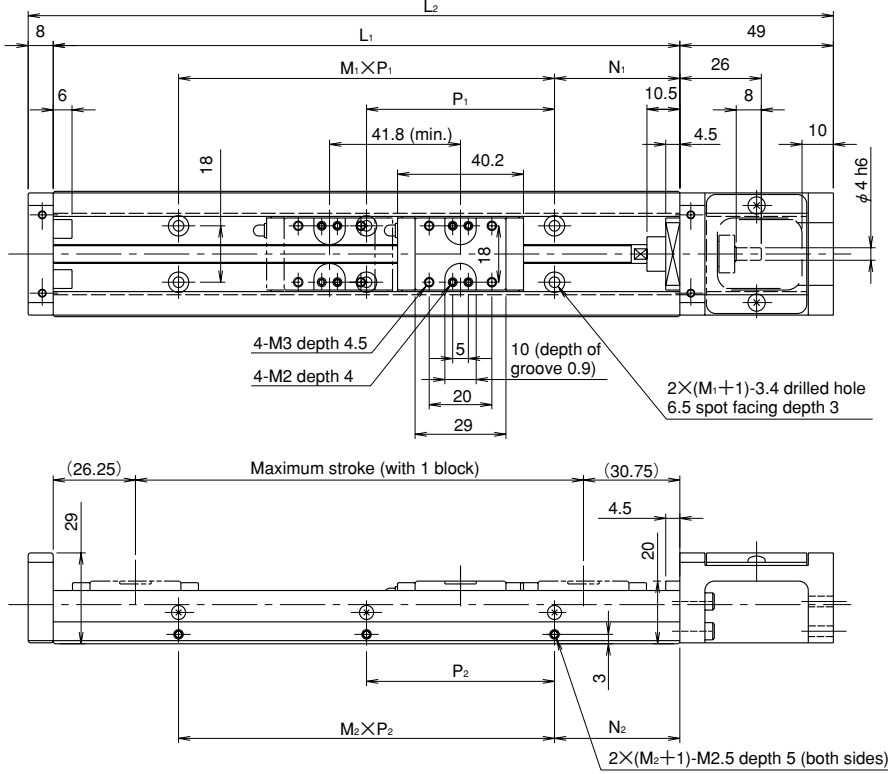
SG series

Model No.

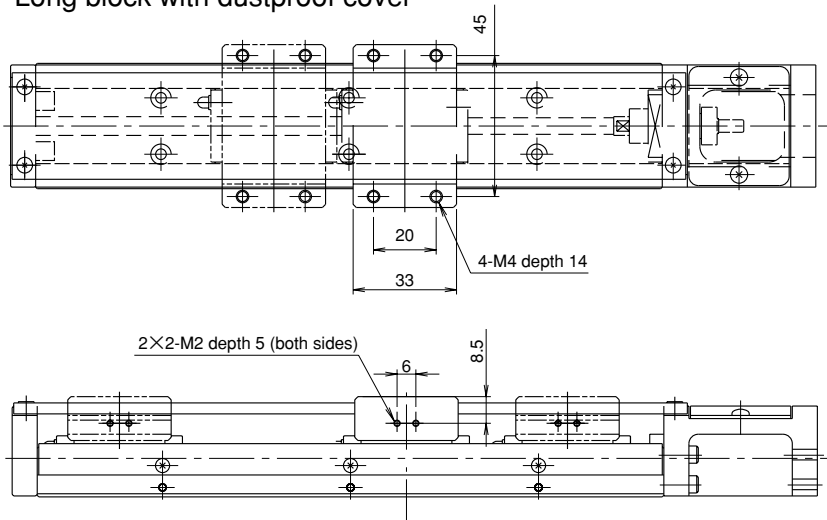
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG20	**	*	***	*
	01: 1mm 05: 5mm	A: With 1 long block B: With 2 long blocks	100, 150, 200	P, H

● LONG BLOCK CONFIGURATIONS

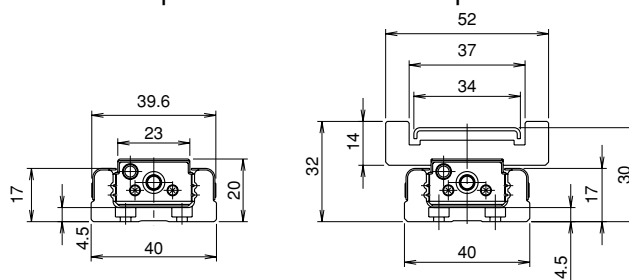
With 1 long block: A (With 2 long blocks: B)



Long block with dustproof cover



Without dustproof cover With dustproof cover



SG series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
100	157	20	1×60	20	1×60	43	—
150	207	15	2×60	15	2×60	93	51
200	257	40		40		143	101

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	1mm	5mm	A	B	A	B		
100	187	925	0.45	—	0.5	—	0.07	0.11
150			0.58	0.65	0.63	0.74		
200			0.71	0.78	0.77	0.88		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

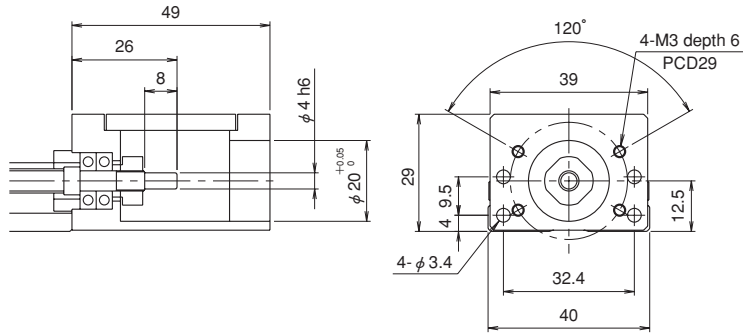
(Note 2) For long rail configurations, please consult KURODA.

Model No.

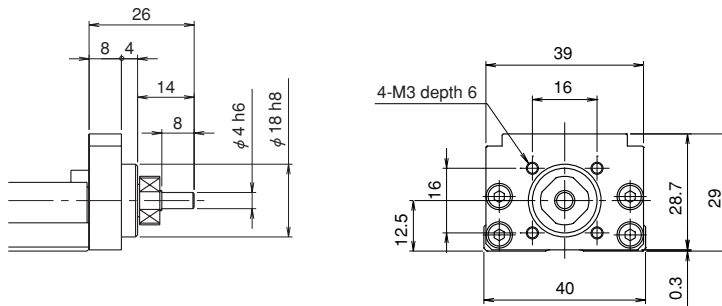
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG20	**	*	***	*
	01: 1mm 05: 5mm	A: With 1 long block B: With 2 long blocks	100, 150, 200	P, H

MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



Motor bracket configuration: R0



Mass of the R0 configuration is 0.04 kg less than the value shown in the table on page 7.

SG series

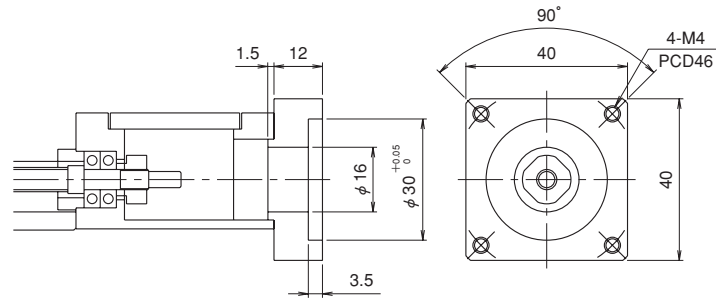
Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

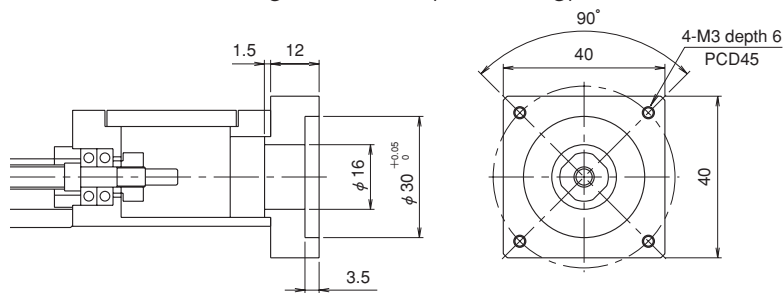
Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

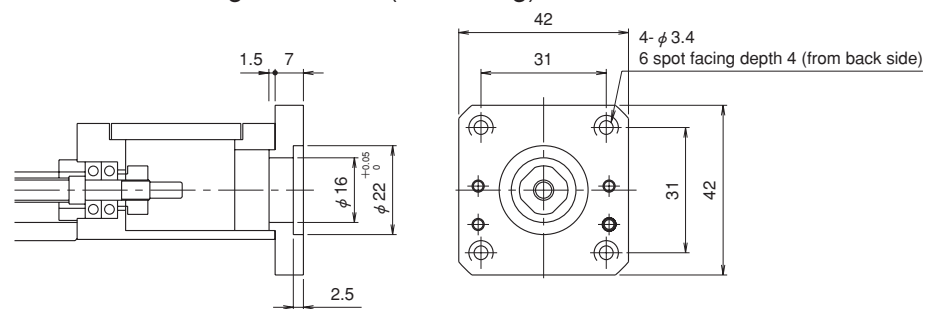
Motor bracket configuration: A1 (mass: 38g)



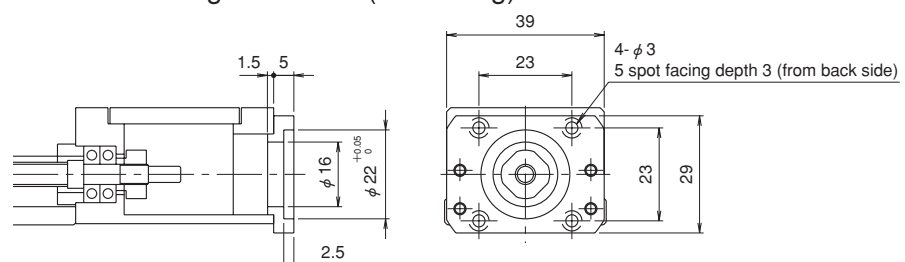
Motor bracket configuration: A3 (mass: 39g)



Motor bracket configuration: A5 (mass: 26g)



Motor bracket configuration: A6 (mass: 10g)



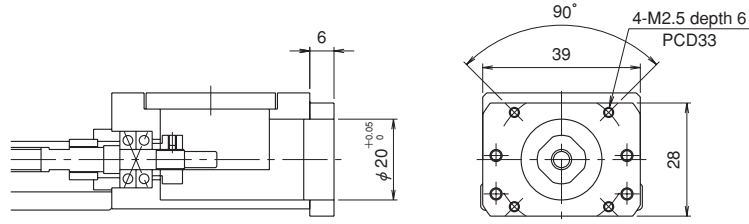
(Note) For A5 and A6 configurations, install the intermediate flange to motor before mounting it to actuator.

Model No.

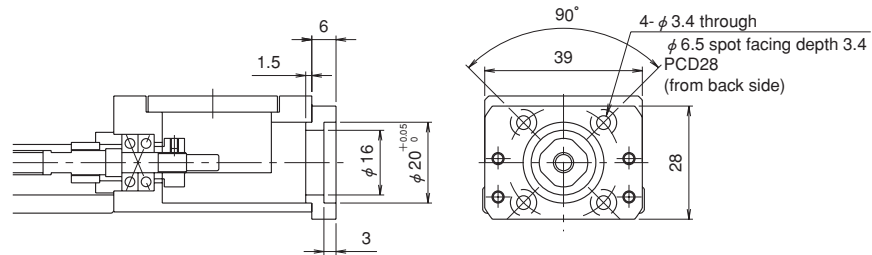
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG20	**	*	***	*
	01: 1mm 05: 5mm	A: With 1 long block B: With 2 long blocks	100, 150, 200	P, H

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

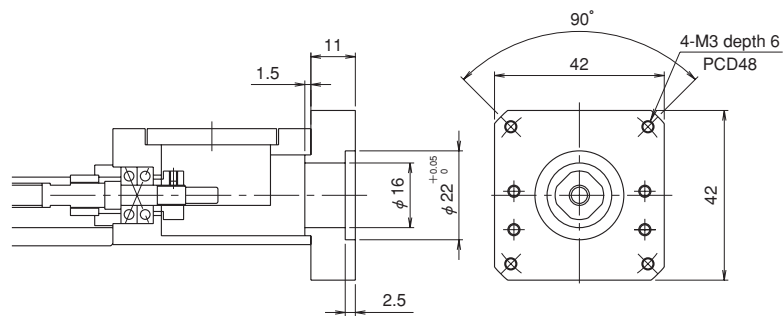
Motor bracket configuration: A8 (mass: 12g)



Motor bracket configuration: A9 (mass: 14g)



Motor bracket configuration: AA (mass: 46g)



(Note) For A9 and AA configurations, install the intermediate flange to motor before mounting it to actuator.

SG series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONSS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling
	Maker	Model No.	Output (W)		
AC Servo motor	PANASONIC	MUMA5A	50	AA	SFC-010DA2 (MIKI PULLEY)
		MUMA01	100		
		MSMA3A	30	A3	
		MSMD(MSMA)5A	50		
	MITSUBISHI ELECTRIC	HC-AQ0135	10	A8	
		HC-AQ0235	20		
		HC-AQ0335	30		
		HF-KP(MP)053	50	A1	
		HF-KP(MP)13	100		
	YASKAWA ELECTRIC	SGMM-A131 *	10	A9	
		SGMM-A231 *	20		
		SGMM-A331 *	30		
		SGMAH-A3	30	A1	
		SGMJV,SGMAV(SGMAS)-5A	50		
		SGMJV,SGMAV(SGMAS)-01	100		
		SGMAV(SGMAS)-C2	150		
SANYO ELECTRIC	Q1AA04003D	30	A1		
	Q1AA04005D	50			
	Q1AA04010D	100			
Stepping motor	ORIENTAL MOTOR	UPD534M-A	—	A5	
		PMU33AH	—	A6	
		UPK(RK)54,AS4	—	A5	
	SANYO ELECTRIC	F series□42mm	—	A5	
	TECHNO DRIVE	* K-S54 *	—	A5	

- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type of coupling for connecting a motor, consult KURODA.
- For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

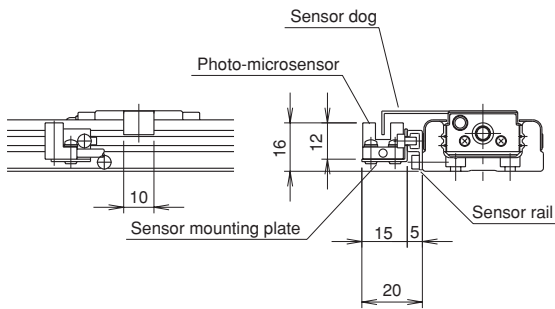
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SG20	**	*	***	*
	01: 1mm 05: 5mm	A: With 1 long block B: With 2 long blocks	100, 150, 200	P, H

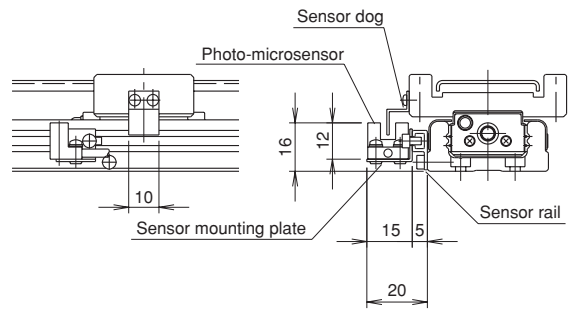
● SENSOR

Symbol S (NPN): Photo-microsensor (SUNX)

Without dustproof cover

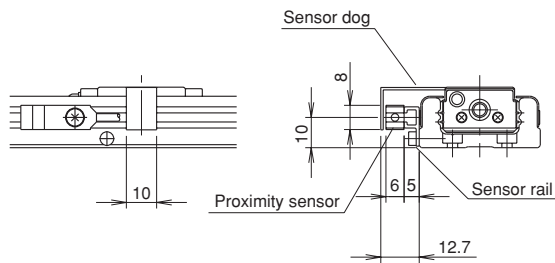


With dustproof cover

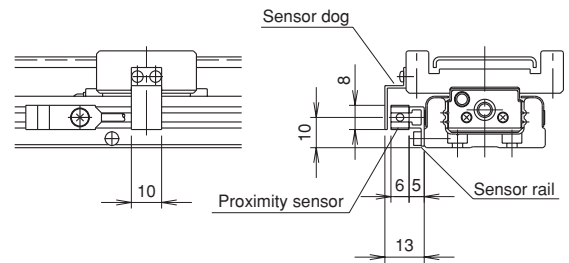


Symbol K (NPN)/E (PNP): Proximity sensor (YAMATAKE)

Without dustproof cover



With dustproof cover



SG series

Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

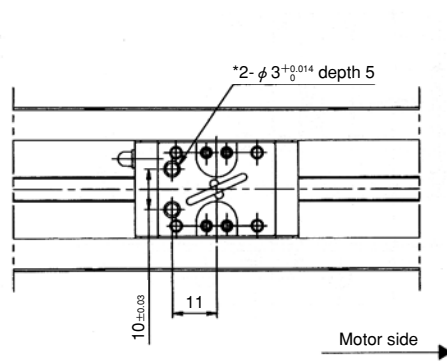
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

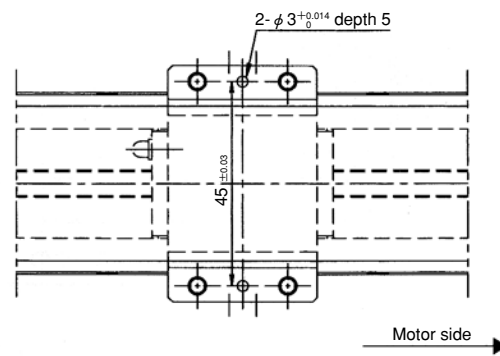
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover



Long block with dustproof cover



The hole with asterisk (*) may have diameter 4 counterbores for erasing the quenching layer when needed.

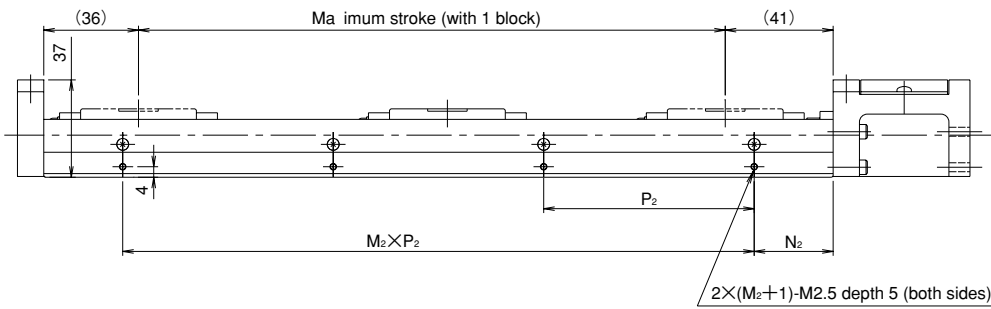
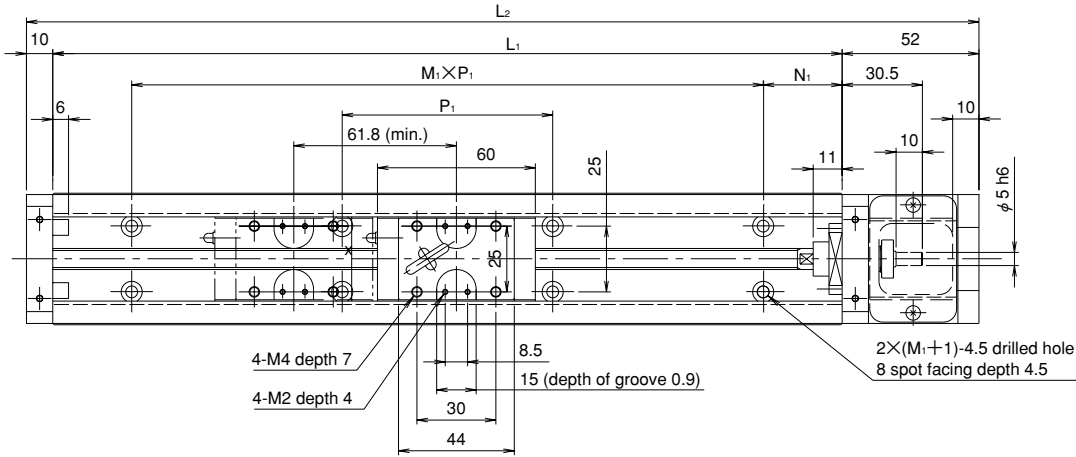
Model No.

Model No.	Lead	Slide block
SG26	**	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks

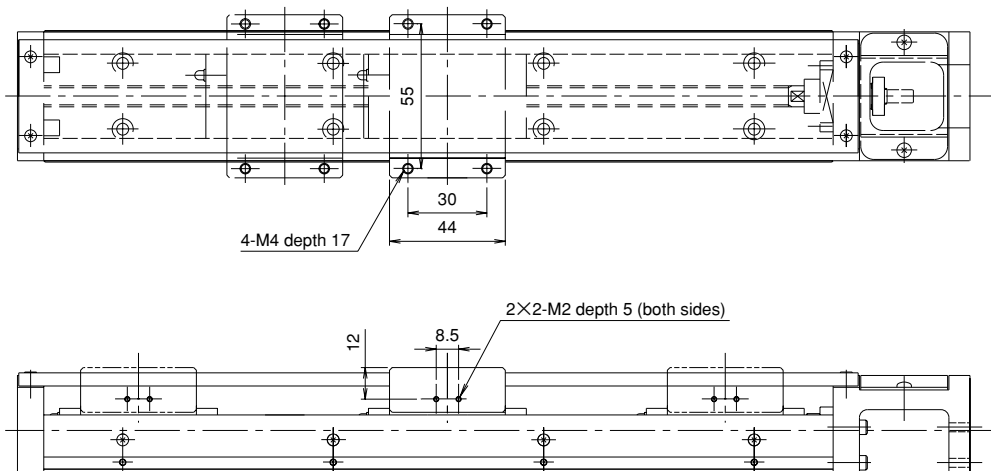
Guide rail length	Performance grade
***	*
150, 200, 250, 300	P, H

● LONG BLOCK CONFIGURATIONS

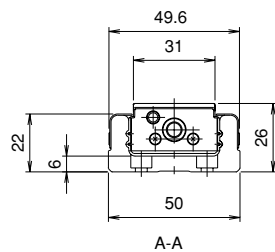
With 1 long block: A (With 2 long blocks: B)



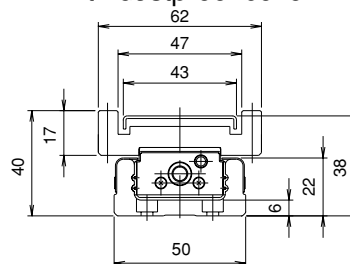
Long block with dustproof cover



Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
150	212	25	1×80	35	1×80	73	—
200	262	20	2×80	20	2×80	123	61
250	312	45		45		173	111
300	362	30	3×80	30	3×80	223	161

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	2mm	5mm	A	B	A	B		
150	281	694	0.93	—	1.07	—	0.17	0.24
200			1.14	1.31	1.3	1.54		
250			1.36	1.53	1.53	1.78		
300			1.57	1.74	1.76	2.01		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

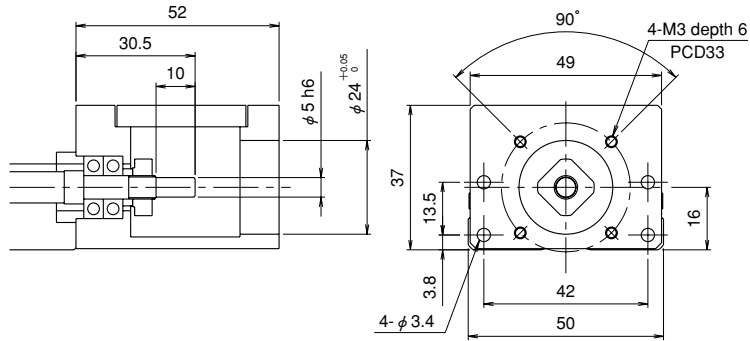
(Note 2) For long rail configurations, please consult KURODA.

Model No.

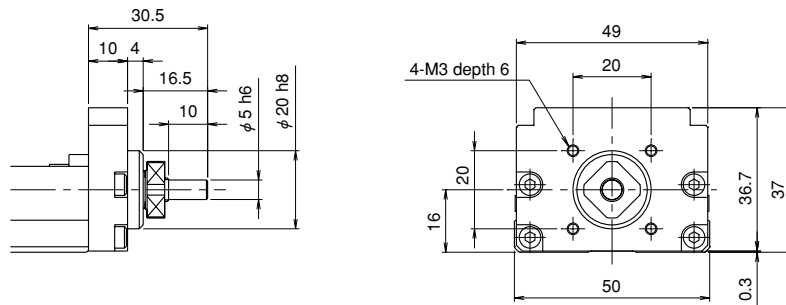
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG26	**	*	***	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	P, H

MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



Motor bracket configuration: R0



Mass of the R0 configuration is 0.08 kg less than the value shown in the table on page 15.

SG series

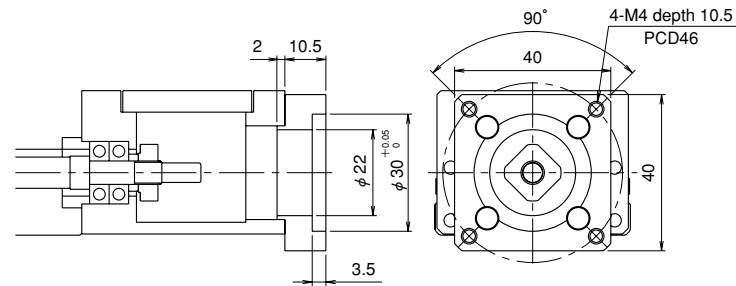
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

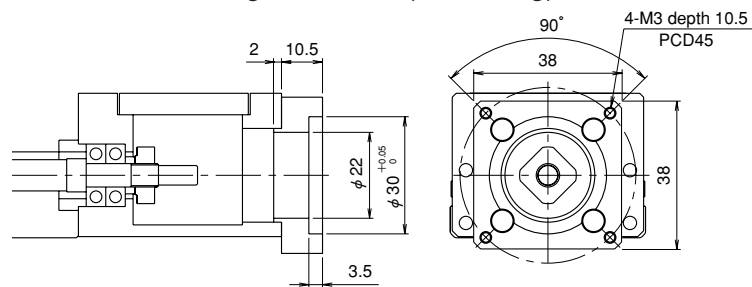
Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

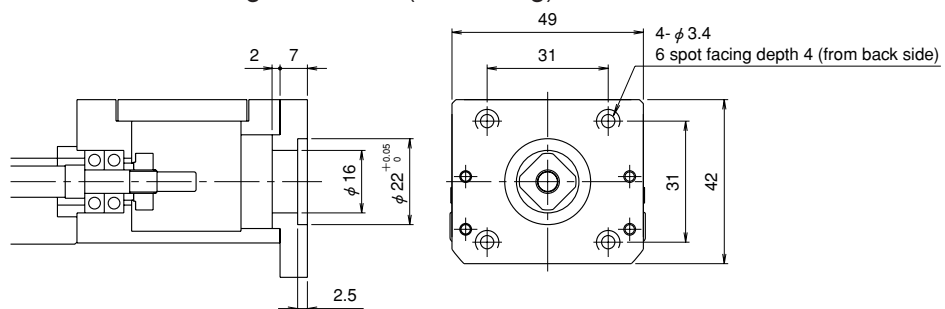
Motor bracket configuration: A1 (mass: 28g)



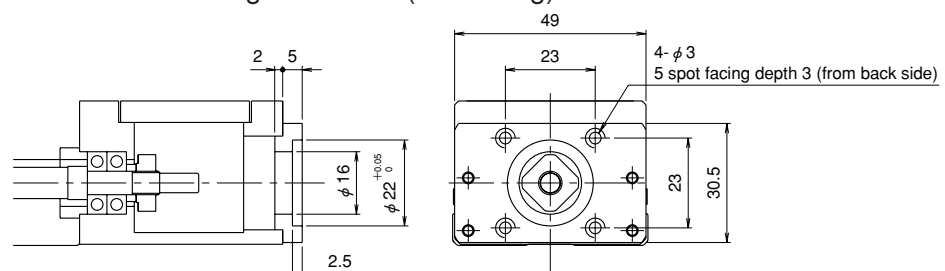
Motor bracket configuration: A3 (mass: 24g)



Motor bracket configuration: A5 (mass: 32g)



Motor bracket configuration: A6 (mass: 16g)



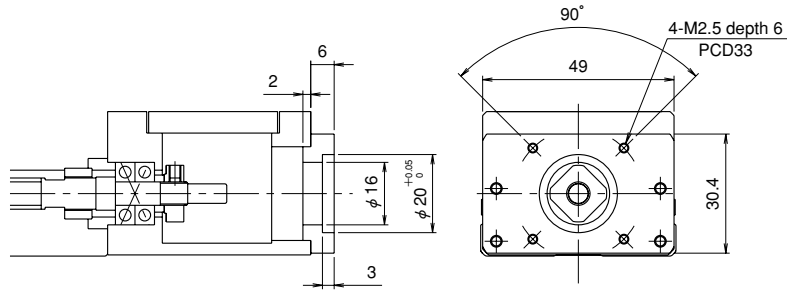
(Note) For A5 and A6 configurations, install the intermediate flange to motor before mounting it to actuator.

Model No.

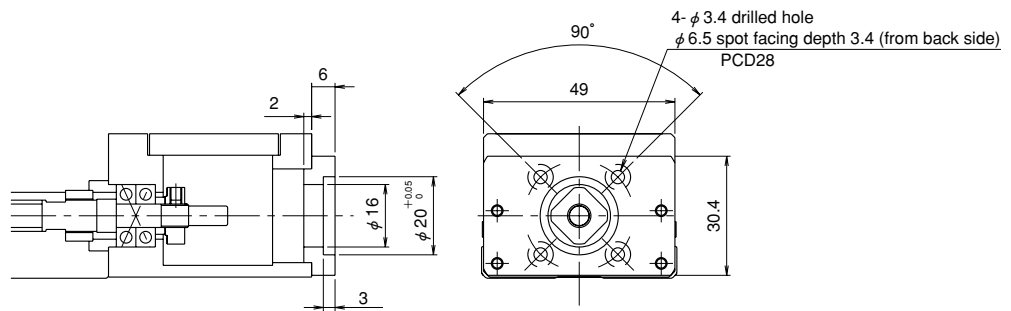
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG26	**	*	***	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	P, H

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

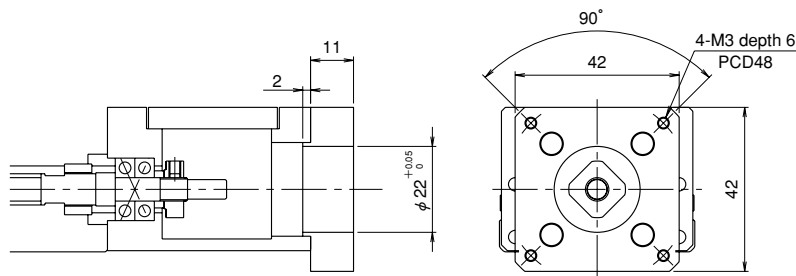
Motor bracket configuration: A8 (mass: 21g)



Motor bracket configuration: A9 (mass: 21g)



Motor bracket configuration: AA (mass: 41g)



(Note) For A9 configuration, install the intermediate flange to motor before mounting it to actuator.

SG series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling
	Maker	Model No.	Output (W)		
AC Servo motor	PANASONIC	MUMA5A	50	AA	SFC-010DA2 (MIKI PULLEY) LAD-20C (SAKAI)
		MUMA01	100		
		MSMA3A	30	A3	
		MSMD(MSMA)5A	50		
	MITSUBISHI ELECTRIC	HC-AQ0135	10	A8	
		HC-AQ0235	20		
		HC-AQ0335	30		
		HF-KP053	50	A1	
		HF-KP13	100		
	YASKAWA ELECTRIC	SGMM-A131 *	10	A9	
		SGMM-A231 *	20		
		SGMM-A331 *	30		
		SGMAH-A3	30	A1	
		SGMJV,SGMAV(SGMAS)-5A	50		
		SGMJV,SGMAV(SGMAS)-01	100		
SGMAV(SGMAS)-C2		150			
SANYO ELECTRIC	Q1AA04003D	30	A1		
	Q1AA04005D	50			
	Q1AA04010D	100			
Stepping motor	ORIENTAL MOTOR	UPD534M-A	—	A5	
		PMU33AH	—	A6	
		UPK(RK)54,AS4	—	A5	
	SANYO ELECTRIC	F series□42mm	—	A5	
	TECHNO DRIVE	* K-S54 *	—	A5	

- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type of coupling for connecting a motor, consult KURODA.
- For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

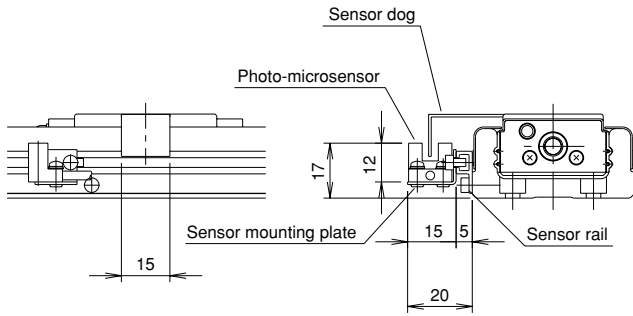
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SG26	**	*	** *	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	P, H

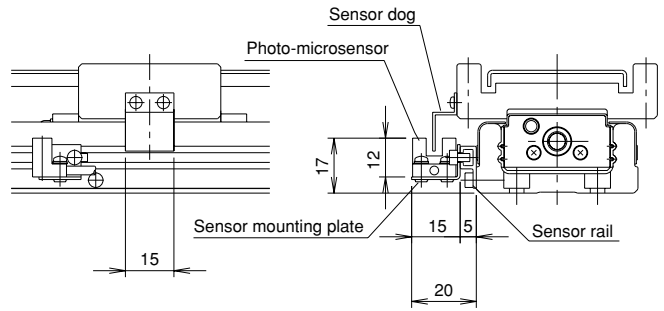
● SENSOR

Symbol S (NPN): Photo-microsensor (SUNX)

Without dustproof cover

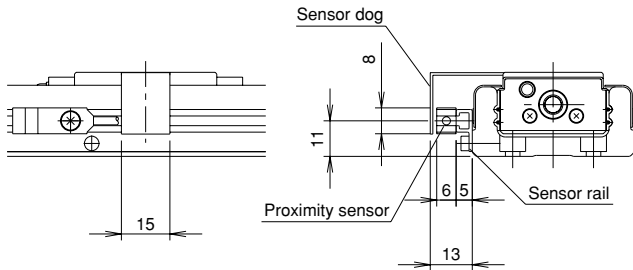


With dustproof cover

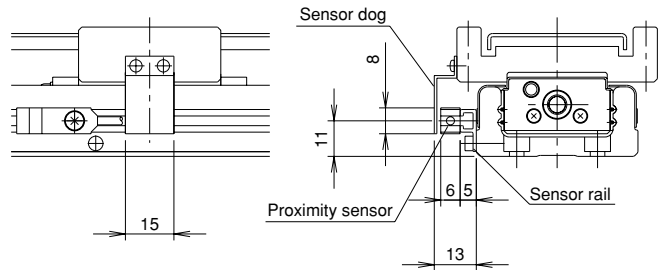


Symbol K (NPN)/E (PNP): Proximity sensor (YAMATAKE)

Without dustproof cover



With dustproof cover



SG series

Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A3, A5, A6, A8, A9, AA, R0	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

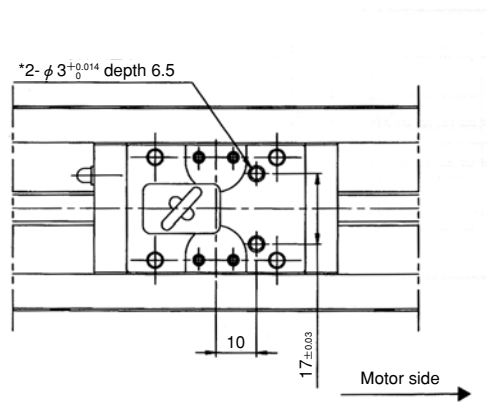
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

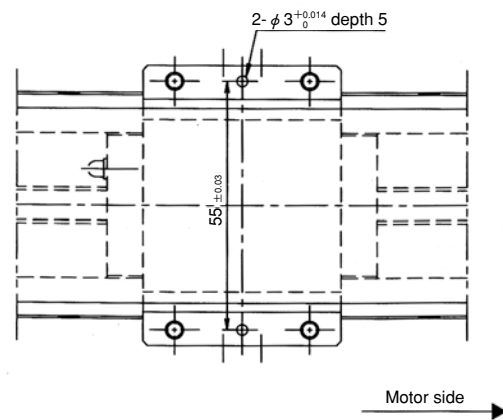
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover



Long block with dustproof cover



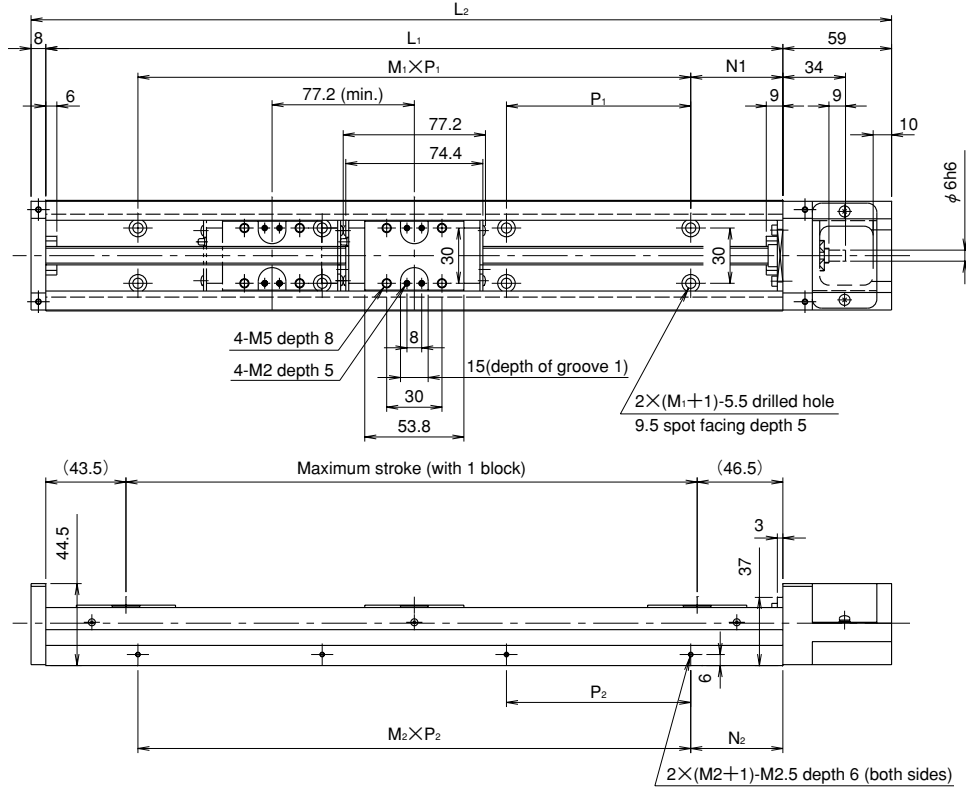
The hole with asterisk (*) may have diameter 4 counterbores for erasing the quenching layer when needed.

Model No.

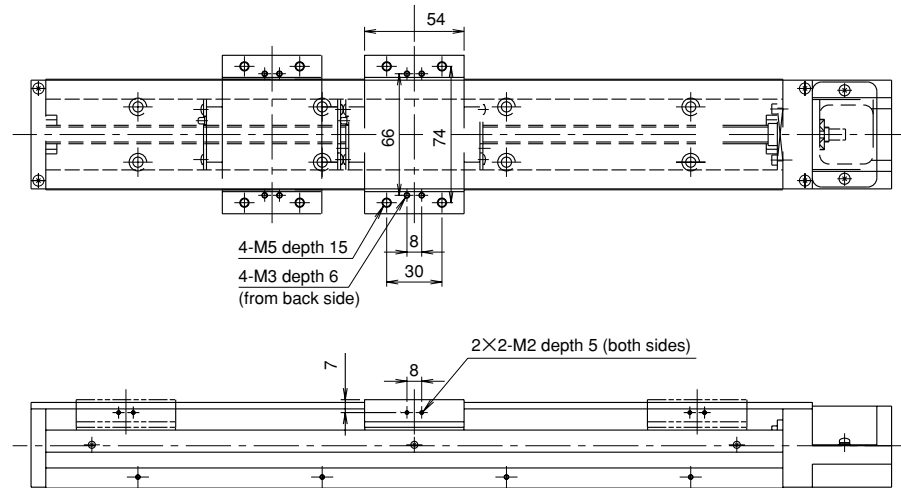
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG33	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	150, 200, 300, 400, 500, 600	P, H

● LONG BLOCK CONFIGURATIONS

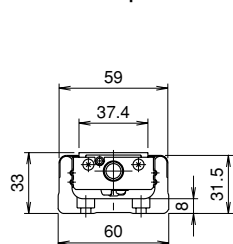
With 1 long block: A (With 2 long blocks: B)



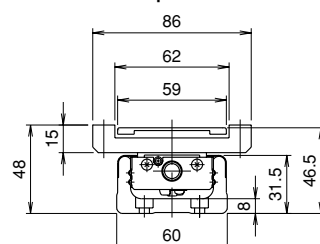
With dustproof cover



Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
150	217	25	1×100	25	1×100	60	—
200	267	50	1×100	50	1×100	110	—
300	367		2×100		2×100	210	133
400	467		3×100		3×100	310	233
500	567		4×100		4×100	410	333
600	667		5×100		4×100	510	433

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)				Slide block	
	Lead			Without cover		With cover		Without cover	With cover
	5mm	10mm	20mm	A	B	A	B		
150	550	1100	1500	1.6 (1.7)	—	1.8 (1.9)	—	0.30	0.40
200				2.0 (2.1)	—	2.1 (2.2)	—		
300				2.6 (2.7)	2.9 (3.0)	2.8 (2.9)	3.2 (3.3)		
400				3.2 (3.4)	3.6 (3.8)	3.5 (3.7)	3.9 (4.1)		
500				3.9 (4.1)	4.2 (4.4)	4.2 (4.4)	4.6 (4.8)		
600	4.6 (4.8)	4.9 (5.1)		4.9 (5.1)	5.3 (5.5)				

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

(Note 2) The figures in parentheses in the above table apply to SG3320 configuration.

(Note 3) For long rail configurations, please consult KURODA.

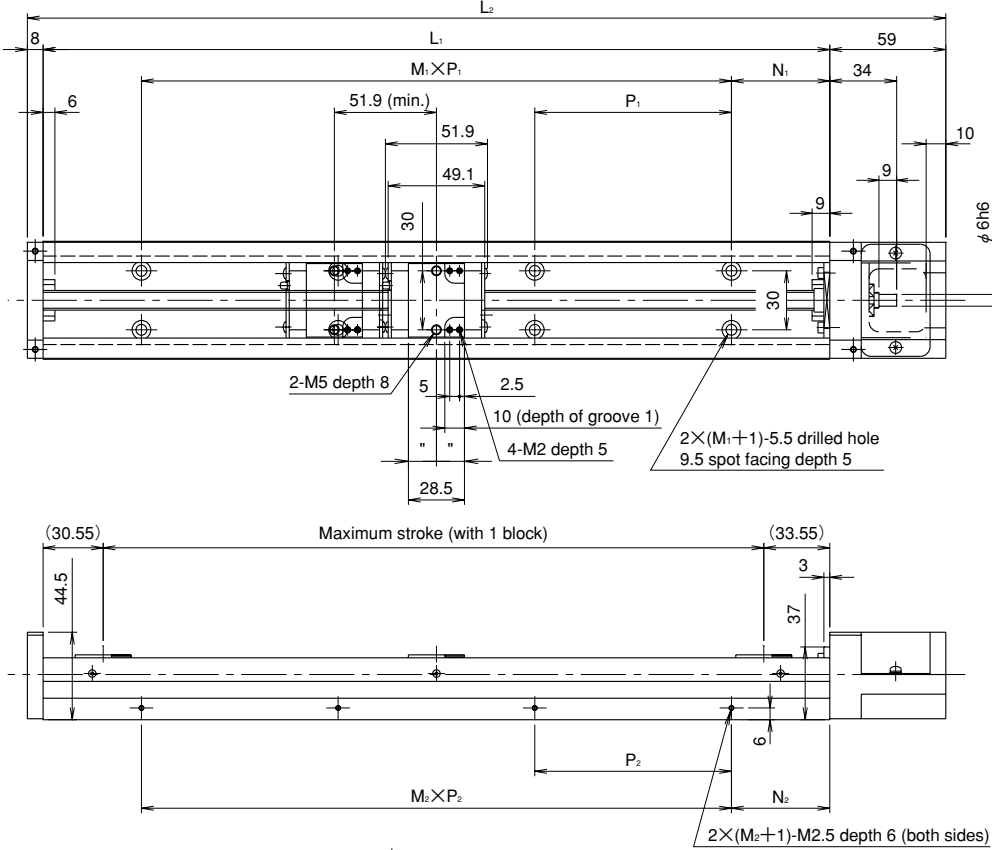
Model No.

Model No.	Lead	Slide block
SG33	* *	*
	05: 5mm	A: With 1 long block
	10: 10mm	B: With 2 long blocks
	20: 20mm	C: With 1 short block D: With 2 short blocks

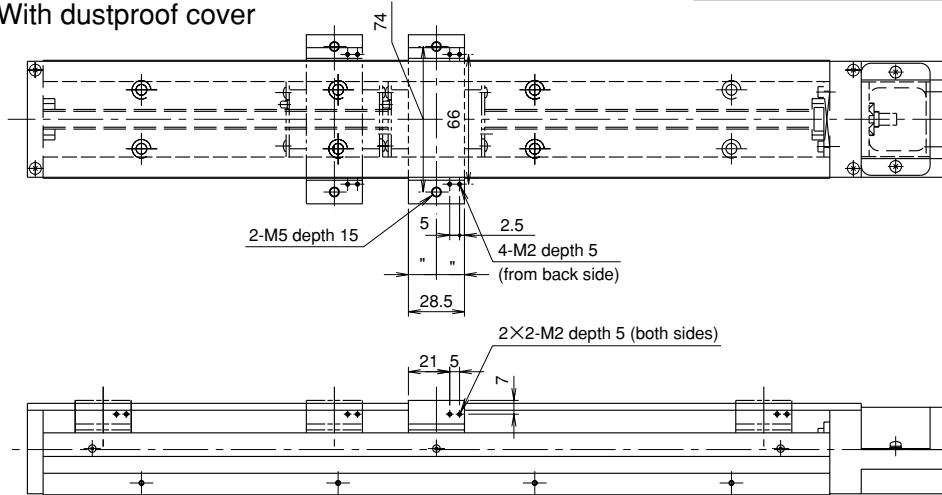
Guide rail length	Performance grade
* * *	*
150, 200, 300, 400, 500, 600	P, H

● SHORT BLOCK CONFIGURATIONS

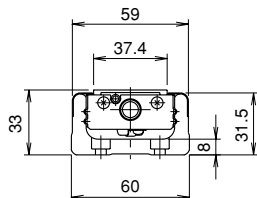
With 1 short block: C (With 2 short blocks: D)



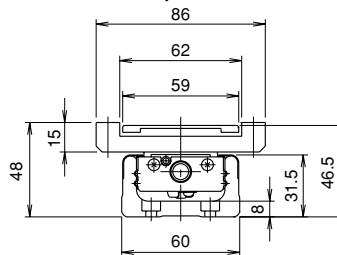
With dustproof cover



Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● SHORT BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Short block	
						C: 1 block	D: 2 blocks
150	217	25	1×100	25	1×100	85	34
200	267	50	1×100	50	1×100	135	84
300	367		2×100		2×100	235	184
400	467		3×100		3×100	335	284
500	567		4×100		4×100	435	384
600	667		5×100		4×100	535	484

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	5mm	10mm	C	D	C	D		
150	550	1100	1.5	1.7	1.6	1.9	0.15	0.20
200			1.8	2	2	2.2		
300			2.5	2.7	2.6	2.9		
400			3.1	3.3	3.3	3.5		
500	460	930	3.8	3.9	4	4.2		
600	310	620	4.4	4.6	4.7	4.9		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

(Note 2) Short-block configuration is not available for SG3320

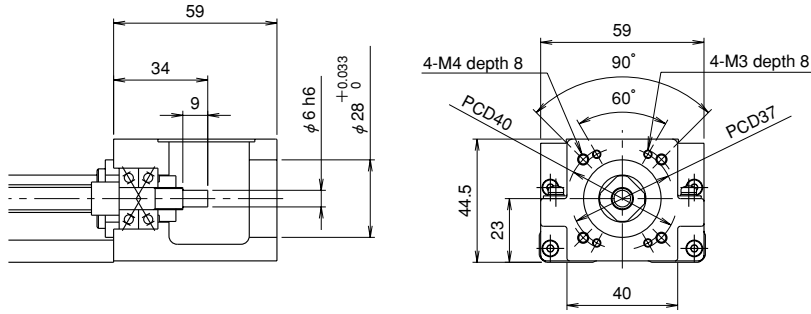
(Note 3) For long rail configurations, please consult KURODA.

Model No.

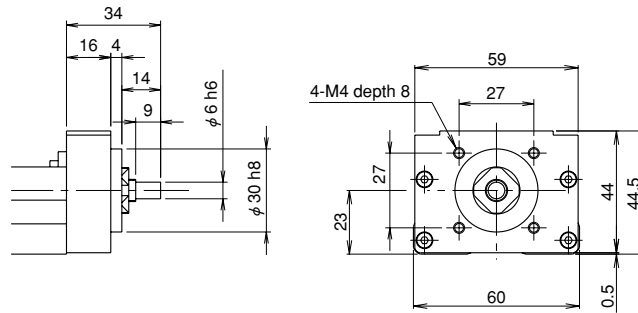
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG33	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	150, 200, 300, 400, 500, 600	P, H

MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



Motor bracket configuration: R0



Mass of the R0 configuration is 0.1 kg less than the values shown in the tables on pages 23 and 25.

SG series

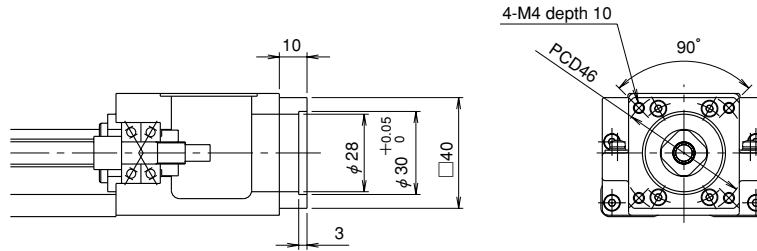
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

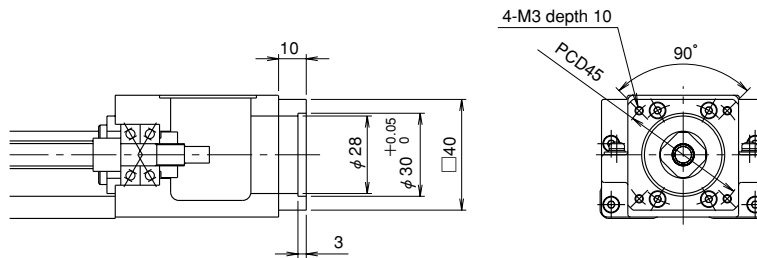
Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

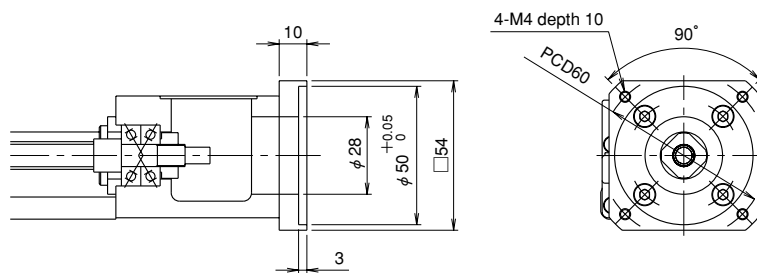
Motor bracket configuration: A1 (mass: 66g)



Motor bracket configuration: A2 (mass: 67g)



Motor bracket configuration: A3 (mass: 133g)

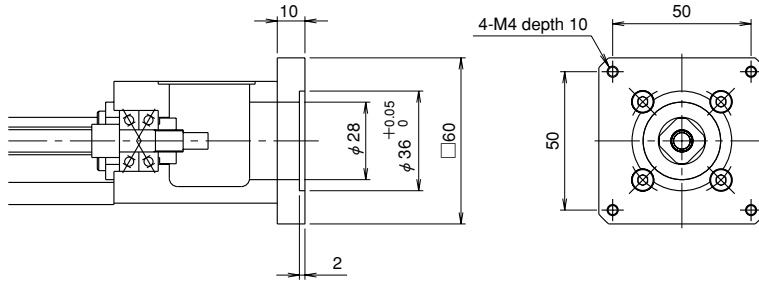


Model No.

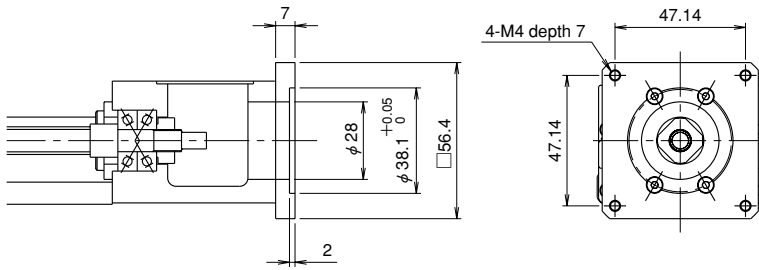
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG33	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	150, 200, 300, 400, 500, 600	P, H

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

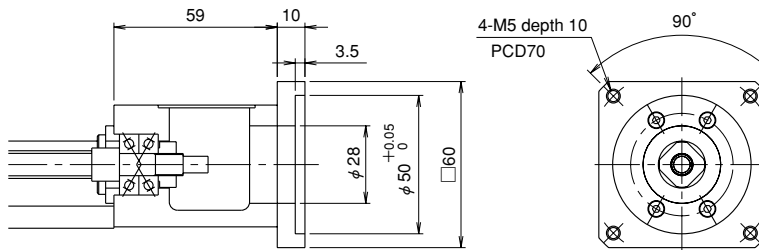
Motor bracket configuration: A4 (mass: 212g)



Motor bracket configuration: A5 (mass: 125g)



Motor bracket configuration: A6 (mass: 215g)



SG series

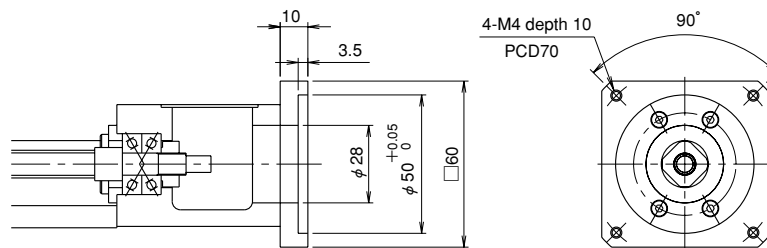
Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

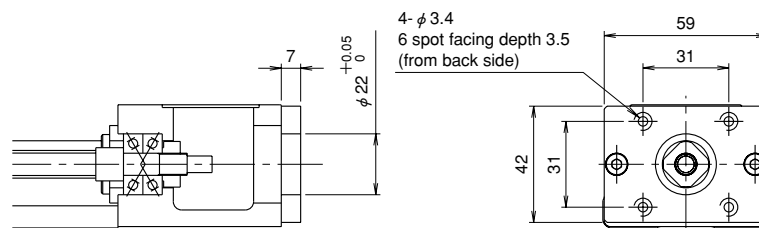
Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

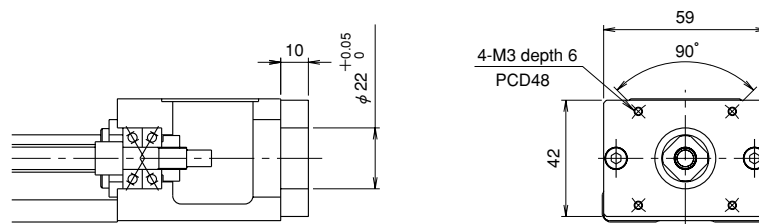
Motor bracket configuration: A7 (mass: 215g)



Motor bracket configuration: B1 (mass: 111g)



Motor bracket configuration: B2 (mass: 167g)



(Note) For B1 and B2 configuration, install the intermediate flange to motor before mounting it to actuator.

Model No.

Model No.	Lead	Slide block
SG33	* *	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: with 2 short blocks

Guide rail length	Performance grade
* * *	*
150, 200, 300, 400, 500, 600	P, H

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling	
	Maker	Model No.	Output (W)			
AC Servo motor	PANASONIC	MUMA5A	50	B2	LAD-25C (SAKAI)	
		MUMA01	100		A7	XBW-27C2 (NABEYA BI-TECH)
		MUMA02	200			A2
		MSMA3A	30	LAD-25C (SAKAI)		
		MSMD(MSMA)5A	50			
		MSMD(MSMA)01	100	A7	XBW-27C2 (NABEYA BI-TECH)	
		MSMD(MSMA)02	200			
	MITSUBISHI ELECTRIC	HF-KP(MP)053	50	A1	SFC-020D2 (MIKI PULLEY)	
		HF-KP(MP)13	100		A6	LAD-25C (SAKAI)
		HF-KP(MP)23	200	A3		XBW-27C2 (NABEYA BI-TECH)
		HA-FF053	50			SFC-020D2 (MIKI PULLEY)
		HA-FF13	100	LAD-25C (SAKAI)		
	YASKAWA ELECTRIC	SGMAH-A3	30	A1	SFC-020D2 (MIKI PULLEY)	
		SGMJV,SGMAV(SGMAS)-5A	50		LAD-25C (SAKAI)	
		SGMJV,SGMAV(SGMAS)-01	100			
		SGMAV(SGMAS)-C2	150			
		SGMJV,SGMAV(SGMAS)-02	200	A6	XBW-27C2 (NABEYA BI-TECH)	
	SANYO ELECTRIC	Q1AA04003D	30	A1	SFC-020D2 (MIKI PULLEY)	
		Q1AA04005D	50		LAD-25C (SAKAI)	
		Q1AA04010D	100			
		Q1AA06020D	200	A6	XBW-27C2 (NABEYA BI-TECH)	
Q2AA05005D		50	A3	SFC-020D2 (MIKI PULLEY)		
Q2AA05010D		100		LAD-25C (SAKAI)		
Stepping motor	ORIENTAL MOTOR	UPD534M-A	—	B1	SFC-010D2 (MIKI PULLEY)	
		UPK(RK)54,AS4	—		LAD-20C (SAKAI)	
		UPK(RK)56,AS6	—	A4		SFC-020D2 (MIKI PULLEY)
		PK26	—	A5	LAD-25C (SAKAI)	
	SANYO ELECTRIC	F series□42mm	—	B1	SFC-010D2 (MIKI PULLEY)	
		F series□60mm	—	A4	SFC-020D2 (MIKI PULLEY)	
	TECHNO DRIVE	*K-S54*	—	B1	SFC-010D2 (MIKI PULLEY)	
		K-S(M)56	—	A4	SFC-020D2 (MIKI PULLEY)	
				LAD-25C (SAKAI)		

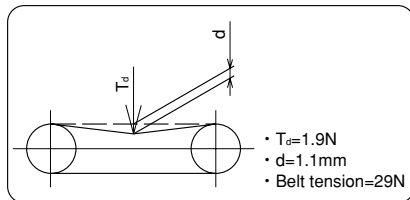
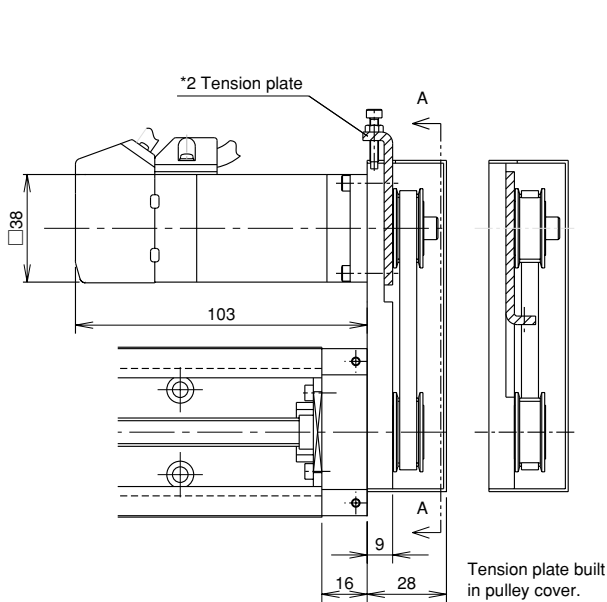
- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type of coupling for connecting a motor, consult KURODA.
- For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

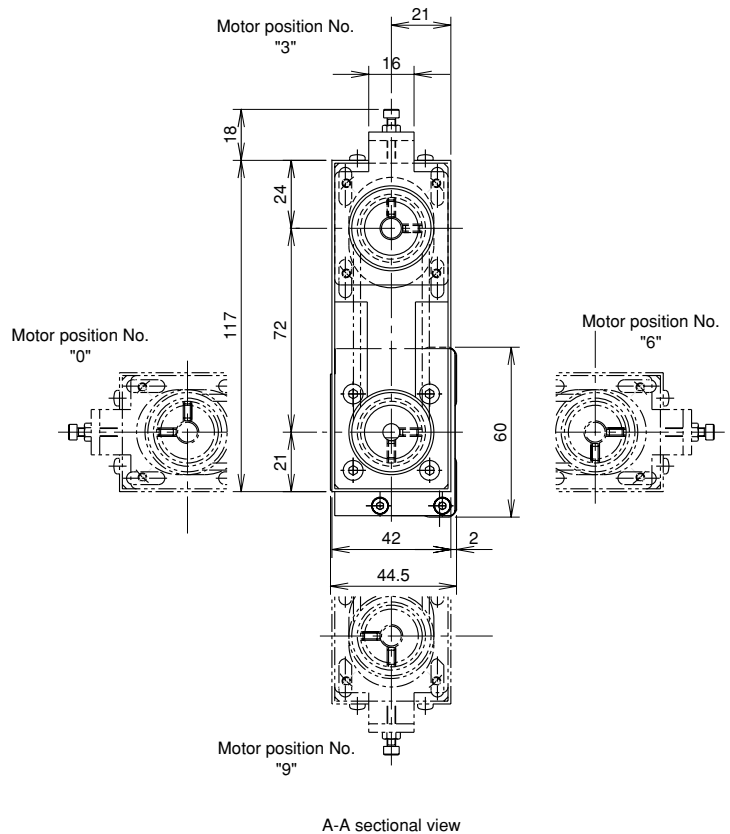
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● PARALLEL MOTOR MOUNTING



Tension of belt

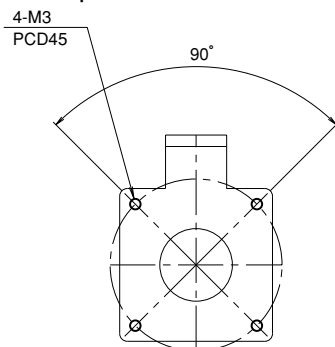


A-A sectional view

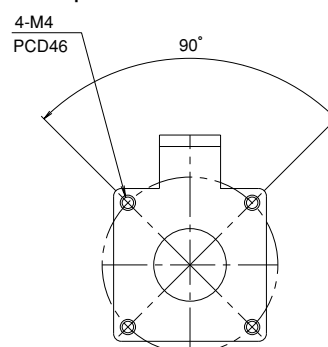
- The above figure shows actuator with MSMA01 (PANASONIC): E□.
- Pulley unit position can be adjusted at 90 degree each.
- Motor parallel mounting can be equipped with dustproof cover and sensor
- Tension plate position can be built in pulley cover.
- The mass is 0.2kg larger than the values shown in tables on pages 23 and 25.
- Inertia moment is $2.22 \times 10^{-5} \text{kg} \cdot \text{m}^2$ larger than the value shown in table on page 5.

Mark	Motor option
F□	PANASONIC MINAS SERIES : 50~100W
E□	YASKAWA ELECTRIC SIGMA SERIES : 50~100W
	MITSUBISHI ELECTRIC HC-MF SERIES : 50~100W
	SANYO ELECTRIC P3 SERIES : 50~100W

Dimensions of parallel motor mounting Type E□



Dimensions of parallel motor mounting Type F□



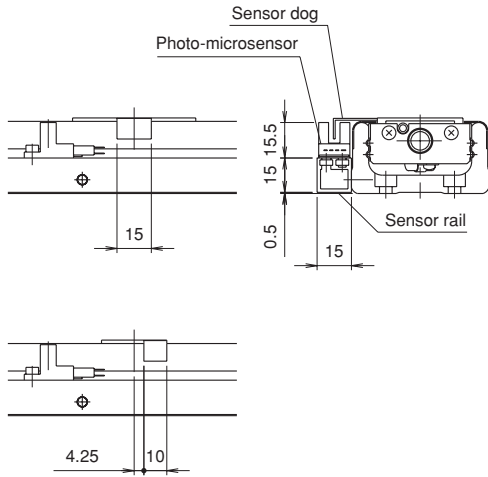
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SG33	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks		

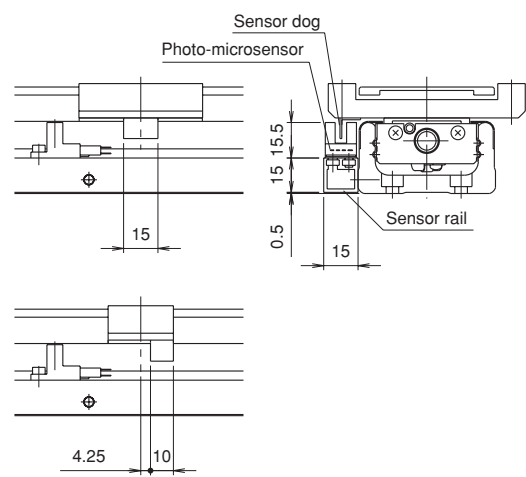
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, SUNX)

Without dustproof cover

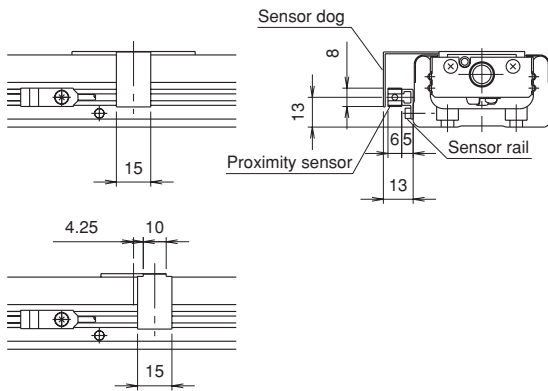


With dustproof cover

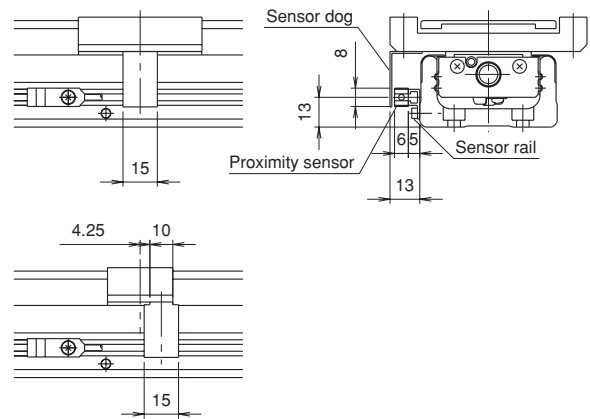


Symbol K (NPN) / E (PNP): Proximity sensor (YAMATAKE)

Without dustproof cover

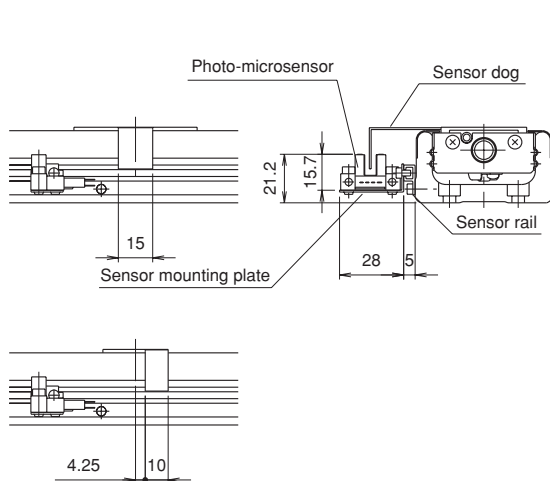


With dustproof cover

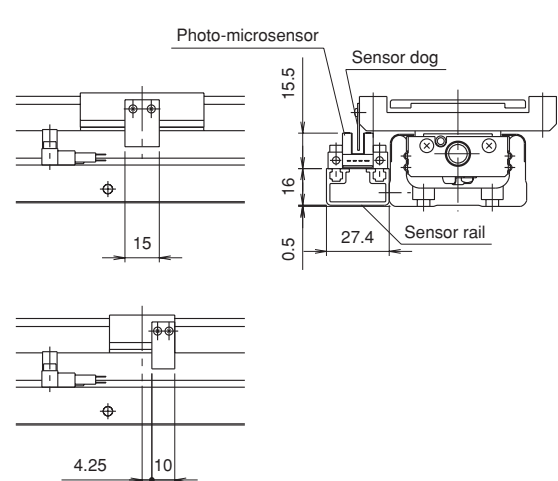


Symbol H (NPN) / J (PNP): Photo-microsensor (OMRON)

Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, A5, A6, A7, B1, B2, R0, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

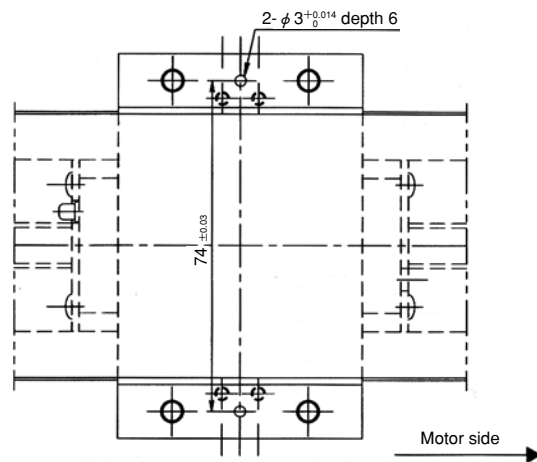
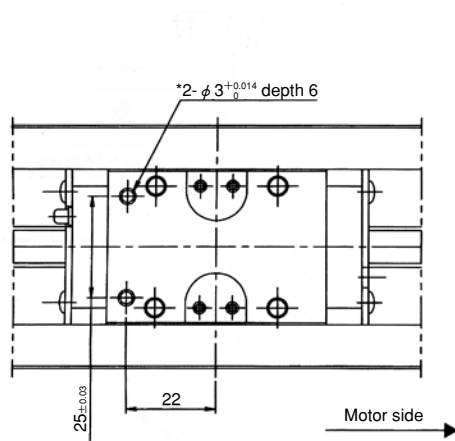
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover

Long block with dustproof cover

For actuators with 2 blocks, the holes are on both blocks.

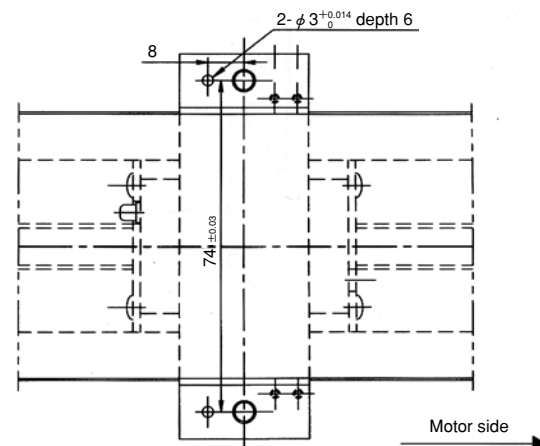
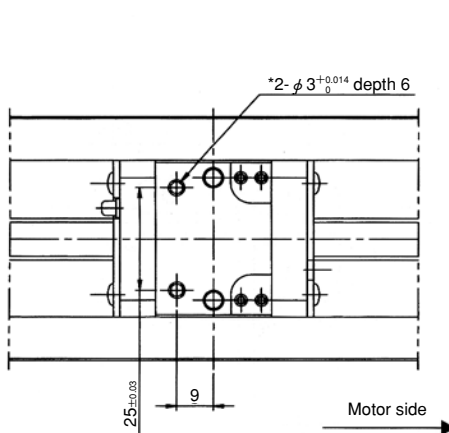


The hole with asterisk (*) may have diameter 5 counterbores for erasing the quenching layer when needed.

Short block without dustproof cover

Short block with dustproof cover

For actuators with 2 blocks, the holes are on both blocks.



The hole with asterisk (*) may have diameter 5 counterbores for erasing the quenching layer when needed.

Model No.

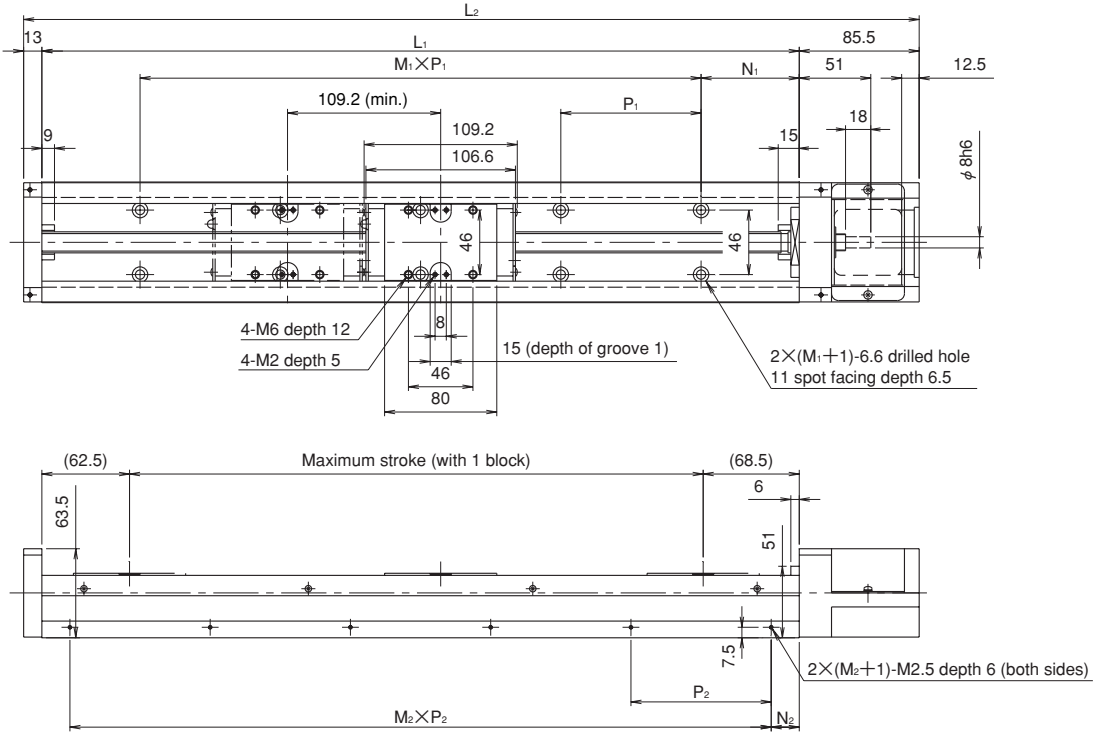
Model No.	Lead	Slide block
SG46	* *	*
	10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks

Guide rail length	Performance grade
* * * *	*
340, 440, 540, 640, 740, 840, 940, 1040, 1140, 1240	P, H

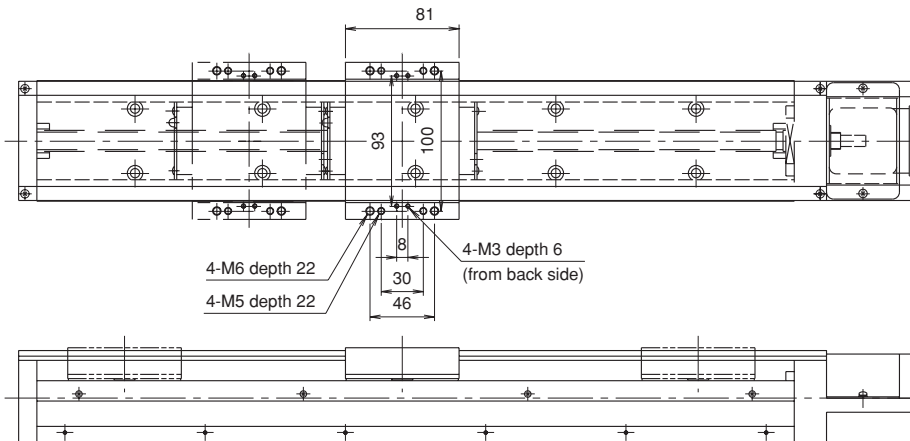
SG series

● LONG BLOCK CONFIGURATIONS

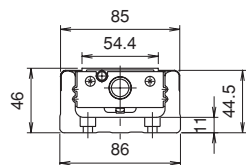
With 1 long block: A (With 2 long blocks: B)



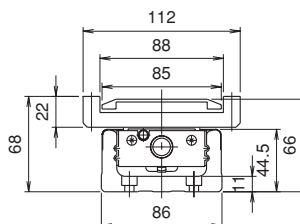
With dustproof cover



Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
340	438.5	70	2×100	20	3×100	209	100
440	538.5		3×100		4×100	309	200
540	638.5		4×100		5×100	409	300
640	738.5		5×100		6×100	509	400
740	838.5		6×100		7×100	609	500
840	938.5		7×100		8×100	709	600
940	1038.5		8×100		9×100	809	700
1040	1138.5		9×100		10×100	909	800
1140	1238.5		10×100		11×100	1009	900
1240	1338.5		11×100		12×100	1109	1000

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	10mm	20mm	A	B	A	B		
340	740	1480	6.5	7.5	7.0	8.0	0.90	1.20
440			8.0	8.5	8.5	9.5		
540			9.0	10.0	10.0	11.0		
640			10.5	11.5	11.0	12.5		
740	650	1300	12.0	13.0	12.5	14.0		
840	500	1000	13.0	14.0	14.0	15.5		
940	390	780	14.5	15.5	15.5	16.5		
1040	315	630	16.0	17.0	17.0	18.0		
1140	260	520	17.5	18.0	18.5	19.5		
1240	220	440	18.5	19.5	19.5	21.0		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

(Note 2) For long rail configurations, please consult KURODA.

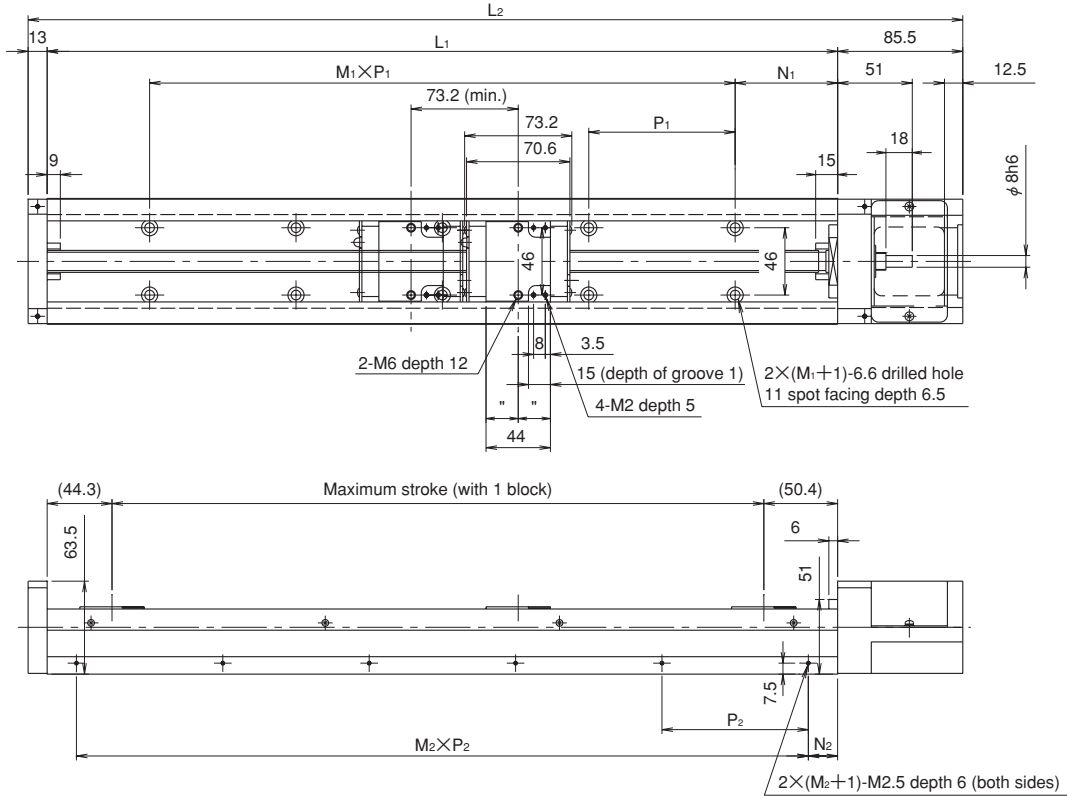
Model No.

Model No.	Lead	Slide block
SG46	* *	*
	10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks

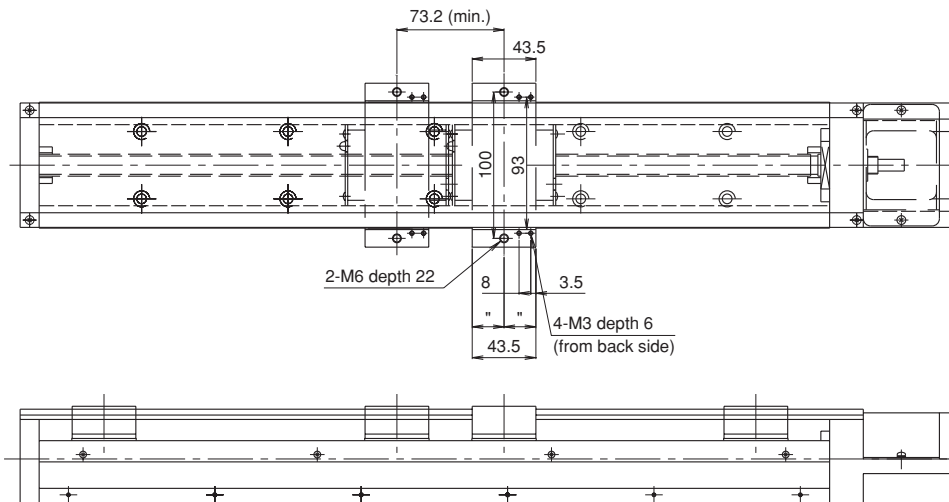
Guide rail length	Performance grade
* * * *	*
340, 440, 540, 640, 740, 840, 940, 1040, 1140, 1240	P, H

● SHORT BLOCK CONFIGURATIONS

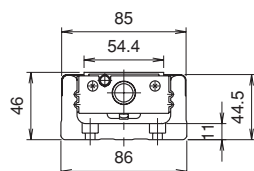
With 1 short block: C (With 2 short blocks: D)



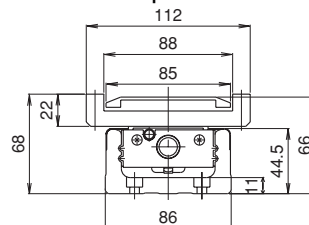
Short block with dustproof cover



Without dustproof cover



With dustproof cover



SG series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● SHORT BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Short block	
						C: 1 block	D: 2 blocks
340	438.5	70	2×100	20	3×100	245	172
440	538.5		3×100		4×100	345	272
540	638.5		4×100		5×100	445	372
640	738.5		5×100		6×100	545	472
740	838.5		6×100		7×100	645	572
840	938.5		7×100		8×100	745	672
940	1038.5		8×100		9×100	845	772
1040	1138.5		9×100		10×100	945	872
1140	1238.5		10×100		11×100	1045	972
1240	1338.5		11×100		12×100	1145	1072

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	10mm	20mm	C	D	C	D		
340	740	1480	6.0	6.5	6.5	7	0.50	0.70
440			7.5	8.0	8	8.5		
540			8.5	9.5	9.5	10		
640			10.0	10.5	10.5	11.5		
740	650	1300	11.5	12.0	12	13		
840	500	1000	13.0	13.5	13.5	14		
940	390	780	14.0	14.5	15	15.5		
1040	315	630	15.5	16.0	16.5	17		
1140	260	520	17.0	17.5	18	18.5		
1240	220	440	18.5	19.0	19	20		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

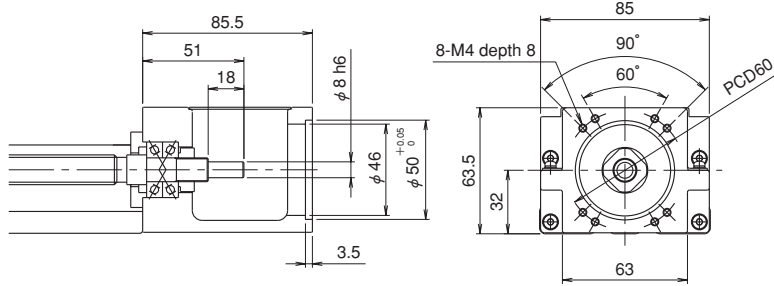
(Note 2) For long rail configurations, please consult KURODA.

Model No.

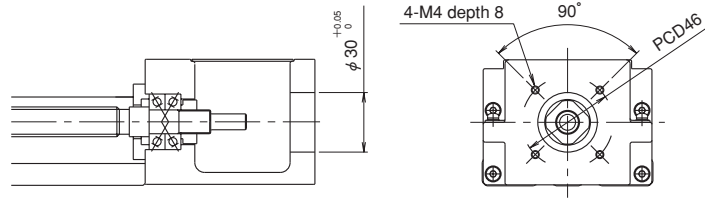
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG46	**	*	****	*
	10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	340, 440, 540, 640, 740, 840, 940, 1040, 1140, 1240	P, H

MOTOR BRACKET CONFIGURATIONS

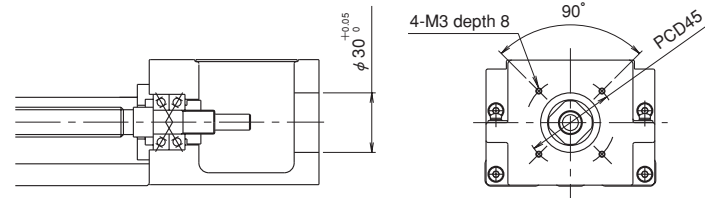
Motor bracket configuration: A0



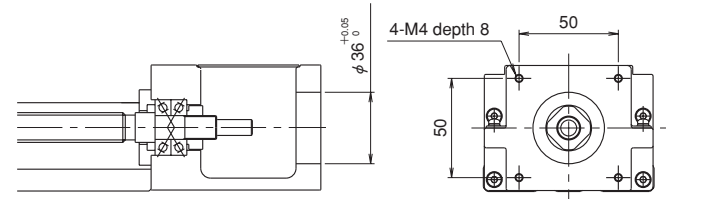
Motor bracket configuration: B0



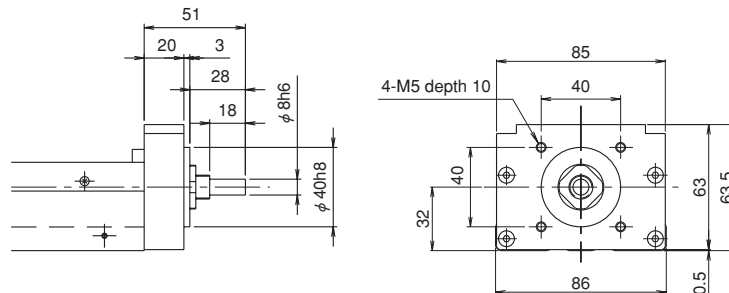
Motor bracket configuration: C0



Motor bracket configuration: D0



Motor bracket configuration: R0



Mass of the R0 configuration is 0.3 kg less than the value shown in the table on page 37.

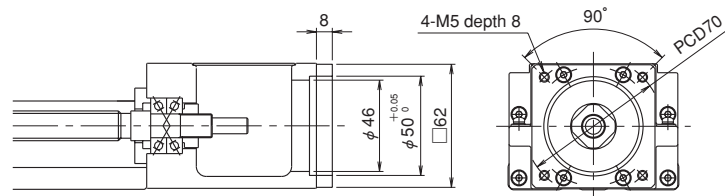
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

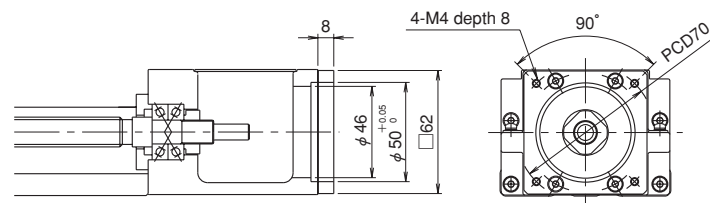
Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

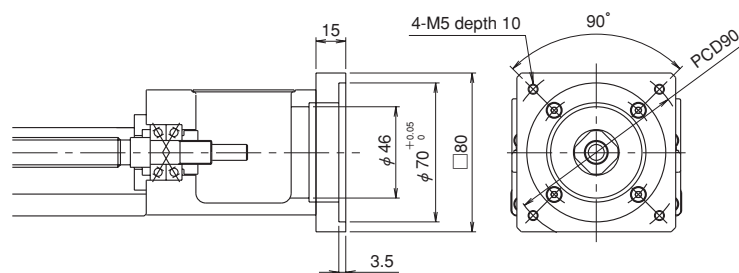
Motor bracket configuration: A1 (mass: 103g)



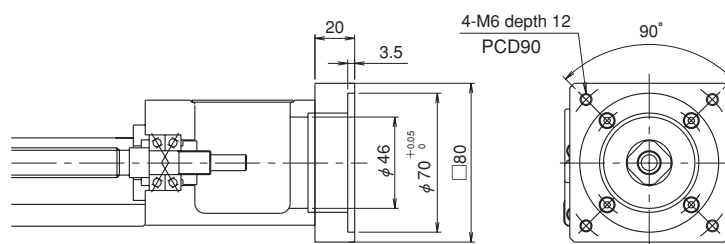
Motor bracket configuration: A2 (mass: 106g)



Motor bracket configuration: A3 (mass: 448g)



Motor bracket configuration: A4 (mass: 628g)



Model No.

Model No.	Lead	Slide block
SG46	* *	*
	10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks

Guide rail length	Performance grade
* * * *	*
340, 440, 540, 640, 740, 840, 940, 1040, 1140, 1240	P, H

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling	
	Maker	Model No.	Output (W)			
AC Servo motor	PANASONIC	MUMA02	200	A2	SFC-030DA2 (MIKI PULLEY)	
		MUMA04	400		LAD-30C (SAKAI)	
		MSMA3A	30	C0	SFC-020DA2 (MIKI PULLEY)	
		MSMD(MSMA)5A	50		LAD-25C (SAKAI)	
		MSMD(MSMA)01	100		A2	SFC-030DA2 (MIKI PULLEY)
		MSMD(MSMA)02	200			LAD-30C (SAKAI)
		MSMD(MSMA)04	400	A3	SFC-040DA2 (MIKI PULLEY)	
		MSMD(MSMA)08	750		LAD-30C (SAKAI)	
	MITSUBISHI ELECTRIC	HF-KP(MP)053	50	B0	SFC-020DA2 (MIKI PULLEY)	
		HF-KP(MP)13	100		LAD-25C (SAKAI)	
		HF-KP(MP)23	200	A1	SFC-030DA2 (MIKI PULLEY)	
		HF-KP(MP)43	400		LAD-30C (SAKAI)	
		HF-KP(MP)73	750	A4	SFC-040DA2 (MIKI PULLEY)	
		HA-FF053	50	A0	SFC-020DA2 (MIKI PULLEY)	
		HA-FF13	100		LAD-25C (SAKAI)	
		HA-FF23	200	A3	SFC-030DA2 (MIKI PULLEY)	
	HA-FF33	300	LAD-30C (SAKAI)			
	YASKAWA ELECTRIC	SGMAH-A3	30	B0	SFC-020DA2 (MIKI PULLEY)	
		SGMJV,SGMAV(SGMAS)-5A	50		LAD-25C (SAKAI)	
		SGMJV,SGMAV(SGMAS)-01	100		A1	SFC-030DA2 (MIKI PULLEY)
		SGMAV(SGMAS)-C2	150			LAD-30C (SAKAI)
		SGMJV,SGMAV(SGMAS)-02	200	A4	SFC-040DA2 (MIKI PULLEY)	
		SGMJV,SGMAV(SGMAS)-04	400		LAD-30C (SAKAI)	
		SGMJV,SGMAV(SGMAS)-08	750	LAD-30C (SAKAI)		
	SANYO ELECTRIC	Q1AA04003D	30	B0	SFC-020DA2 (MIKI PULLEY)	
		Q1AA04005D	50		LAD-25C (SAKAI)	
		Q1AA04010D	100		A1	SFC-030DA2 (MIKI PULLEY)
		Q1AA06020D	200	LAD-30C (SAKAI)		
		Q1AA06040D	400	A4	SFC-040DA2 (MIKI PULLEY)	
		Q1AA07075D	750		LAD-30C (SAKAI)	
		Q2AA05005D	50	A0	SFC-020DA2 (MIKI PULLEY)	
		Q2AA05010D	100		LAD-25C (SAKAI)	
		Q2AA07020D	200	A3	SFC-030DA2 (MIKI PULLEY)	
Q2AA07030D		300	LAD-30C (SAKAI)			
Q2AA07040D	400	LAD-30C (SAKAI)				
Stepping motor	ORIENTAL MOTOR	UPK(RK)56,AS6	—	D0	SFC-020DA2 (MIKI PULLEY) LAD-25C (SAKAI)	
	SANYO ELECTRIC	F series□60mm	—	D0		
	TECHNO DRIVE	*K-S(M)56*	—	D0		

- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type of coupling for connecting a motor, consult KURODA.
- For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

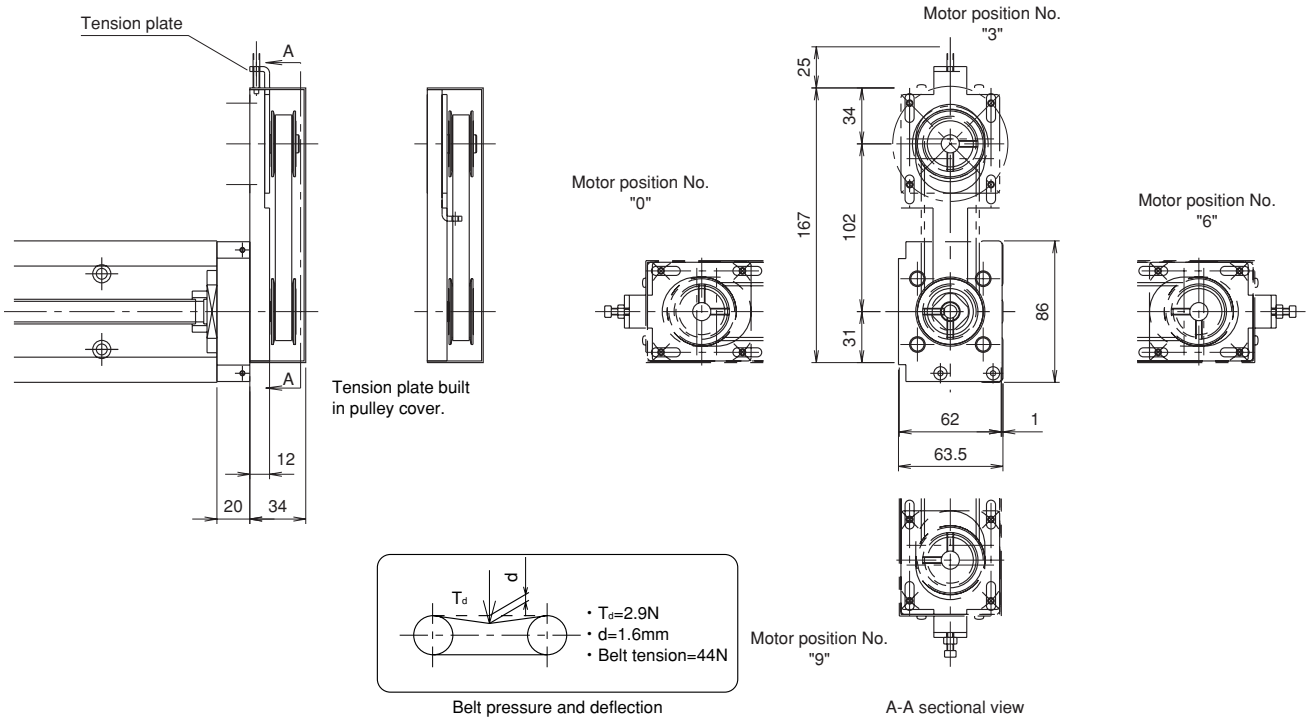
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● PARALLEL MOTOR MOUNTING

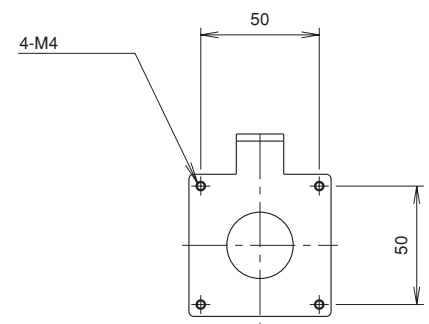
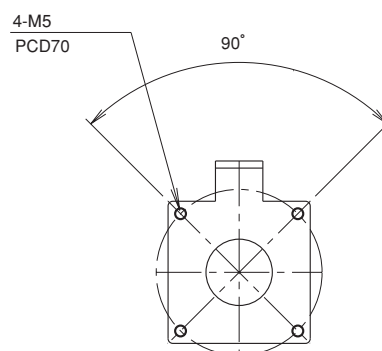
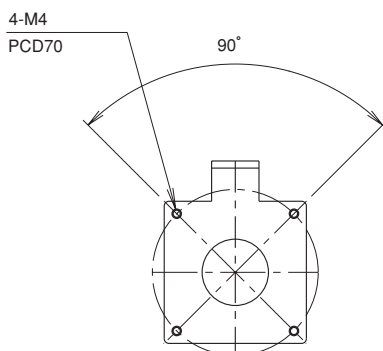
● SG46



- The above figure shows actuator with MSMA01 (PANASONIC): E□.
- Pulley unit position can be adjusted at 90 degree each.
- Motor parallel mounting can be equipped with dustproof cover and sensor
- Tension plate position can be built in pulley cover.
- The mass is 0.7kg larger than the values shown in tables on pages 35 and 37.
- Inertia moment is $1.24 \times 10^{-5} \text{kg} \cdot \text{m}^2$ larger than the value shown in table on page 5.

Mark	Motor option
E□	PANASONIC MINAS SERIES : 200W
F□	YASKAWA ELECTRIC SIGMA SERIES : 200W
	mitsubishi electric HC-MF SERIES : 200W
	SANYO ELECTRIC P3 SERIES : 200W
G□	ORIENTAL MOTOR STEPPING MOTOR □60 SERIES

Dimensions of parallel motor mounting Type E□ Dimensions of parallel motor mounting Type F□ Dimensions of parallel motor mounting Type G□



Model No.

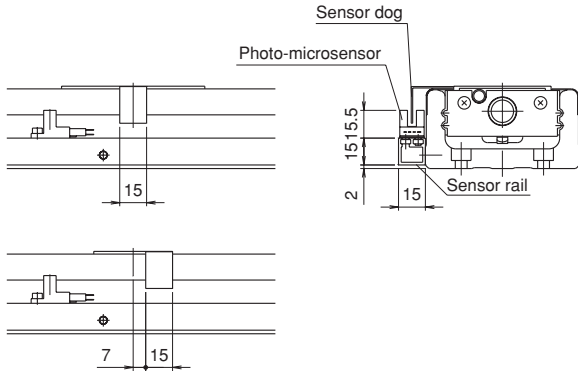
Model No.	Lead	Slide block
SG46	**	*
	10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks

Guide rail length	Performance grade
****	*
340, 440, 540, 640, 740, 840, 940, 1040, 1140, 1240	P, H

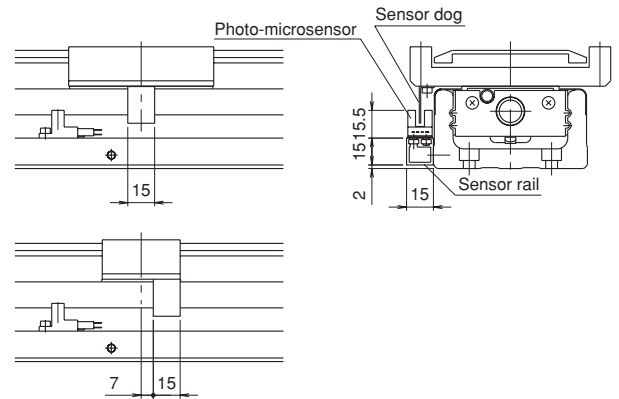
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, SUNX)

Without dustproof cover

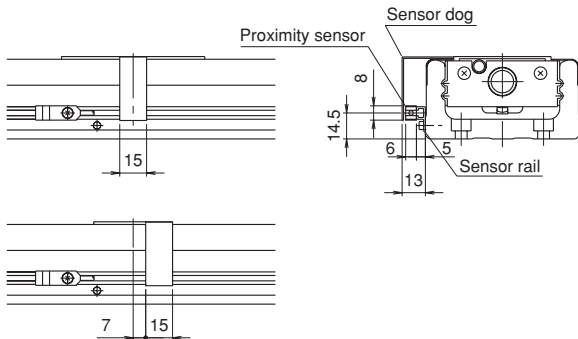


With dustproof cover

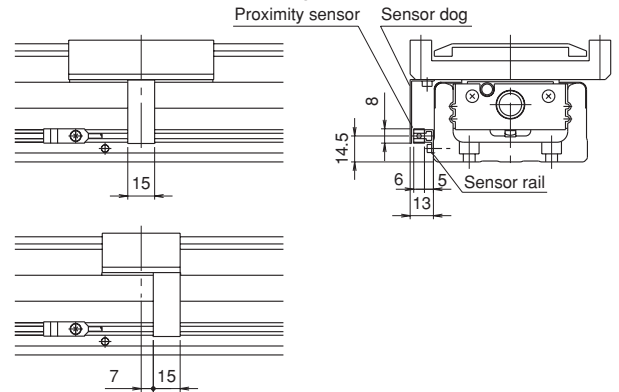


Symbol K (NPN) / E (PNP): Proximity sensor (YAMATAKE)

Without dustproof cover

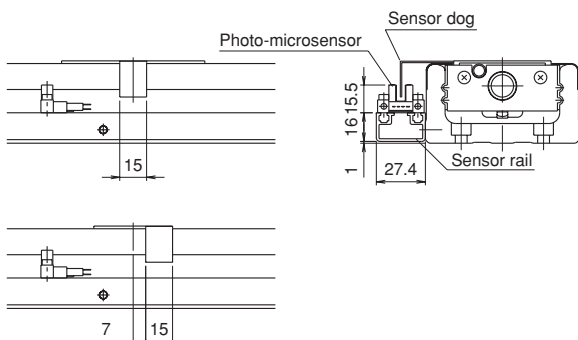


With dustproof cover

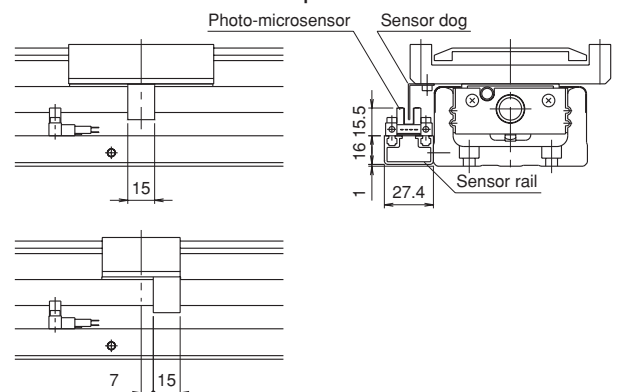


Symbol H (NPN) / J (PNP): Photo-microsensor (OMRON)

Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, B0, C0, D0, R0, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

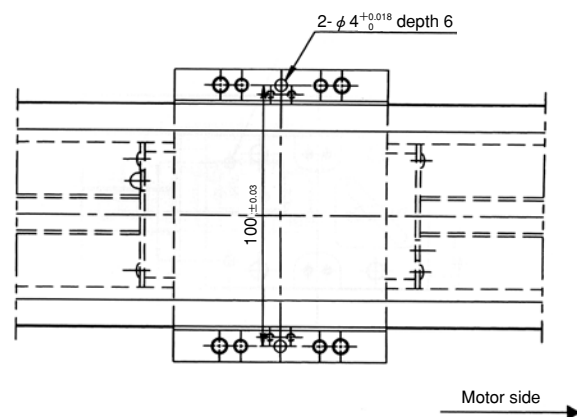
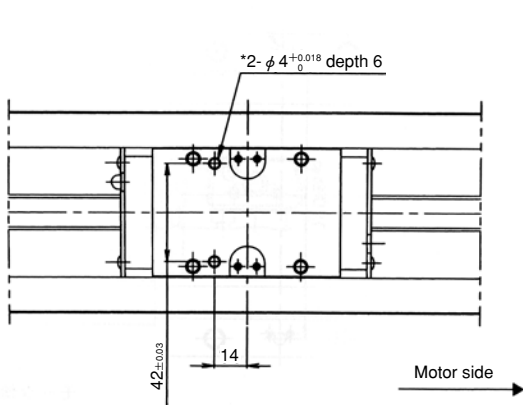
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover

Long block with dustproof cover

For actuators with 2 blocks, the holes are on both blocks.

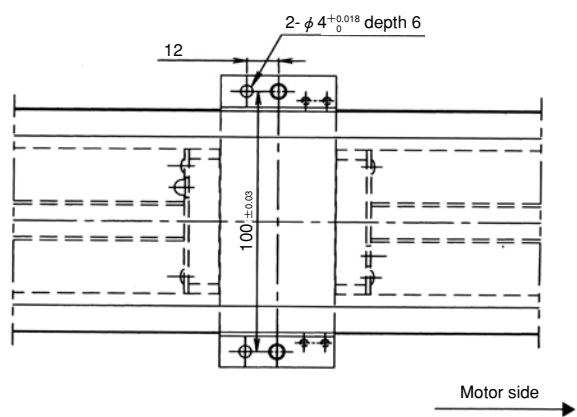
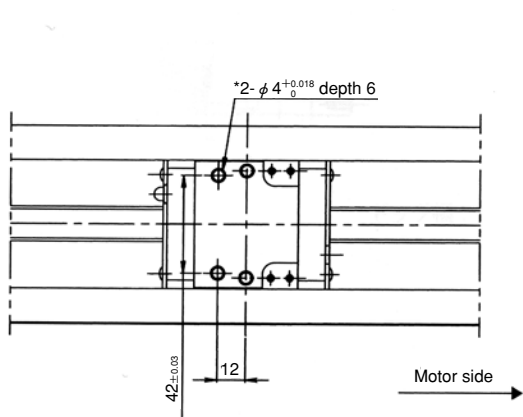


The hole with asterisk (*) may have diameter 5 counterbores for erasing the quenching layer when needed.

Short block without dustproof cover

Short block with dustproof cover

For actuators with 2 blocks, the holes are on both blocks.



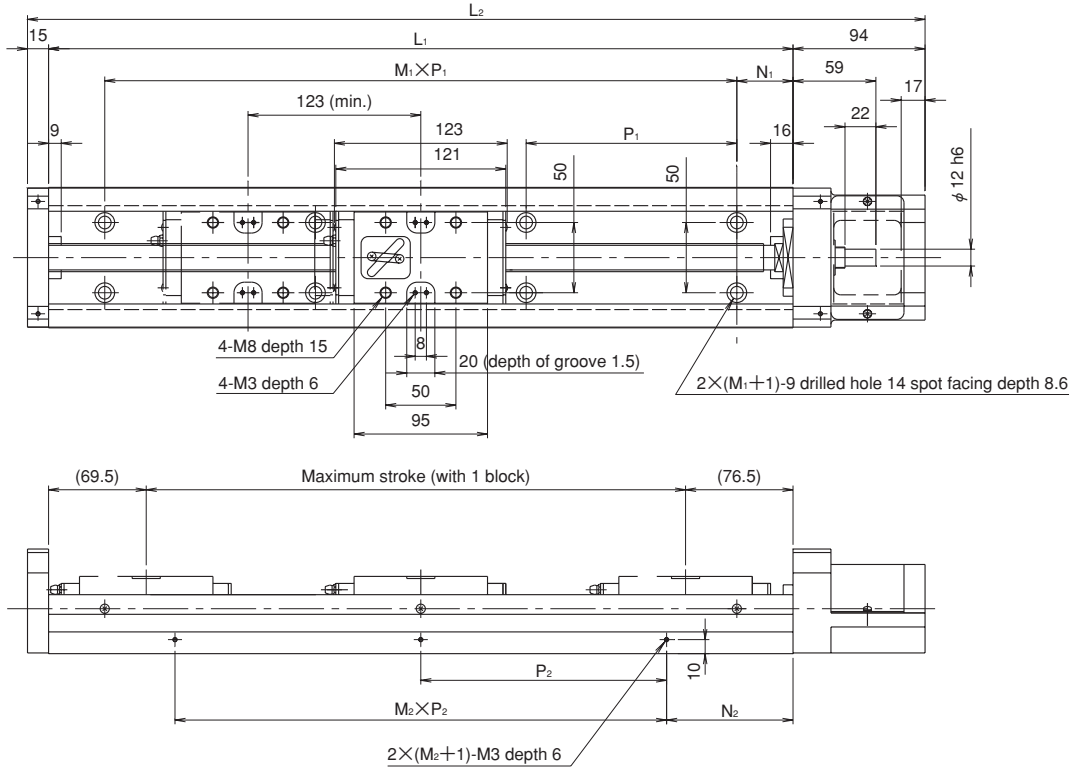
The hole with asterisk (*) may have diameter 5 counterbores for erasing the quenching layer when needed.

Model No.

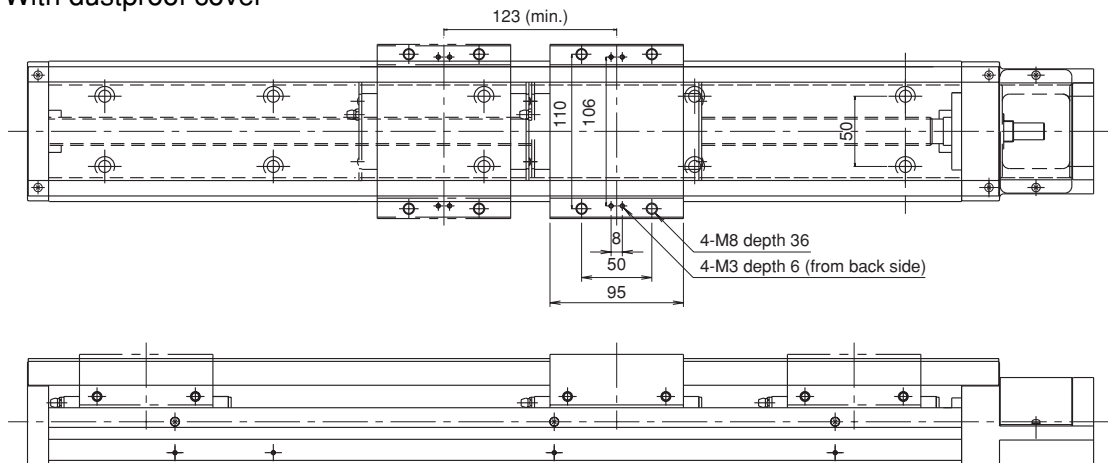
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG55	**	*	****	*
	20: 20mm	A: With 1 long block B: With 2 long blocks	980, 1080, 1180, 1280, 1380	P, H

LONG BLOCK CONFIGURATIONS

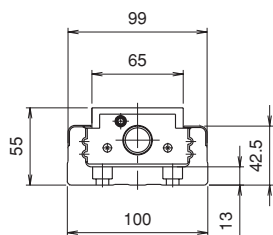
With 1 long block: A (With 2 long blocks: B)



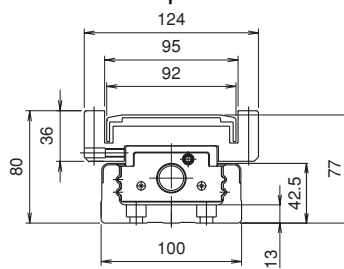
With dustproof cover



Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, R0	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
980	1089	40	6×150	90	4×200	834	711
1080	1189	15	7×150	40	5×200	934	811
1180	1289	65		90		1034	911
1280	1389	40	8×150	40	6×200	1134	1011
1380	1489	15	9×150	90		1234	1111

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (m/s)	Mass (kg)						
		Lead 20mm	Without cover		With cover		Slide block	
			A	B	A	B	Without cover	With cover
980	1120	20	22	21	24	1.70	2.30	
1080	910	22	24	23	26			
1180	750	23	25	25	27			
1280	630	25	27	27	29			
1380	530	27	29	29	31			

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

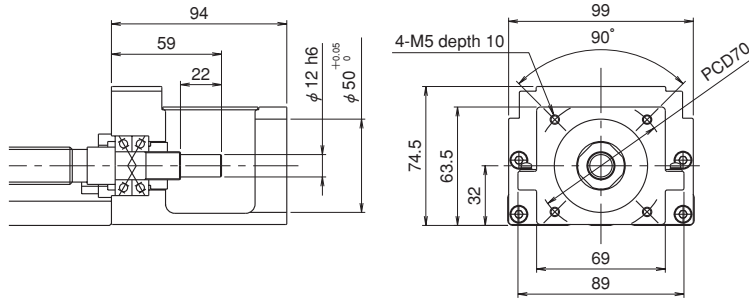
(Note 2) For long rail configurations, please consult KURODA.

Model No.

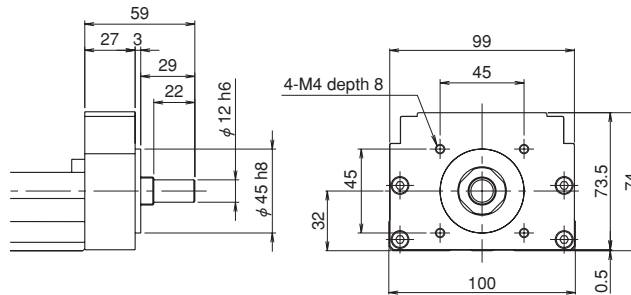
Model No.	Lead	Slide block	Guide rail length	Performance grade
SG55	** *	*	****	*
	20: 20mm	A: With 1 long block B: With 2 long blocks	980, 1080, 1180, 1280, 1380	P, H

● MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



Motor bracket configuration: R0



Mass of the R0 configuration is 0.3 kg less than the value shown in the table on page 45.

SG series

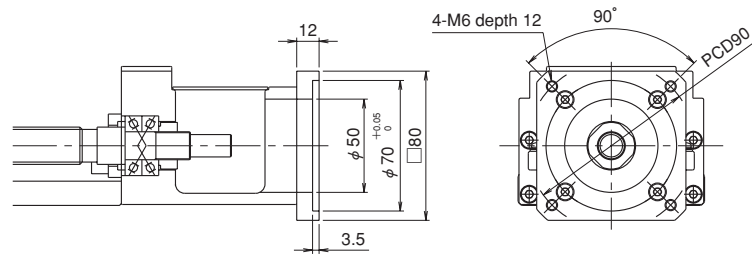
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, R0	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

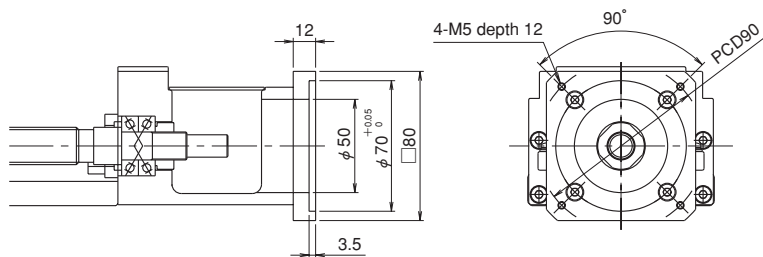
Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

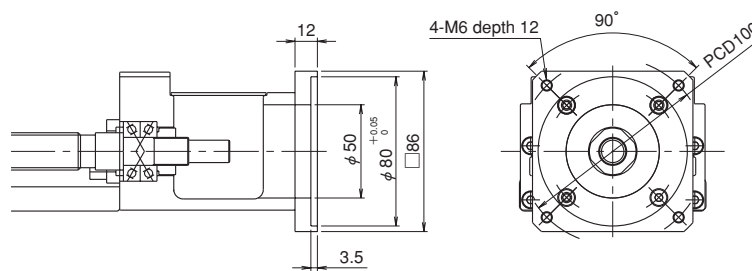
Motor bracket configuration: A1 (mass: 329g)



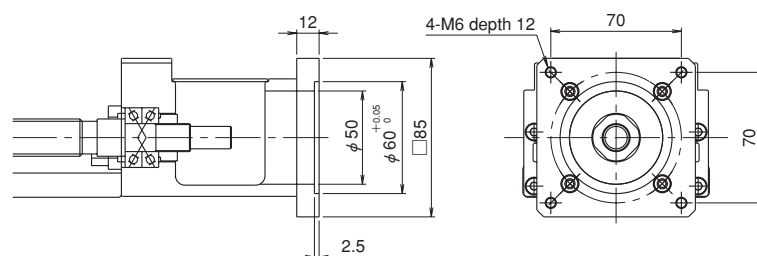
Motor bracket configuration: A2 (mass: 333g)



Motor bracket configuration: A3 (mass: 399g)



Motor bracket configuration: A4 (mass: 449g)



Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SG55	**	*	****	*
	20: 20mm	A: With 1 long block B: With 2 long blocks	980, 1080, 1180, 1280, 1380	P, H

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling
	Maker	Model No.	Output (W)		
AC Servo motor	PANASONIC	MSMD(MSMA)08	750	A2	SFC-040DA2 (MIKI PULLEY) LAD-40C (SAKAI)
	MITSUBISHI ELECTRIC	HF-KP(MP)23	200	A0	SFC-035DA2 (MIKI PULLEY) LAD-35C (SAKAI)
		HF-KP(MP)43	400		
		HF-KP(MP)73	750	A1	SFC-040DA2 (MIKI PULLEY) LAD-40C (SAKAI)
		HA-FF23	200	A2	
		HA-FF33	300		
	YASKAWA ELECTRIC	SGMJV,SGMAV(SGMAS)-02	200	A0	SFC-035DA2 (MIKI PULLEY) LAD-35C (SAKAI)
		SGMJV,SGMAV(SGMAS)-04	400		
		SGMJV,SGMAV(SGMAS)-08	750	A1	SFC-040DA2 (MIKI PULLEY) LAD-40C (SAKAI)
	SANYO ELECTRIC	Q1AA06020D	200	A0	SFC-035DA2 (MIKI PULLEY) LAD-35C (SAKAI)
		Q1AA06040D	400		
		Q1AA07075D	750	A1	SFC-040DA2 (MIKI PULLEY) LAD-40C (SAKAI)
		Q2AA07020D	200	A2	
		Q2AA07030D	300		
Q2AA07040D		400			
Q2AA08050D		500	A3		
Q2AA08075D	750				
Stepping motor	ORIENTAL MOTOR	UPK(RK)59,AS9	—	A4	SFC-035DA2 (MIKI PULLEY) LAD-35C (SAKAI)
	SANYO ELECTRIC	F series□85mm	—		
	TECHNO DRIVE	* K-M(G)59 *	—		

- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type of coupling for connecting a motor, consult KURODA.
- For detailed specifications of above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, R0	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

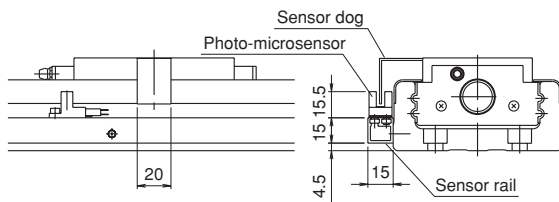
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

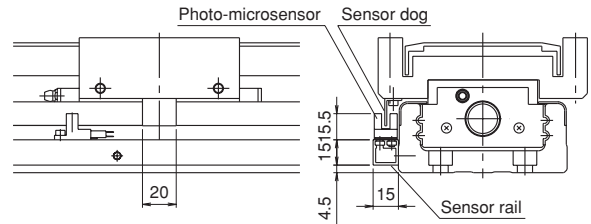
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, SUNX)

Without dustproof cover

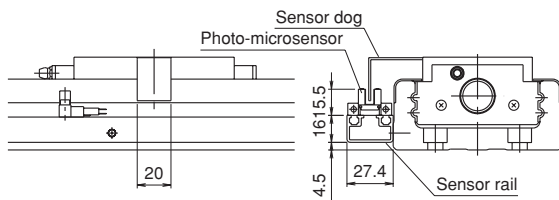


With dustproof cover

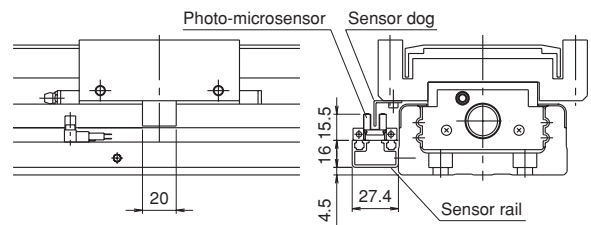


Symbol H (NPN) / J (PNP): Photo-microsensor (OMRON)

Without dustproof cover

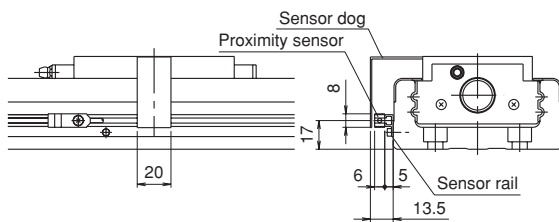


With dustproof cover

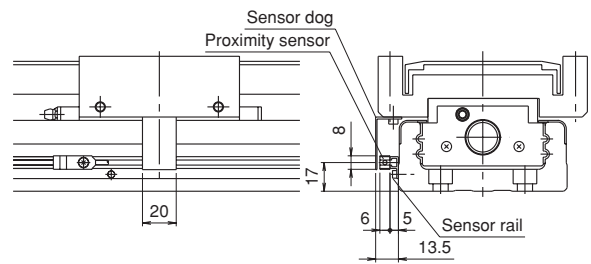


Symbol K (NPN) / E (PNP): Proximity sensor (YAMATAKE)

Without dustproof cover



With dustproof cover



Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SG55	**	*	****	*
	20: 20mm	A: With 1 long block B: With 2 long blocks	980, 1080, 1180, 1280, 1380	P, H

Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, R0	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P, H, J: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

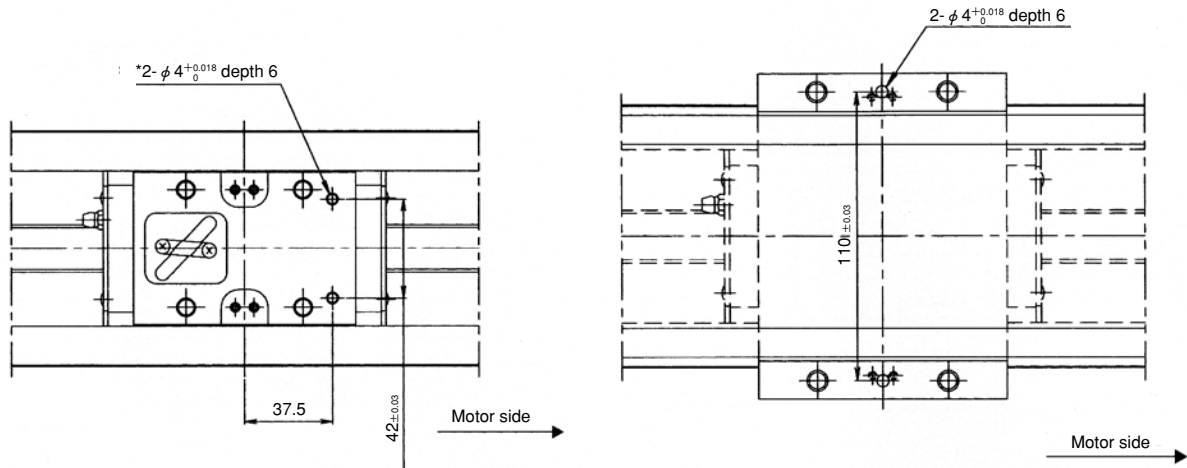
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover

Long block with dustproof cover

For actuators with 2 blocks, the holes are on both blocks.



The hole with asterisk (*) may have diameter 5 counterbores for erasing the quenching layer when needed.

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VARIATIONS

Model No.	SE15	SE23	SE30	SE45
Performance grade	U: Repeated positioning accuracy $\pm 5 \mu\text{m}^*$ (Ball screw - lead accuracy C7 grade, axial clearance 0mm) W: Repeated positioning accuracy $\pm 10 \mu\text{m}^*$ (Ball screw - lead accuracy C7 grade, axial clearance 0.02mm or less)			
Screw shaft dia. (mm)	6	8	10	15
lead (mm)	1	☉		
	2	☉	●	
	4		●	☉
	5		☉	☉
	8		●	
	10			☉
	20			☉



☉: In-stock items ●: Manufactured by order
 (Note 1) Asterisked (*) items may be different from the values shown above, depending on applied options and usage.

SE series

HOW TO INTERPRET MODEL NO.

Model	Lead	Slide block	Guide rail length (Note 4)	Performance grade
SE**	**	*	***	*
SE15	1, 2	A: With 1 long block B: With 2 long blocks	100, 150, 200	U grade • Repeated positioning accuracy $\pm 5 \mu\text{m}$ • Lead accuracy grade C7 or equivalent • Axial clearance 0mm
SE23	2, 5		150, 200, 250, 300	
SE30	4, 5, 10	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	150, 200, 300, 400, 500, 600, 700, 750	W grade • Repeated positioning accuracy $\pm 10 \mu\text{m}$ • lead accuracy grade C7 or equivalent • Axial clearance 0.02mm or less
SE45	5, 10, 20		540, 640, 740, 840, 940	

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3	N: Without cover C: With dustproof cover	N: Without sensor K, E: Proximity sensor	N: Standard treatment (Note 1) L: Anti corrosive black coating	N: Standard grease (Note 2) C: Dust preventive grease (Note 3)	Not available
A0, A1, A2, A3, A5, A6, A7		N: Without sensor S: Photo-microsensor K, E: Proximity sensor			PS: Dowel pin hole provided
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□		N: Without sensor M, Y, C, P: Photo-microsensor			No symbol: Not provided
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□		N: Without sensor M, Y, C, P: Photo-microsensor			

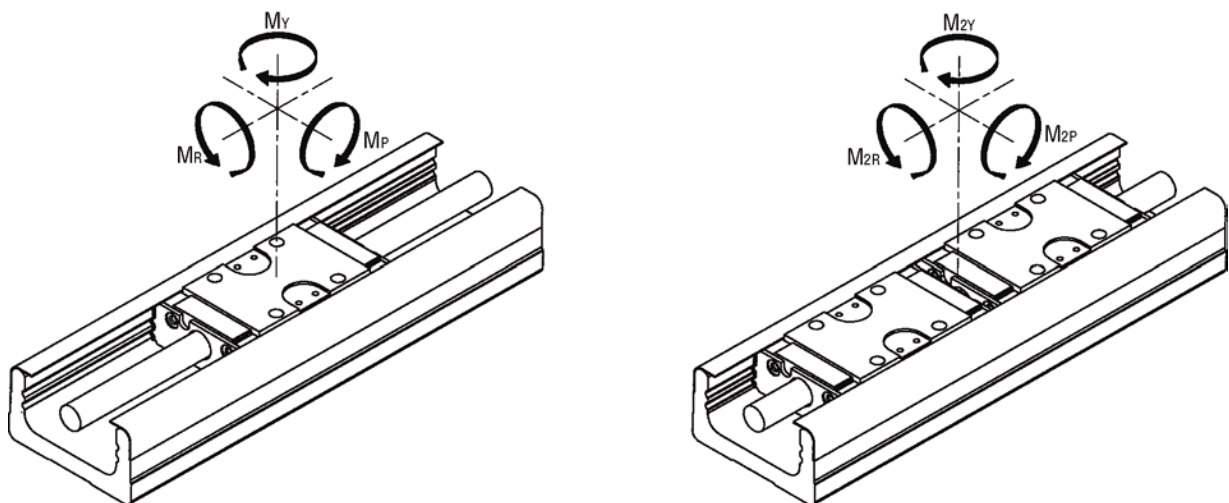
(Note 1) With standard specifications of surface treatment (Symbol N), only guide rails are treated with black coating.
 (Note 2) With standard grease (Symbol: N), Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) is contained in slide block and ball screw components.
 (Note 3) For dust preventive grease (Symbol C), KURODA C-grease is contained.
 (Note 4) For specifications of guide rail with long rails or intermediate stroke of non-standard length, consult KURODA.

SPECIFICATIONS

Model No.			SE1501	SE1502	SE2302	SE2305	SE3004	SE3005	SE3010	SE4505	SE4510	SE4520			
Performance grade			W	U	W	U	W	U	W	U	W	U	W	U	
Guide	Radial clearance		μm		-3~0		-3~0		-3~0		-5~0				
	Long block	Basic dynamic load rating	C	kN		1.6		4.3		7		27			
		Basic static load rating	Co	kN		2.7		7.0		11.8		45.0			
		Static permissible moment	M _P	N·m	10		46		101		572				
			M _{2P}		60		276		606		3,432				
			M _Y		11		51		120		681				
			M _{2Y}		71		306		720		4,086				
			M _R		28		134		260		1,410				
	M _{2R}	56		268		520		2,820							
	Short block	Basic dynamic load rating	C	kN		Not available		Not available		Not available		16.9			
		Basic static load rating	Co	kN		Not available		Not available		Not available		28.1			
		Static permissible moment	M _P	N·m	Not available		Not available		Not available		Not available		223		
			M _{2P}		Not available		Not available		Not available		Not available		1,341		
			M _Y		Not available		Not available		Not available		Not available		266		
M _{2Y}			Not available		Not available		Not available		Not available		1,598				
M _R			Not available		Not available		Not available		Not available		887				
M _{2R}	Not available		Not available		Not available		Not available		1,774						
Ball screw	Shaft diameter		mm		6		8		10		15				
	Lead		mm		1	2	2	5	4	5	10	5	10	20	
	Basic dynamic load rating	Ca	kN		0.39	0.54	1.8	1.9	3.0	3.0	2.0	5.1	5.1	3.1	
	Basic static load rating	Coa	kN		0.77	0.76	3.2	3.1	5.3	5.3	3.2	10.5	10.5	6.6	
	Precision grade				C7 grade or equivalent		C7 grade or equivalent		C7 grade or equivalent		C7 grade or equivalent				
	Axial clearance		mm		~0.02	0	~0.02	0	~0.02	0	~0.02	0	~0.02	0	~0.02
Fixed side bearing	Model No. of bearing				604 or equivalent		AC6-16DF or equivalent		708DFP5 or equivalent		5201A or equivalent				
	Basic dynamic load rating	Cb	kN		0.5		1.79		4.40		5.90				
	Basic static load rating	Cob	kN		0.19		1.76		4.36		3.20				

SE series

DIRECTION OF MOMENT



ACCURACY

Model No.	Guide rail length (mm)	Repeated positioning accuracy (μm)		Positioning accuracy (μm)		Travelling parallelism B (μm)		Backlash (μm)		Starting torque ($\text{N}\cdot\text{m}$)	
		W	U	W	U	W	U	W	U	W	U
SE15	100	± 10	± 5	65		15		20	5	0.010	0.012
	150			70							
	200			75							
SE23	150	± 10	± 5	70		15		20	5	0.03	0.06
	200			75							
	250			85							
	300			90							
SE30	150	± 10	± 5	70		15		20	5	0.07	0.15
	200			80							
	300			90							
	400			95							
	500			100		25					
	600			110							
	700			120							
	750			130							
SE45	540	± 10	± 5	110		40		20	5	0.1	0.2
	640			120							
	740			130							
	840			150		50					
	940			170							

(Note 1) Measurement is to be performed with KURODA's specified motor mounted.

(Note 2) Above starting torque value is applied when the standard grease is used. The value may change depending on the properties of the grease.

INERTIA

Inertia for slide block and ball screw of ballscrew actuator is shown in the following table.

(Unit: $\times 10^{-5} \text{kg}\cdot\text{m}^2$)

Model No.	Guide rail length (mm)	Without dustproof cover				With dustproof cover			
		Long block		Short block		Long block		Short block	
		1 block	2 blocks	1 block	2 blocks	1 block	2 blocks	1 block	2 blocks
		A	B	C	D	A	B	C	D
SE1501	100	0.0111	—	—	—	0.012	—	—	—
	150	0.0160	0.0161			0.0161	0.0162		
	200	0.0210	0.0211			0.0211	0.0212		
SE1502	100	0.0115	—	—	—	0.0116	—	—	—
	150	0.0164	0.0167			0.0166	0.0171		
	200	0.0214	0.0217			0.0216	0.0220		
SE2302	150	0.0607	—	—	—	0.0615	—	—	—
	200	0.0764	0.0779			0.0772	0.0787		
	250	0.0921	0.0936			0.0929	0.0944		
	300	0.1080	0.1090			0.1090	0.1100		
SE2305	150	0.0696	—	—	—	0.0741	—	—	—
	200	0.0853	0.0946			0.0898	0.0992		
	250	0.1010	0.1100			0.1060	0.1150		
	300	0.1170	0.1260			0.1210	0.1310		
SE3004	150	0.157	—	—	—	0.162	—	—	—
	200	0.196	—			0.201	—		
	300	0.273	0.284			0.277	0.289		
	400	0.350	0.361			0.354	0.366		
	500	0.426	0.438			0.431	0.442		
	600	0.503	0.514			0.507	0.519		
	700	0.580	0.591			0.584	0.596		
SE3005	150	0.165	—	—	—	0.172	—	—	—
	200	0.203	—			0.21	—		
	300	0.28	0.298			0.287	0.305		
	400	0.356	0.374			0.363	0.381		
	500	0.433	0.451			0.44	0.458		
	600	0.51	0.528			0.517	0.535		
	700	0.587	0.605			0.593	0.611		
SE3010	150	0.222	—	—	—	0.25	—	—	—
	200	0.261	—			0.288	—		
	300	0.337	0.409			0.365	0.437		
	400	0.414	0.486			0.442	0.514		
	500	0.491	0.562			0.518	0.59		
	600	0.567	0.639			0.595	0.667		
	700	0.644	0.716			0.672	0.744		
	750	0.682	0.754			0.71	0.782		
SE4505	540	2.40	2.46	2.38	2.42	2.42	2.50	2.40	2.45
	640	2.79	2.85	2.77	2.81	2.81	2.89	2.78	2.83
	740	3.17	3.24	3.16	3.20	3.20	3.28	3.17	3.22
	840	3.56	3.62	3.55	3.59	3.59	3.67	3.56	3.61
	940	3.95	4.01	3.94	3.97	3.98	4.05	3.95	4.00
SE4510	540	2.58	2.81	2.51	2.66	2.67	2.98	2.56	2.76
	640	2.97	3.20	2.90	3.05	3.06	3.37	2.95	3.15
	740	3.36	3.59	3.28	3.44	3.44	3.76	3.33	3.54
	840	3.75	3.98	3.67	3.82	3.83	4.14	3.72	3.93
	940	4.14	4.36	4.06	4.21	4.22	4.53	4.11	4.31
SE4520	540	3.31	4.22	3.01	3.62	3.65	4.89	3.21	4.02
	640	3.70	4.61	3.40	4.00	4.03	5.28	3.60	4.41
	740	4.09	5.00	3.78	4.39	4.42	5.67	3.99	4.80
	840	4.48	5.39	4.17	4.78	4.81	6.06	4.38	5.19
	940	4.86	5.78	4.56	5.17	5.20	6.45	4.76	5.57

(Note 1) Dash (-) in the above table means the configuration is not available.

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease
* *	*	*	*	*
A0, A1, A2, A3	N: Without cover C: With dustproof cover	N: Without sensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	P_2	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
100	147	25	1×50	3	106	60	—
150	197		2×50		156	110	70
200	247		3×50		206	160	120

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	1mm	2mm	A	B	A	B		
100	133	260	0.28	—	0.31	—	0.03	0.05
150			0.36	0.39	0.39	0.44		
200	90	180	0.45	0.48	0.48	0.53		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

(Note 2) Hex socket head cap screws (M3×5, with stainless steel) should be used for fixing guide rails.

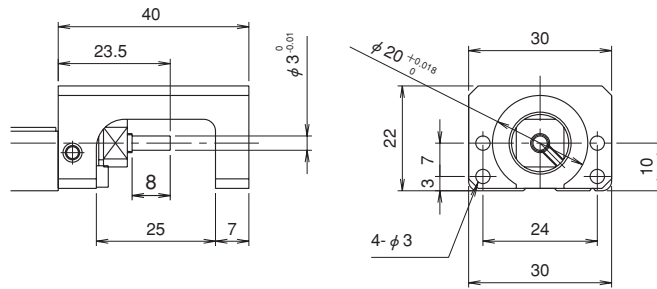
(Note 3) For long rail configurations, please consult KURODA.

Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE15	**	*	***	*
	01: 1mm 02: 2mm	A: With 1 long block B: With 2 long blocks	100, 150, 200	W, U

● MOTOR BRACKET CONFIGURATIONS

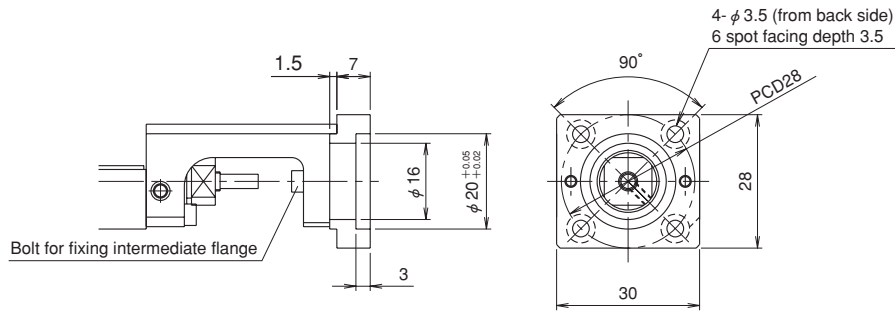
Motor bracket configuration: A0



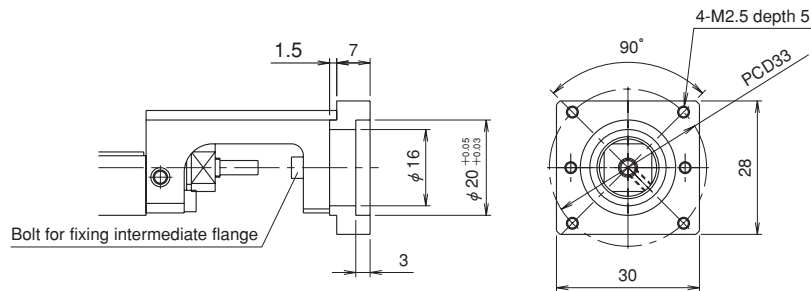
Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease
**	*	*	*	*
A0, A1, A2, A3	N: Without cover C: With dustproof cover	N: Without sensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

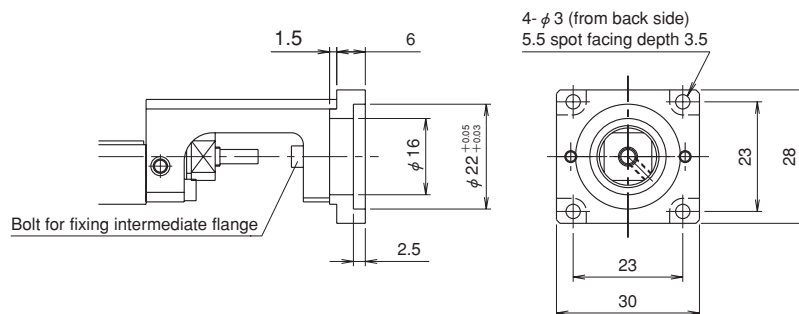
Motor bracket configuration: A1 (mass: 10g)



Motor bracket configuration: A2 (mass: 10g)



Motor bracket configuration: A3 (mass: 10g)



(Note) For A1 and A3 configuration, install the intermediate flange to motor before mounting it to actuator.

Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE15	**	*	***	*
	01: 1mm 02: 2mm	A: With 1 long block B: With 2 long blocks	100, 150, 200	W, U

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling
	Maker	Model No.	Output (W)		
AC Servo motor	MITSUBISHI	HC-AQ013	10	A2	ALS-014 (MIKI PULLEY)
	ELECTRIC	HC-AQ023	20		
	YASKAWA ELECTRIC	SGMM-A1	10	A1	
		SGMM-A2	20		
Stepping motor	ORIENTAL MOTOR	PK223	—	A3	
		PK225	—		

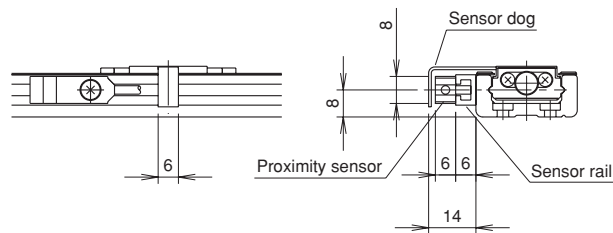
- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type coupling for connecting a motor, consult KURODA.
- For detailed specifications for above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease
**	*	*	*	*
A0, A1, A2, A3	N: Without cover C: With dustproof cover	N: Without sensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

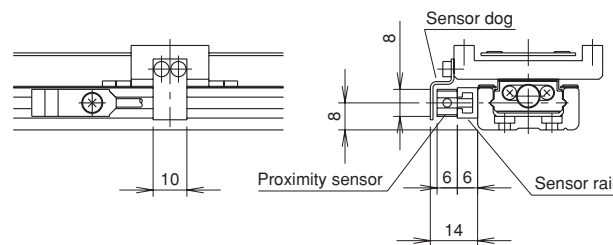
● SENSOR

Symbol K (NPN) / E (PNP): Proximity sensor (YAMATAKE)

Without cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A5, A6, A7	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
150	210	35	1×80	25	1×100	76	—
200	260	20	2×80	50		126	57
250	310	45		3×80	25	2×100	176
300	360	30	50		226		157

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)				Slide block	
	Lead		Without cover		With cover		Without cover	With cover
	2mm	5mm	A	B	A	B		
150	200	490	1.00	—	1.11	—	0.14	0.26
200			1.21	1.35	1.32	1.46		
250			1.41	1.56	1.52	1.67		
300			1.61	1.76	1.73	1.88		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

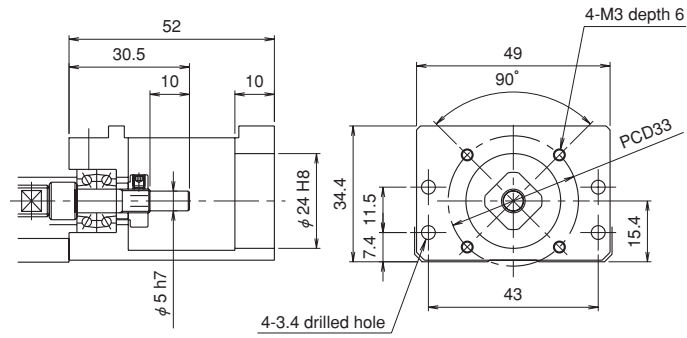
(Note 2) For long rail configurations, please consult KURODA.

Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE23	**	*	***	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	W, U

● MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



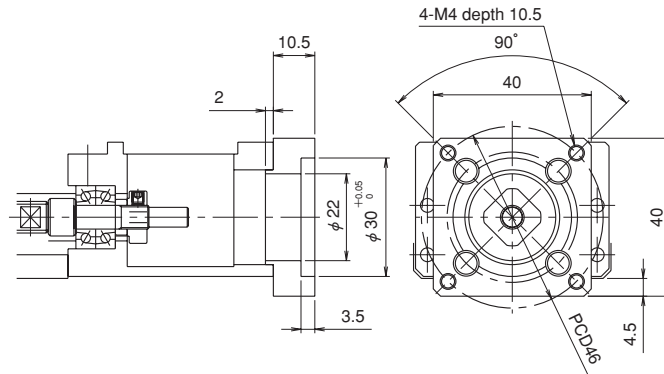
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A5, A6, A7	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

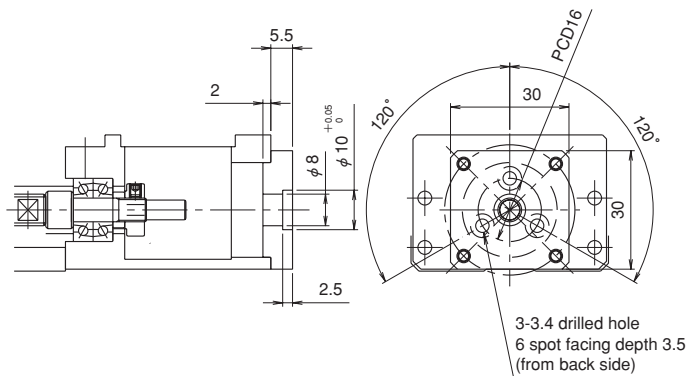
Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

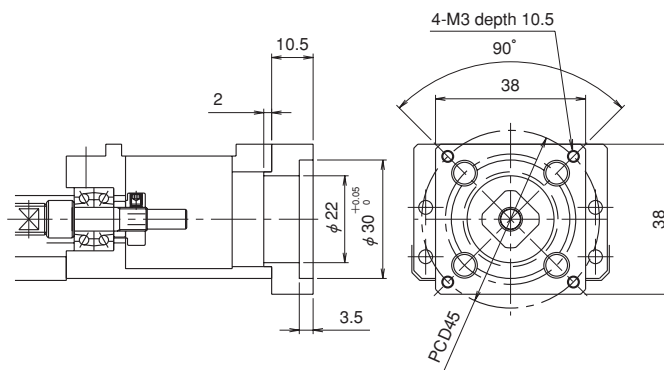
Motor bracket configuration: A1 (mass: 28g)



Motor bracket configuration: A2 (mass: 12g)



Motor bracket configuration: A3 (mass: 24g)



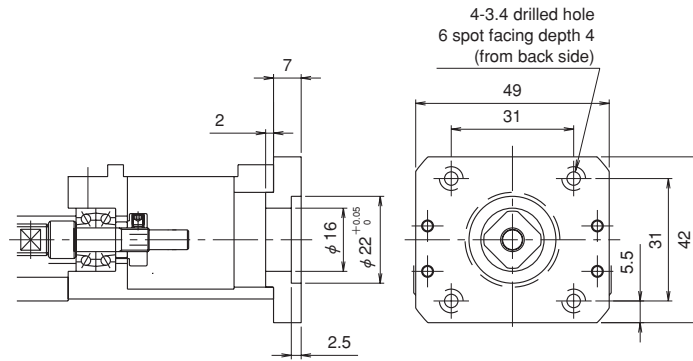
(Note) For A2 configuration, install the intermediate flange to motor before mounting it to actuator.

Model No.

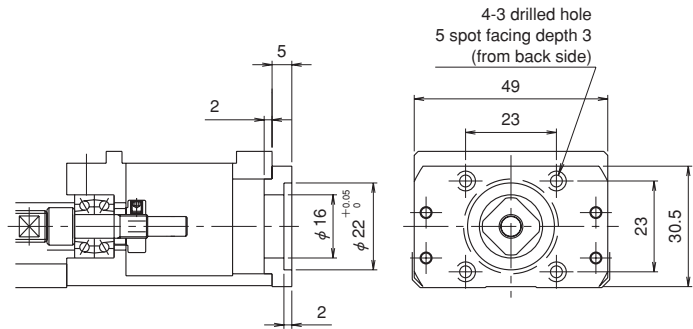
Model No.	Lead	Slide block	Guide rail length	Performance grade
SE23	**	*	** *	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	W, U

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

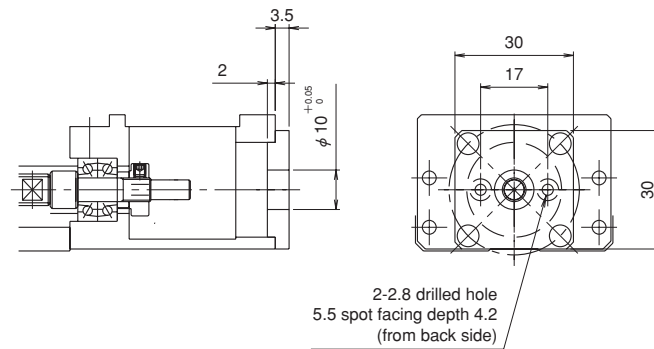
Motor bracket configuration: A5 (mass: 32g)



Motor bracket configuration: A6 (mass: 16g)



Motor bracket configuration: A7 (mass: 8g)



(Note) For A5, A6, and A7 configuration, install the intermediate flange to motor before mounting it to actuator.

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A5, A6, A7	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling
	Maker	Model No.	Output (W)		
AC Servo motor	PANASONIC	MSM5BZ21A	5	A2	SFC-010DA2 (MIKI PULLEY) LAD-20C (SAKAI)
		MSM1AZ21A	10		
		MSM2AZ21A	20		
		MSMA3AZ	30	A3	
		MSMA5AZ	50		
		MSMA01	100		
	MITSUBISHI ELECTRIC	HC-KFS (MFS,PQ)053	50	A1	
		HC-KFS (MFS,PQ)13	100		
	YASKAWA ELECTRIC	SGMAH (SGML)-A3	30	A1	
		SGMAH (SGML)-A5	50		
		SGMAH (SGML)-01	100		
	SANYO ELECTRIC	P30B04003	30	A1	
		P30B04005	50		
		P30B04010	100		
	CITIZEN CHIBA PRECISION	EA-2565	12	A7	
		EA-2580	20		
	HITACHI INDUSTRIAL EQUIPMENT SYSTEMS	ADMA-R5	50	A1	
ADMA-01		100			
TAMAGAWA SEIKI	TS4601	30	A1		
	TS4602	50			
	TS4603	100			
FANUC	β M0.2	50	A1		
	β M0.3	100			
Stepping motor	ORIENTAL MOTOR	UPD534M-A	—	A5	
		PMU33AH	—	A6	
		UPK (RK)54,AS4	—	A5	

- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type coupling for connecting a motor, consult KURODA.
- For detailed specifications for above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

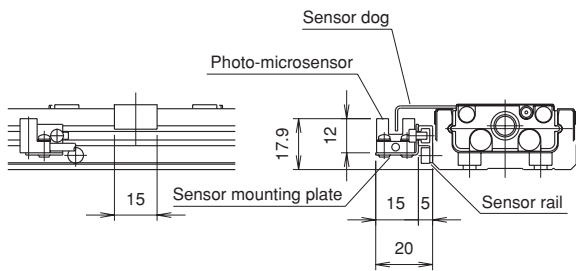
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE23	**	*	** *	*
	02: 2mm 05: 5mm	A: With 1 long block B: With 2 long blocks	150, 200, 250, 300	W, U

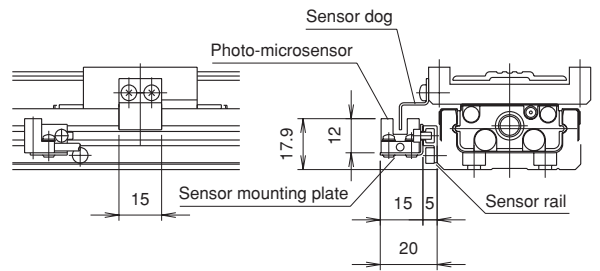
● **SENSOR**

Symbol S (NPN): Photo-microsensor (SUNX)

Without cover

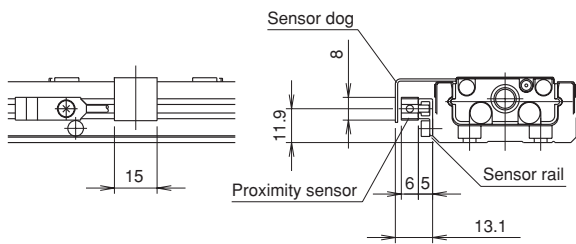


With dustproof cover

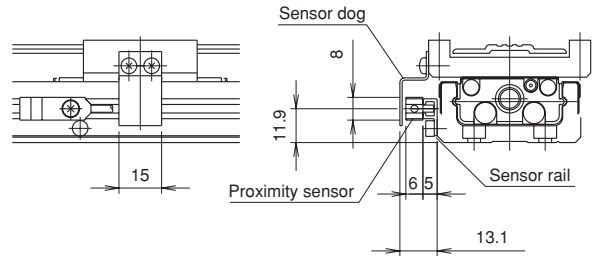


Symbol K (NPN) / E (PNP): Proximity sensor (YAMATAKE)

Without cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A5, A6, A7	N: Without cover C: With dustproof cover	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

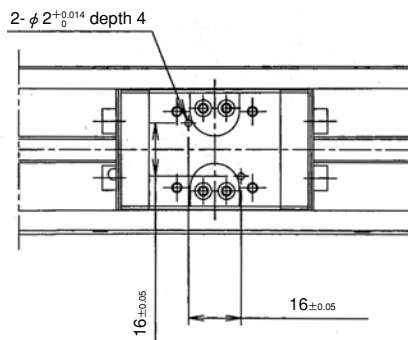
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

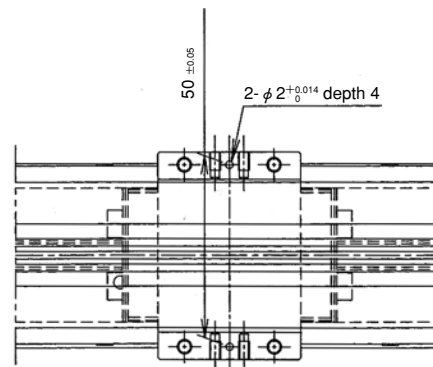
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For an actuator with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover



Long block with dustproof cover



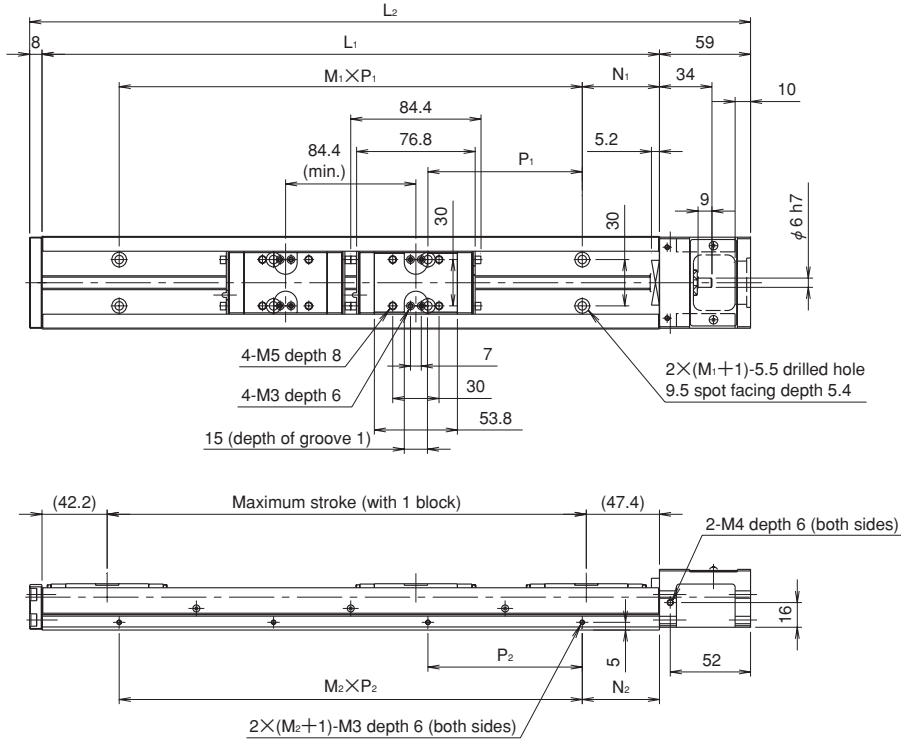
Model No.

Model No.	Lead	Slide block
SE30	* *	*
	04: 4mm 05: 5mm 10: 10mm	A: With 1 long block B: With 2 long blocks

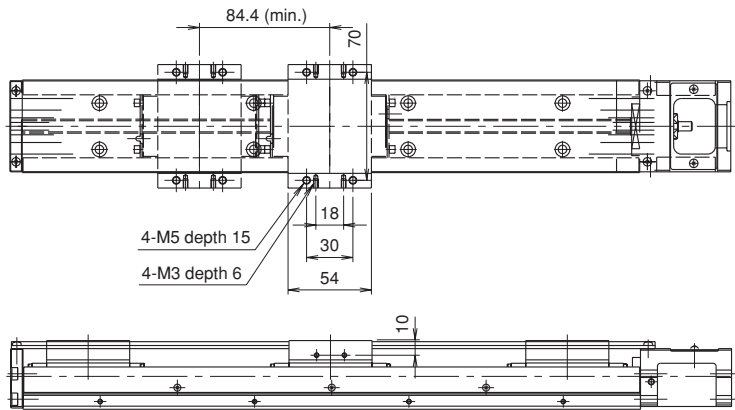
Guide rail length	Performance grade
* * *	*
150, 200, 300, 400, 500, 600, 700, 750	W, U

LONG BLOCK CONFIGURATIONS

With 1 long block: A (With 2 long blocks: B)

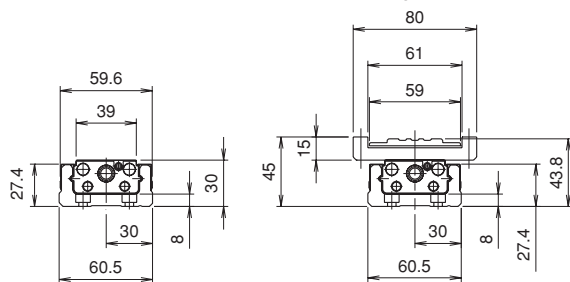


With dustproof cover



Without cover

With dustproof cover



SE series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
150	217	25	1×100	25	1×100	60	—
200	267	50		50		110	—
300	367		2×100		210	126	
400	467		3×100		310	226	
500	567		4×100		410	326	
600	667		5×100		510	426	
700	767	6×100	610	526			
750	817	25	7×100	25	7×100	660	576

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)				Slide block	
	Lead			Without cover		With cover		Without cover	With cover
	4mm	5mm	10mm	A	B	A	B		
150	320	400	810	1.6	—	1.7	—	0.30	0.40
200				1.9	—	2.1	—		
300				2.6	2.9	2.7	3.2		
400				3.3	3.6	3.4	3.8		
500				3.9	4.2	4.1	4.5		
600	240	300	600	4.6	4.9	4.7	5.1		
700	170	210	430	5.2	5.5	5.4	5.8		
750	—	—	380	5.6	5.9	5.7	6.1		

(Note 1) Guide rail length of 750 mm is available only for SE3010.

(Note 2) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

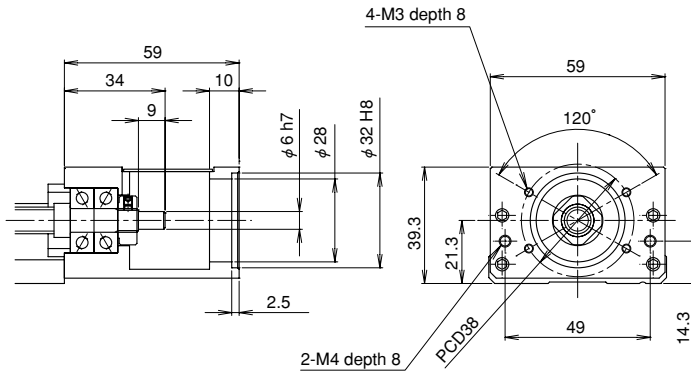
(Note 3) For long rail configurations, please consult KURODA.

Model No.

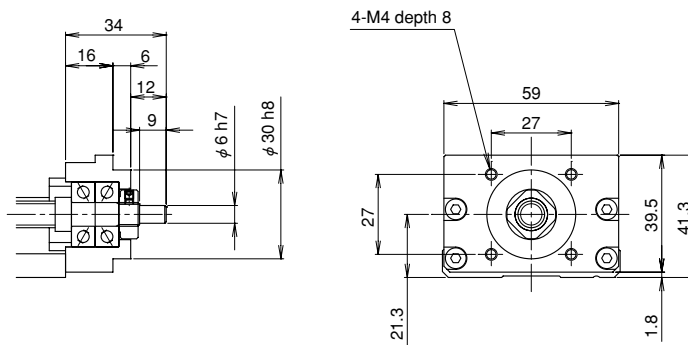
Model No.	Lead	Slide block	Guide rail length	Performance grade
SE30	**	*	***	*
	04: 4mm 05: 5mm 10: 10mm	A: With 1 long block B: With 2 long blocks	150, 200, 300, 400, 500, 600, 700, 750	W, U

MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



Motor bracket configuration: RN



Mass of the RN configuration is 0.085 kg less than the value shown in the table on page 71.

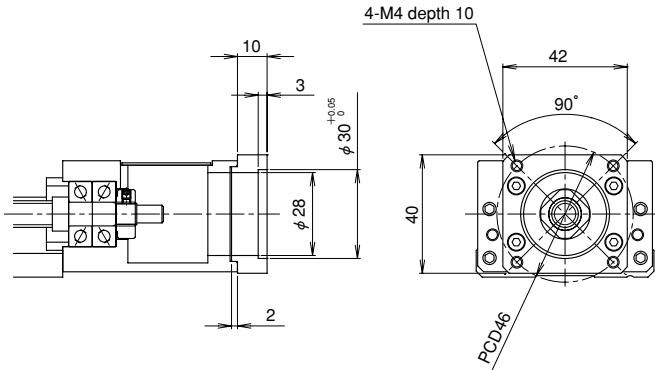
Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

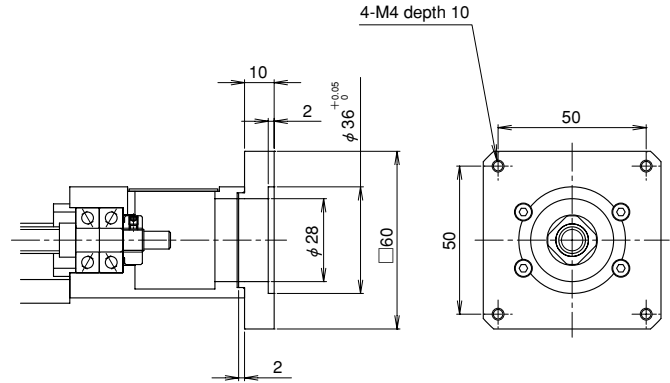
Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

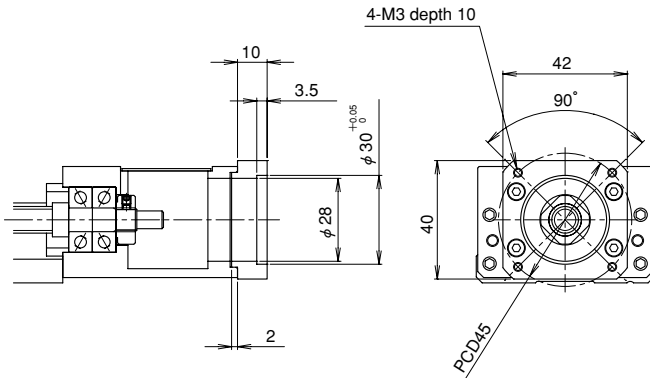
Motor bracket configuration: A1 (mass: 25g)



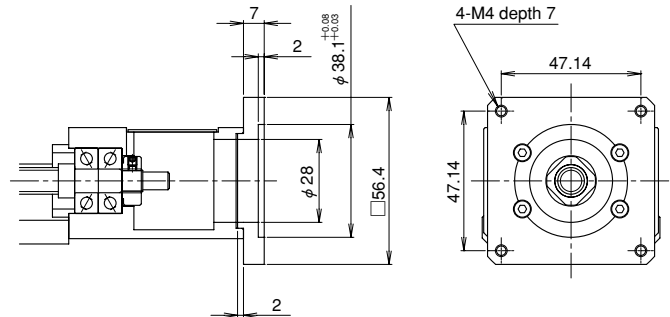
Motor bracket configuration: A4 (mass: 71g)



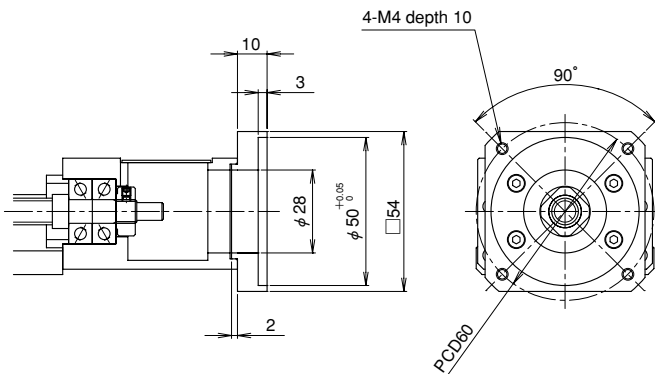
Motor bracket configuration: A2 (mass: 25g)



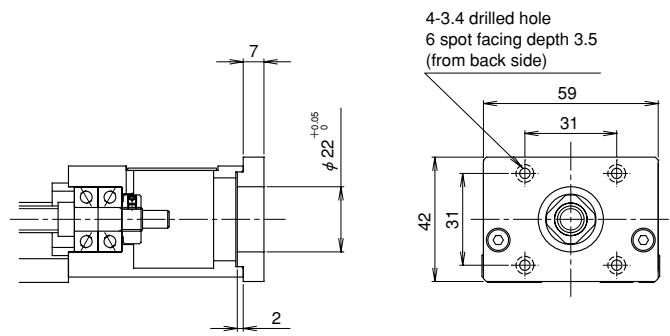
Motor bracket configuration: A5 (mass: 46g)



Motor bracket configuration: A3 (mass: 55g)



Motor bracket configuration: B1 (mass: 37g)



(Note) For B1 configuration, install the intermediate flange to motor before mounting it to actuator.

Model No.

Model No.	Lead	Slide block
SE30	* *	*
	04: 4mm 05: 5mm 10: 10mm	A: With 1 long block B: With 2 long blocks

Guide rail length	Performance grade
* * *	*
150, 200, 300, 400, 500, 600, 700, 750	W, U

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling
	Maker	Model No.	Output (W)		
AC Servo motor	PANASONIC	MSMA3AZ	30	A2	SFC-020DA2 (MIKI PULLEY) LAD-25C (SAKAI)
		MSMA5AZ	50		
		MSMA01	100		
	MITSUBISHI ELECTRIC	HC-KFS (MFS,PQ)053	50	A1	
		HC-KFS (MFS,PQ)13	100	A3	
		HA-FF053	50		
		HA-FF13	100		
	YASKAWA ELECTRIC	SGMAH (SGML)-A3	30	A1	
		SGMAH (SGML)-A5	50		
		SGMAH (SGML)-01	100		
	SANYO ELECTRIC	P30B04003	30	A1	
		P30B04005	50		
		P30B04010	100	A3	
		P50B05005	50		
		P50B05010	100		
	HITACHI INDUSTRIAL EQUIPMENT SYSTEMS	ADMA-R5	50	A1	
		ADMA-01	100		
	TAMAGAWA SEIKI	TS4601	30	A1	
TS4602		50			
TS4603		100			
FANUC	β M0.2	50	A1		
	β M0.3	100			
Stepping motor	ORIENTAL MOTOR	UPK (RK)54,AS4	—	B1	
		UPK (RK)56,AS6	—	A4	
		UK26,UMK26,CSK26	—	A5	

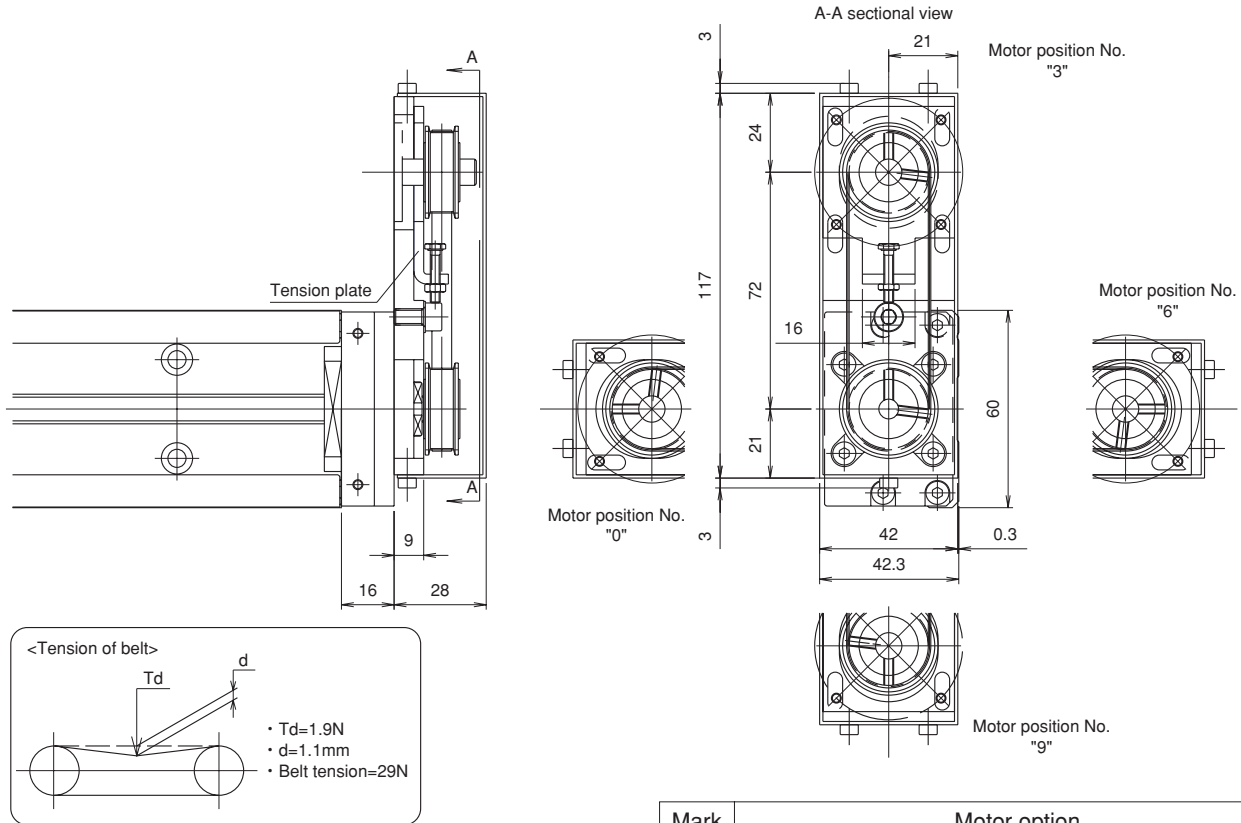
- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type coupling for connecting a motor, consult KURODA.
- For detailed specifications for above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

● PARALLEL MOTOR MOUNTING



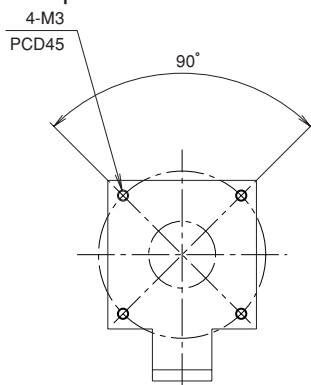
- The above figure shows actuator with MSMA01 (PANASONIC): E□.
- Pulley unit position can be adjusted at 90 degree each.
- Motor parallel mounting can be equipped with dustproof cover and sensor
- Fill Motor position No. in □.

If the pulley cover may not be removable due to restrictions arising from direction of the unit, consult KURODA for modifying positions of the pulley-cover fixing bolts (3 M3 hex socket bolts).

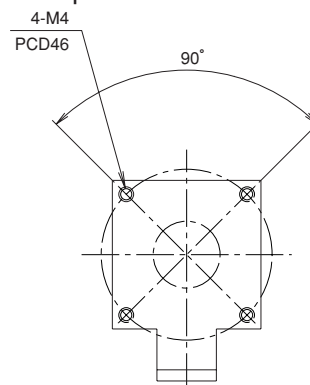
- Tension plate position can be built in pulley cover.
- Although tension plate is attached inside the cover with standard specifications, it can also be attached to outside the cover. Consult KURODA for such modification.
- The mass is 0.2kg larger than the values shown in table on page 71.
- Inertia moment is $2.22 \times 10^{-5} \text{kg} \cdot \text{m}^2$ larger than the value shown in table on page 55.

Mark	Motor option
E□	PANASONIC MINAS SERIES : 50~100W
F□	YASKAWA ELECTRIC SIGMA SERIES : 50~100W
	MITSUBISHI ELECTRIC HC-MF SERIES : 50~100W
	SANYO ELECTRIC P3 SERIES : 50~100W

Dimensions of parallel motor mounting Type E□



Dimensions of parallel motor mounting Type F□



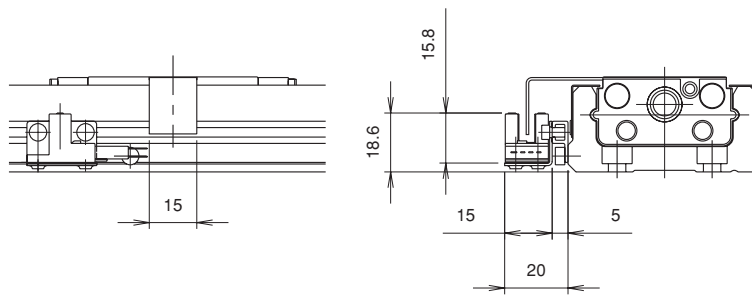
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE30	**	*	***	*
	04: 4mm 05: 5mm 10: 10mm	A: With 1 long block B: With 2 long blocks	150, 200, 300, 400, 500, 600, 700, 750	W, U

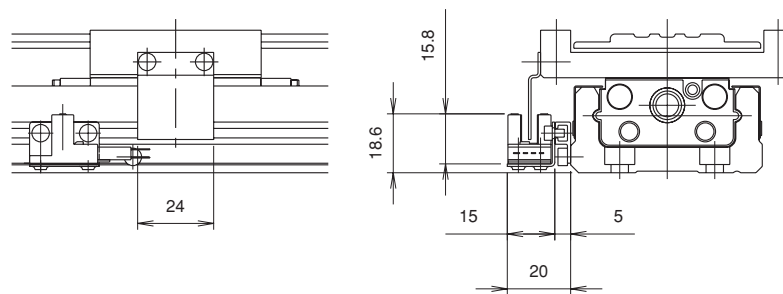
● SENSOR

Symbol C (NPN) / P (PNP), M / Y (PNP): Photo-microsensor (OMRON, SUNX)

Without dustproof cover



With dustproof cover



SE series

Motor bracket configuration	Type of cover	Sensor
**	*	*
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor

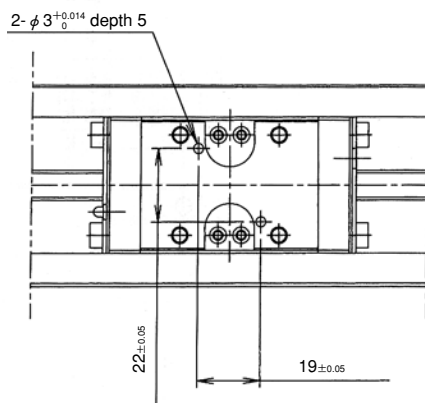
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
**
PS: Dowel pin hole provided No symbol: Not provided

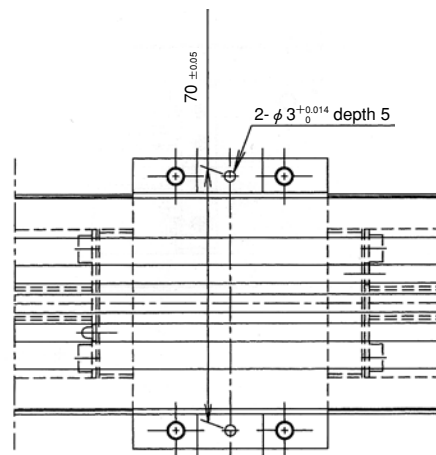
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For actuators with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without dustproof cover



Long block with dustproof cover

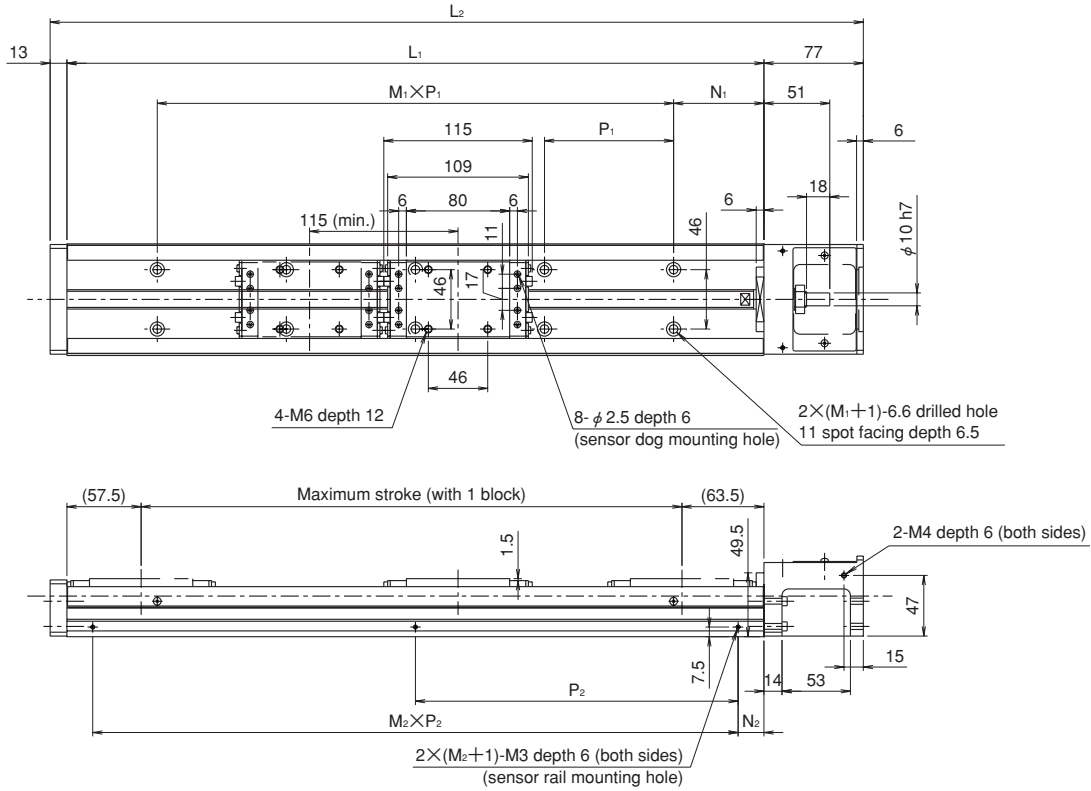


Model No.

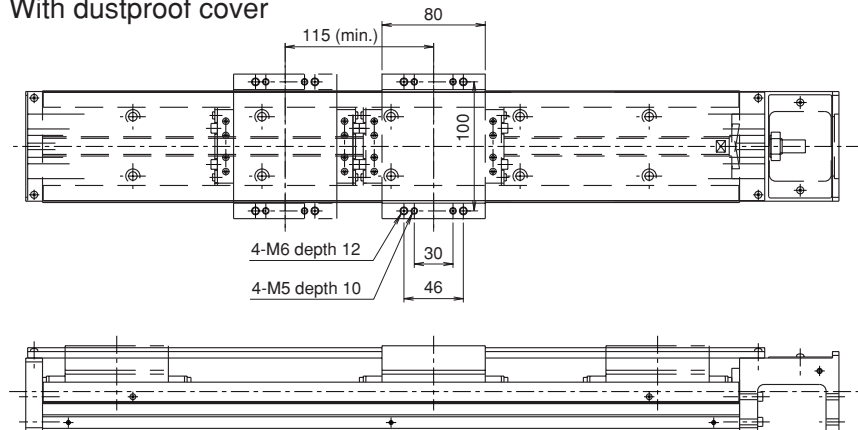
Model No.	Lead	Slide block	Guide rail length	Performance grade
SE45	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	540, 640, 740, 840, 940	W, U

LONG BLOCK CONFIGURATIONS

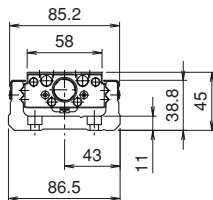
With 1 long block: A (With 2 long blocks: B)



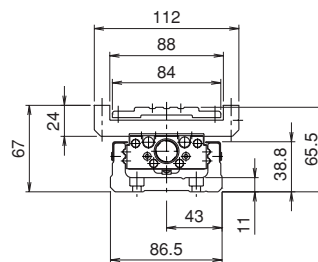
With dustproof cover



Without cover



With dustproof cover



SE series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Long block	
						A: 1 block	B: 2 blocks
540	630	70	4×100	20	2×250	419	304
640	730		5×100		2×300	519	404
740	830		6×100		2×350	619	504
840	930		7×100		2×400	719	604
940	1030		8×100		3×300	819	704

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)				Slide block	
	Lead			Without cover		With cover		Without cover	With cover
	5mm	10mm	20mm	A	B	A	B		
540	260	520	1040	8.5	9.4	9.6	10.9	0.86	1.19
640				9.8	10.7	11	12.2		
740				11	11.9	12.4	13.6		
840				12.3	13.2	13.8	15		
940	200	410	830	13.5	14.4	15.1	16.4		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

(Note 2) For long rail configurations, please consult KURODA.

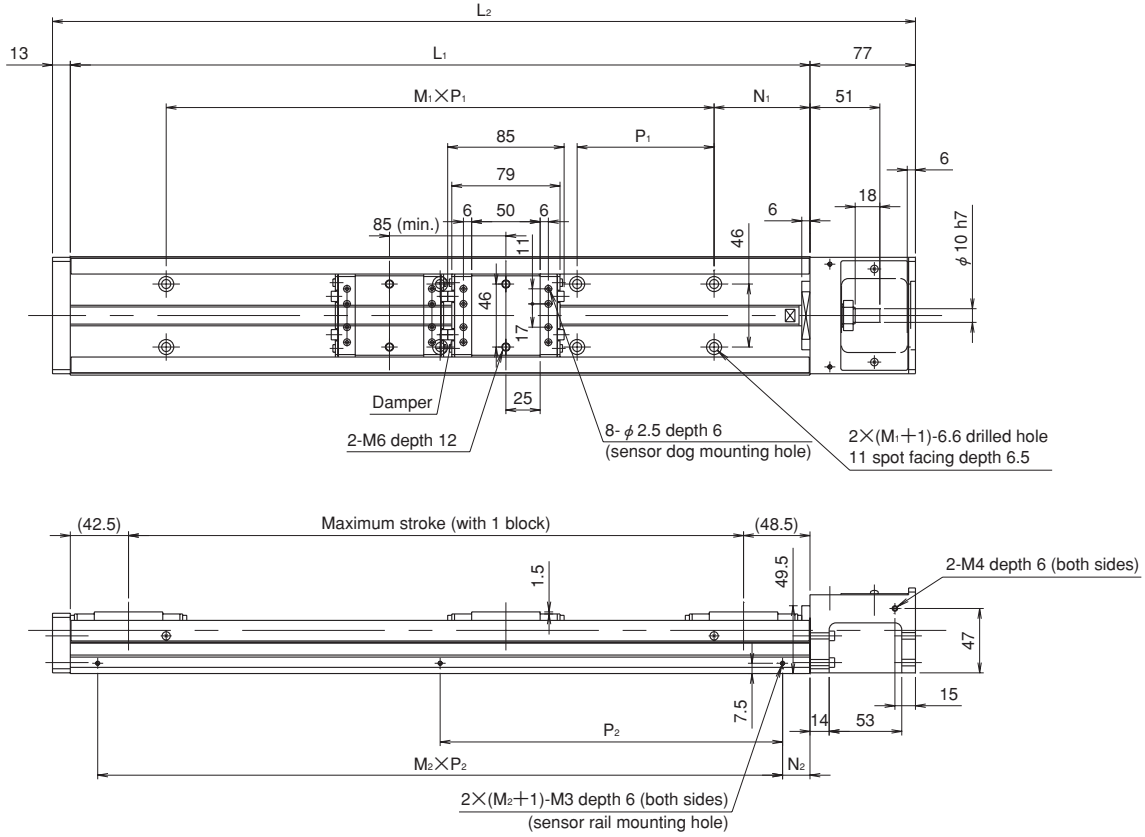
Model No.

Model No.	Lead	Slide block
SE45	* *	*
	05: 5mm	A: With 1 long block
	10: 10mm	B: With 2 long blocks
	20: 20mm	C: With 1 short block D: With 2 short blocks

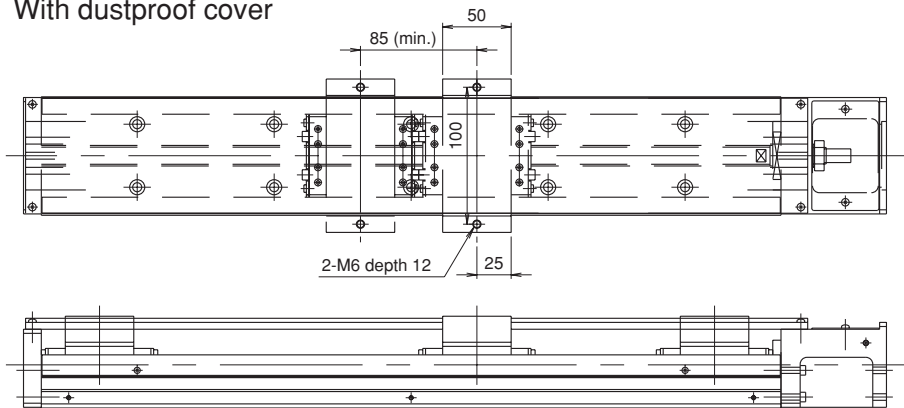
Guide rail length	Performance grade
* * *	*
540, 640, 740, 840, 940	W, U

● SHORT BLOCK CONFIGURATIONS

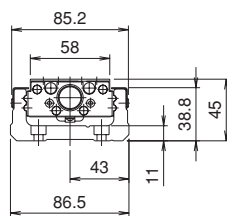
With 1 short block: C (With 2 short blocks: D)



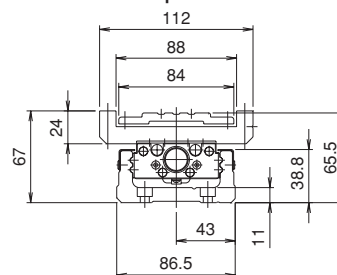
With dustproof cover



Without cover



With dustproof cover



SE series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease	Dowel pin hole
**	*	*	*	*	**
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease	PS: Dowel pin hole provided No symbol: Not provided

● SHORT BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke	
						Short block	
						C: 1 block	D: 2 blocks
540	630	70	4×100	20	2×250	449	364
640	730		5×100		2×300	549	464
740	830		6×100		2×350	649	564
840	930		7×100		2×400	749	664
940	1030		8×100		3×300	849	764

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)				Slide block	
	Lead			Without cover		With cover		Without cover	With cover
	5mm	10mm	20mm	C	D	C	D		
540	260	520	1040	8.2	8.8	9.2	10	0.58	0.79
640				9.5	10.1	10.6	11.4		
740				10.7	11.3	12	12.8		
840				12	12.6	13.3	14.1		
940	200	410	830	13.2	13.8	14.7	15.5		

(Note 1) The mass indicated in the columns "Without cover" and "With cover" in the above table includes the mass of slide block.

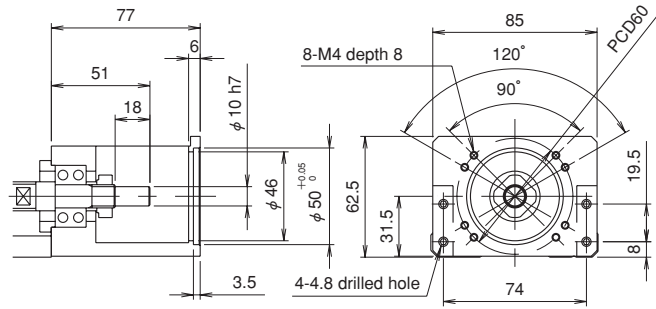
(Note 2) For long rail configurations, please consult KURODA.

Model No.

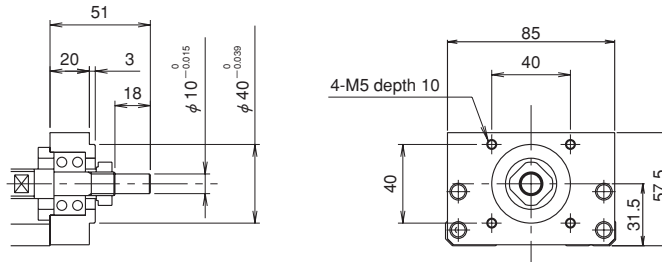
Model No.	Lead	Slide block	Guide rail length	Performance grade
SE45	**	*	** *	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	540, 640, 740, 840, 940	W, U

MOTOR BRACKET CONFIGURATIONS

Motor bracket configuration: A0



Motor bracket configuration: RN



Mass of the RN configuration is 0.26 kg less than the values shown in the tables on pages 79 and 81.

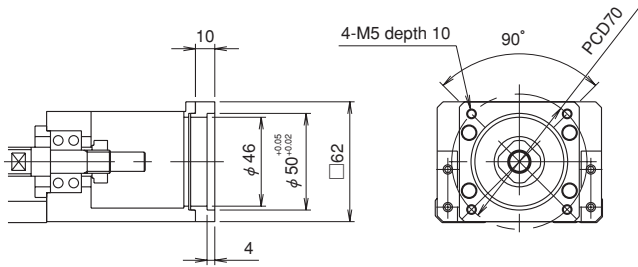
Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

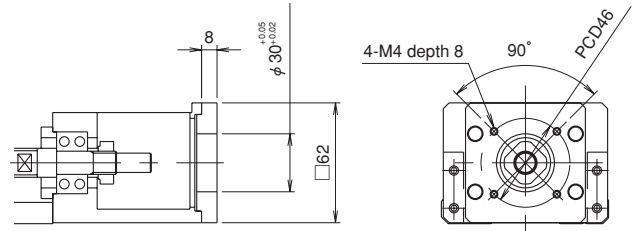
Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

● MOTOR BRACKET CONFIGURATIONS (INTERMEDIATE FLANGE)

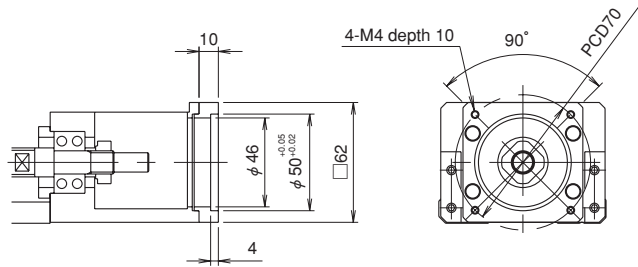
Motor bracket configuration: A1 (mass: 53g)



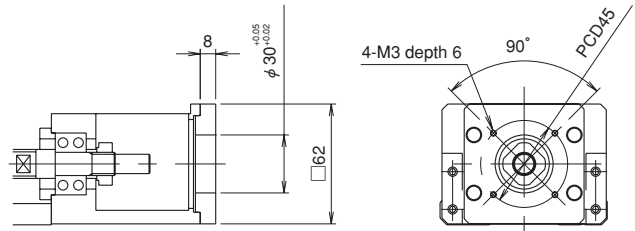
Motor bracket configuration: A4 (mass: 73g)



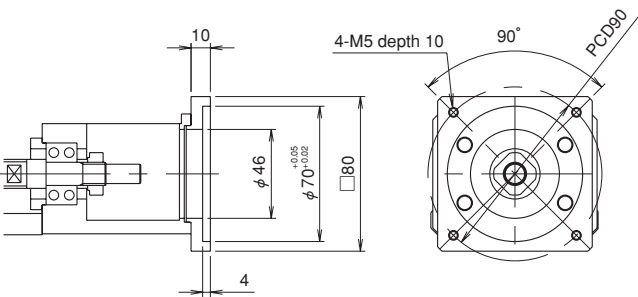
Motor bracket configuration: A2 (mass: 53g)



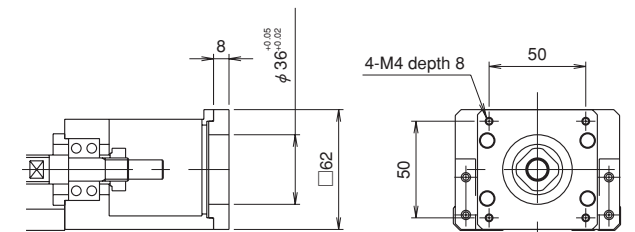
Motor bracket configuration: A5 (mass: 73g)



Motor bracket configuration: A3 (mass: 103g)



Motor bracket configuration: A6 (mass: 64g)



SE series

Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE45	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks	540, 640, 740, 840, 940	W, U

● MOTOR BRACKET CONFIGURATIONS AND MOTOR OPTION

Motor type	Motor option			Motor bracket configuration	Recommended coupling	
	Maker	Model No.	Output (W)			
AC Servo motor	PANASONIC	MSMA3AZ	30	A5	SFC-020DA2 (MIKI PULLEY)	
		MSMA5AZ	50			
		MSMA01	100			
		MSMA02	200			
		MSMA04	400			
	MITSUBISHI ELECTRIC	HC-KFS (MFS,PQ)053	50	A4	SFC-020DA2 (MIKI PULLEY)	
		HC-KFS (MFS,PQ)13	100	A1		
		HC-KFS (MFS,PQ)23	200			
		HC-KFS (MFS,PQ)43	400			
		HA-FF053	50	A0		SFC-020DA2 (MIKI PULLEY)
		HA-FF13	100			
		HA-FF23	200			
		HA-FF33	300			
	YASKAWA ELECTRIC	SGMAH (SGML)-A3	30	A4	SFC-020DA2 (MIKI PULLEY)	
		SGMAH (SGML)-A5	50			
		SGMAH (SGML)-01	100			
		SGMAH (SGML)-02	200			
		SGML-03	300			
		SGMAH (SGML)-04	400			
	SANYO ELECTRIC	P30B04003	30	A4	SFC-020DA2 (MIKI PULLEY)	
		P30B04005	50			
		P30B04010	100			
		P30B06020	200			
		P30B06040	400			
		P50B05005	50			A0
		P50B05010	100			
		P50B07020	200			
		P50B07030	300			
		P50B07040	400			A3
	HITACHI INDUSTRIAL EQUIPMENT SYSTEMS	ADMA-R5	50	A4	SFC-020DA2 (MIKI PULLEY)	
		ADMA-01	100			
		ADMA-02	200			
ADMA-04		400				
TAMAGAWA SEIKI	TS4601	30	A4	SFC-020DA2 (MIKI PULLEY)		
	TS4602	50				
	TS4603	100				
	TS4606	100				
	TS4607	200				
	TS4609	400				
FANUC	β M0.2	50	A4	SFC-020DA2 (MIKI PULLEY)		
	β M0.3	100				
Stepping motor	ORIENTAL MOTOR	UPK (RK)56,AS6	—	A6		

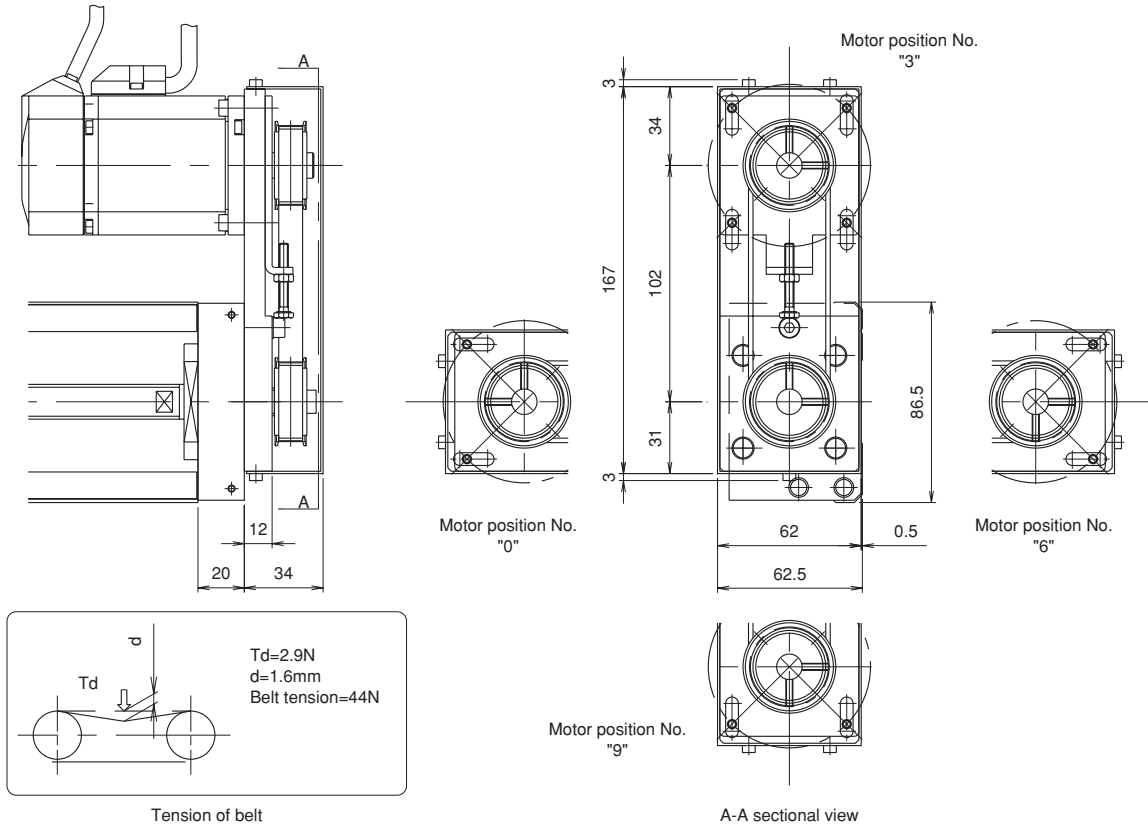
- For motors other than above-mentioned, consult KURODA.
- When selecting a rigid type coupling for connecting a motor, consult KURODA.
- For detailed specifications for above-mentioned motors and couplings, refer to catalogs or websites provided by the makers.

Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

● PARALLEL MOTOR MOUNTING



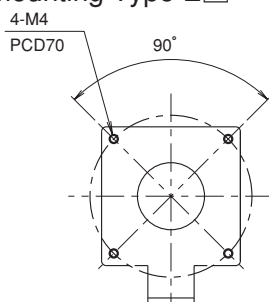
- The above figure shows actuator with MSMA02 (PANASONIC): E□.
- Pulley unit position can be adjusted at 90 degree each.
- Fill motor position No. in □.

If the pulley cover may not be removable due to restrictions arising from direction of the unit, consult KURODA for modifying positions of the pulley-cover fixing bolts (3 M3 cross recessed flat head machine screws).

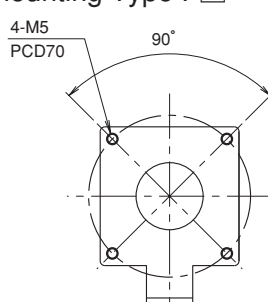
- Motor parallel mounting can be equipped with dustproof cover and sensor
- Although tension plate is attached inside the cover with standard specifications, it can also be attached to outside the cover. Consult KURODA for such modification.
- Tension plate position can be built in pulley cover.
- The mass is 0.7kg larger than the values shown in tables on pages 79 and 81.
- Inertia moment is $1.24 \times 10^{-5} \text{kg} \cdot \text{m}^2$ larger than the value shown in table on page 55.

Mark	Motor option
E□	PANASONIC MINAS SERIES : 200, 400W
F□	YASKAWA ELECTRIC SIGMA SERIES : 200, 400W
	MITSUBISHI ELECTRIC HC-MF SERIES : 200, 400W
G□	SANYO ELECTRIC P3 SERIES : 200, 400W
	ORIENTAL MOTOR STEPPING MOTOR □60 SERIES

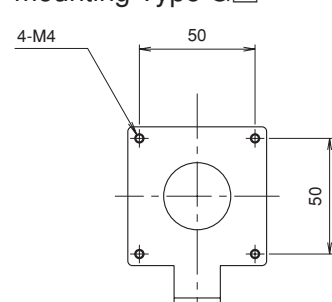
Dimensions of parallel motor mounting Type E□



Dimensions of parallel motor mounting Type F□



Dimensions of parallel motor mounting Type G□



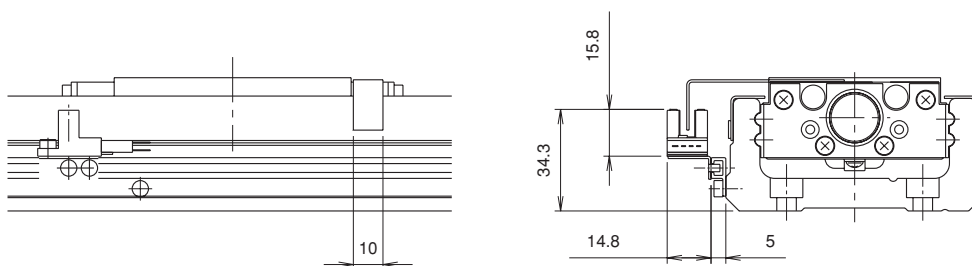
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SE45	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block B: With 2 long blocks C: With 1 short block D: With 2 short blocks		

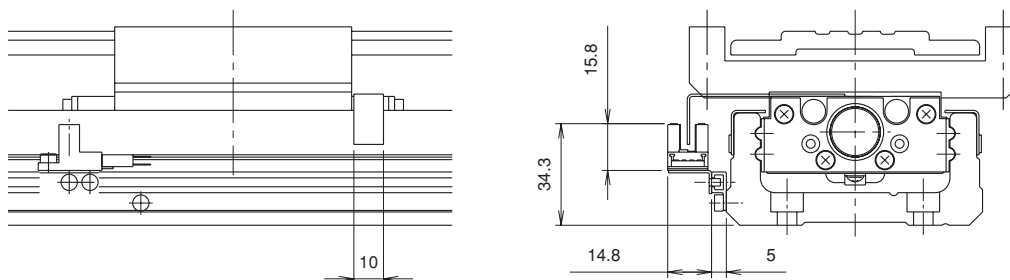
● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, SUNX)

Without dustproof cover



With dustproof cover



Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Without cover C: With dustproof cover	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

Dowel pin hole
* *
PS: Dowel pin hole provided No symbol: Not provided

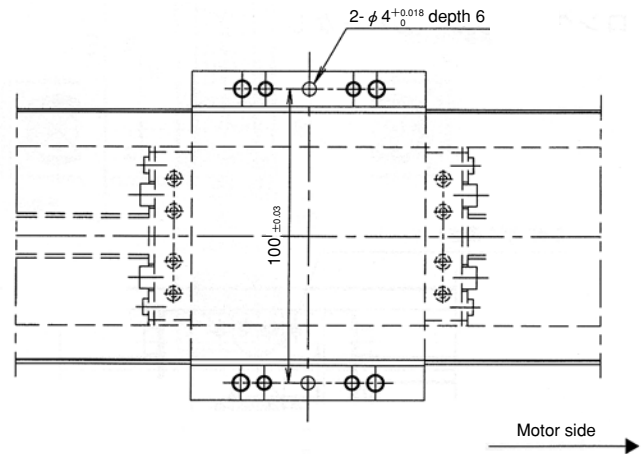
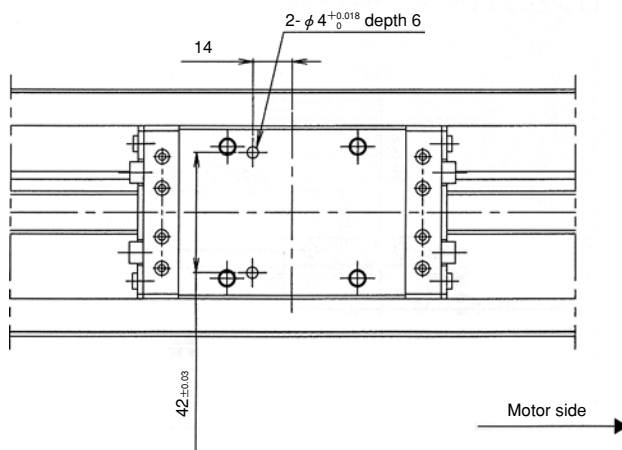
● DOWEL PIN HOLE

Dowel pin holes can be equipped on the slide blocks or the sub tables by adding the "PS" (Option) to the end of the model number. For an actuator with 2 blocks, they are on both driving-side block and driven-side block. Please note that dowel pins are not equipped.

Long block without cover

Long block with dustproof cover

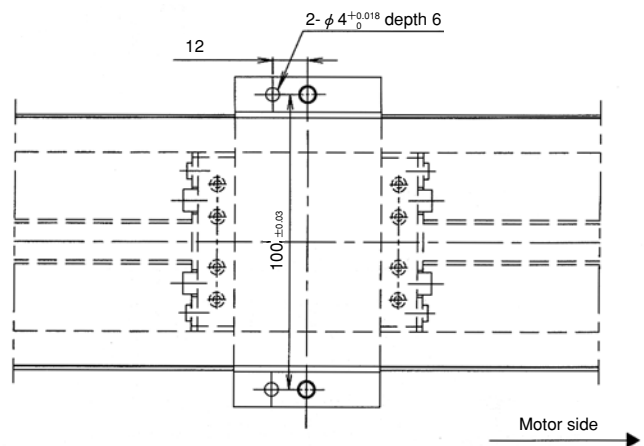
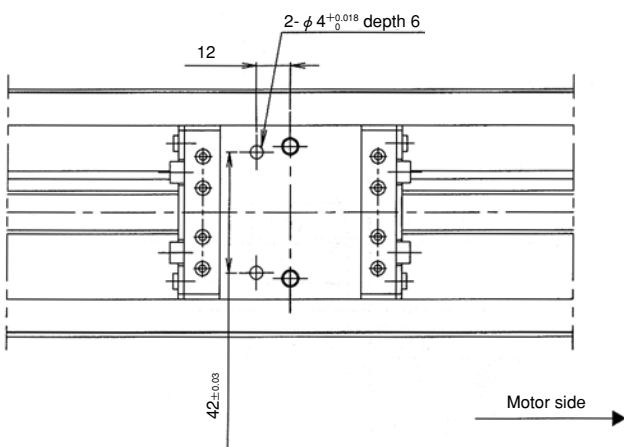
For actuators with 2 blocks, the holes are on both blocks.



Short block without cover

Short block with dustproof cover

For actuators with 2 blocks, the holes are on both blocks.



CONTENTS

FULL-COVER TYPE BALLSCREW ACTUATORS/SC SERIES

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(Note) For motor bracket configurations and parallel motor mounting, refer to pages 82 to 85 in SE series section.	
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VARIATIONS

Model No.	SC23	SC30	SC45
Performance grade	U: Repeated positioning accuracy $\pm 5 \mu\text{m}^*$ (Ball screw - lead accuracy C7 grade, axial clearance 0mm) W: Repeated positioning accuracy $\pm 10 \mu\text{m}^*$ (Ball screw - lead accuracy C7 grade, axial clearance 0.02mm or less)		
Screw shaft dia. (mm)	8	10	15
lead (mm)	2	◎	●
	4	●	◎
	5	◎	◎
	8	●	
	10		◎
	20		◎



◎: In-stock items ●: Manufactured by order

(Note 1) Asterisked (*) items may be different from the values shown above, depending on applied options and usage.

HOW TO INTERPRET MODEL NO.

Model	Lead	Slide block	Guide rail length (Note 4)	Performance grade
SC**	**	*	***	*
SC23	2, 5	A: With 1 long block	150, 200, 250, 300	U grade • Repeated positioning accuracy $\pm 5 \mu\text{m}$ • Lead accuracy C7 grade or equivalent • Axial clearance 0mm
SC30	4, 5, 10		150, 200, 300, 400, 500, 600, 700, 750	W grade • Repeated positioning accuracy $\pm 10 \mu\text{m}$ • Lead accuracy C7 grade or equivalent • Axial clearance 0.02mm or less
SC45	5, 10, 20		540, 640, 740, 840, 940	

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease
**	*	*	*	*
A0, A1, A2, A3, A5, A6, A7	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment (Note1) C: Anti corrosive black coating	N: Standard grease (Note 2) C: Dust preventive grease (KURODA C-grease)
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□		N: Without sensor M, Y, C, P: Photo-microsensor		
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□		N: Without sensor M, Y, C, P: Photo-microsensor		

(Note 1) With standard specifications of surface treatment (Symbol N), only guide rails are treated with black coating.

(Note 2) With standard grease (Symbol: N), Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) is contained in slide block and ball screw components.

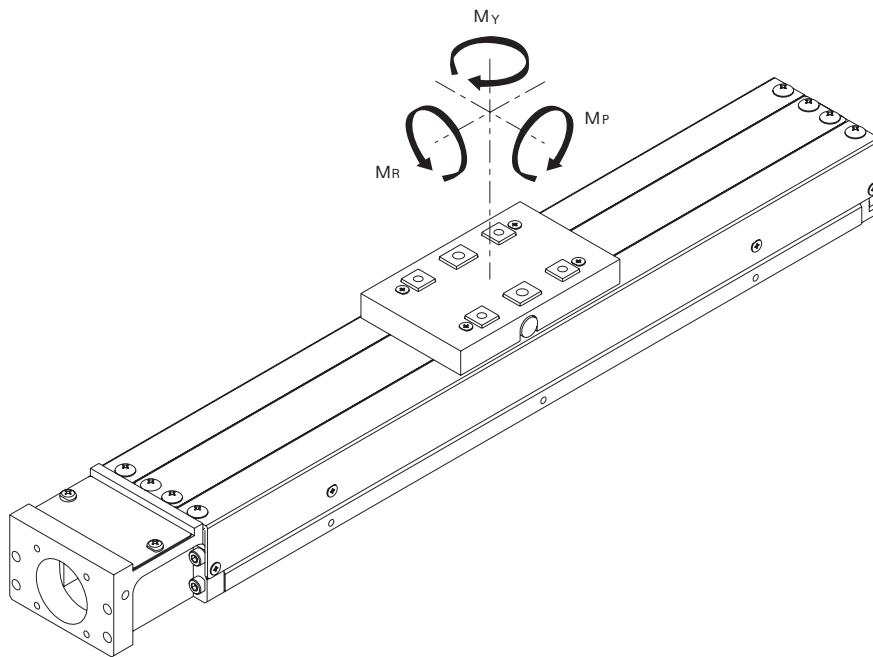
(Note 3) For specifications of guide rail with long rail or intermediate stroke of non-standard length, consult KURODA.

SPECIFICATIONS

Model no.			SC2302		SC2305		SC3004		SC3005		SC3010		SC4505		SC4510		SC4520	
Performance grade			W	U	W	U	W	U	W	U	W	U	W	U	W	U	W	U
Guide	Radial clearance		μm	-3~0				-3~0				-5~0						
	Long block	Basic dynamic load rating	C	4.3				7				27						
		Basic static load rating	C_0	7.0				11.8				45.0						
		Static permissible moment	M_P	N·m	29				43				68					
			M_Y		51				107				194					
M_R	61				84				250									
Ball screw	Shaft diameter		mm	8				10				15						
	Lead		mm	2	5		4	5	10		5	10	20					
	Basic dynamic load rating	C_a	kN	1.8	1.9		3.0	3.0	2.0		5.1	5.1	3.1					
	Basic static load rating	C_{0a}	kN	3.2	3.1		5.3	5.3	3.2		10.5	10.5	6.6					
	Precision grade			C7 grade or equivalent				C7 grade or equivalent				C7 grade or equivalent						
	Axial clearance		mm	~0.02	0	~0.02	0	~0.02	0	~0.02	0	~0.02	0	~0.02	0	~0.02	0	~0.02
Fixed side bearing	Model No. of bearing			AC6-16DF or equivalent				708DFP5 or equivalent				5201A or equivalent						
	Basic dynamic load rating	C_b	kN	1.79				4.40				5.90						
	Basic static load rating	C_{0b}	kN	1.76				4.36				3.20						

(Note 1) Static permissible moment shows rigidity value based on dimensions and material of table.

DIRECTION OF MOMENT



ACCURACY

Model No.	Guide rail length (mm)	Repeated positioning accuracy (μm)		Positioning accuracy (μm)		Travelling parallelism B (μm)		Backlash (μm)		Starting torque ($\text{N}\cdot\text{m}$)	
		W	U	W	U	W	U	W	U	W	U
SC23	150	± 10	± 5	70		15		20	5	0.03	0.06
	200			75							
	250			85							
	300			90							
SC30	150	± 10	± 5	70		15		20	5	0.07	0.15
	200			80							
	300			90							
	400			95							
	500			100		25					
	600			110							
	700			120							
	750			130							
SC45	540	± 10	± 5	110		40		20	5	0.1	0.2
	640			120							
	740			130							
	840			150		50					
	940			170							

(Note 1) Measurement is to be performed with KURODA's specified motor mounted.

(Note 2) Above starting torque value is applied when the standard grease is used. The value may change depending on the properties of the grease.

INERTIA

Inertia for slide block and ball screw of ballscrew actuator is shown in the following table.

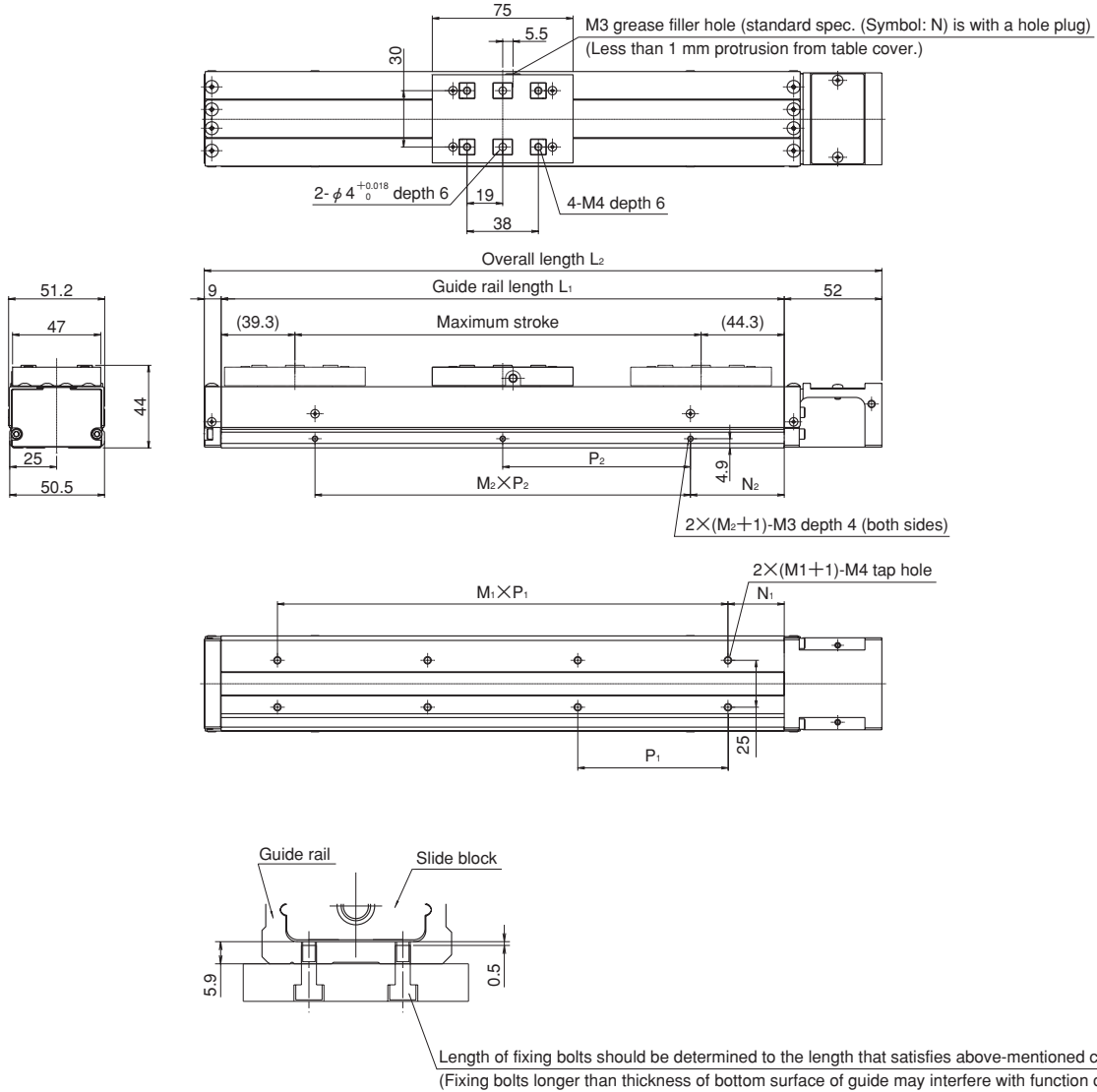
(Unit: $\times 10^{-5} \text{kg} \cdot \text{m}^2$)

Model No.	Guide rail length (mm)	Full-cover type
		Long block A: 1 block
SE2302	150	0.0616
	200	0.0773
	250	0.0930
	300	0.1090
SE2305	150	0.0756
	200	0.0913
	250	0.1070
	300	0.1230
SE3004	150	0.165
	200	0.204
	300	0.280
	400	0.357
	500	0.434
	600	0.510
	700	0.587
SE3005	150	0.176
	200	0.214
	300	0.291
	400	0.367
	500	0.444
	600	0.521
	700	0.597
SE3010	150	0.261
	200	0.299
	300	0.376
	400	0.453
	500	0.529
	600	0.606
	700	0.683
	750	0.721
SE4505	540	2.43
	640	2.81
	740	3.20
	840	3.59
	940	3.98
SE4510	540	2.68
	640	3.07
	740	3.46
	840	3.84
	940	4.23
SE4520	540	3.69
	640	4.08
	740	4.47
	840	4.86
	940	5.24

Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SC23	**	*	***	*
	02: 2mm 05: 5mm	A: With 1 long block	150, 200, 250, 300	W, U

● FULL-COVER TYPE LONG BLOCK CONFIGURATIONS



SC series

Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease
**	*	*	*	*
A0, A1, A2, A3, A5, A6, A7	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor S: Photo-microsensor K, E: Proximity sensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● FULL-COVER TYPE LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke
						Long block
						A: 1 block
150	211	35	1×80	25	1×100	66
200	261	20	2×80	50		116
250	311	45		3×80	25	2×100
300	361	30	50		216	

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)		Mass (kg)	
	Lead		Full-cover type	Mass of table (slide block + table + table cover parts)
	1mm	2mm	A: With 1 long block	
150	200	490	1.20	0.25
200			1.41	
250			1.63	
300			1.84	

(Note 1) Mass of full-cover type actuators in the above table includes mass of table.

(Note 2) For long rail configurations, please consult KURODA.

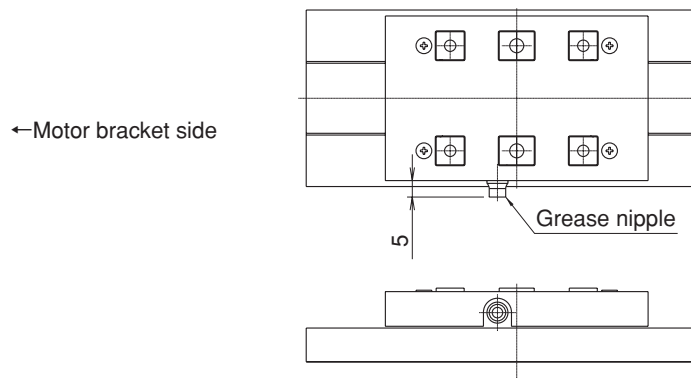
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SC23	**	*	***	*
	02: 2mm 05: 5mm	A: With 1 long block	150, 200, 250, 300	W, U

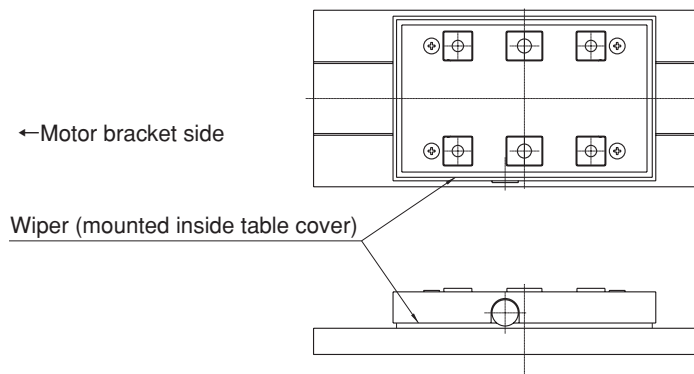
● COVER CONFIGURATION

The below-mentioned configurations with grease nipple and/or wiper are available for full-covered series. Standard specification (Symbol: N) has a plug equipped with grease filler hole.

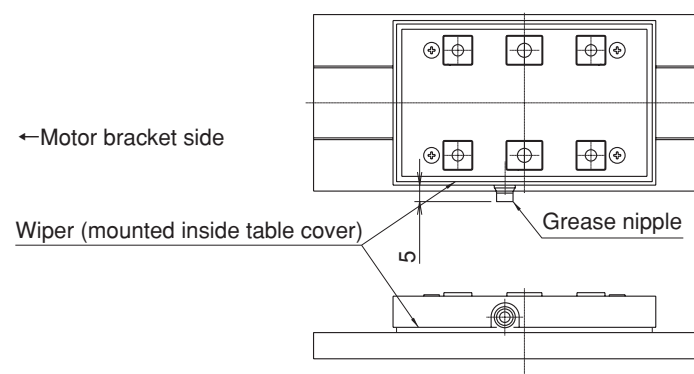
Full-cover type with grease nipple (Symbol: G)



Full-cover type with wiper (Symbol: S)



Full-cover type with grease nipple and wiper (Symbol: D)

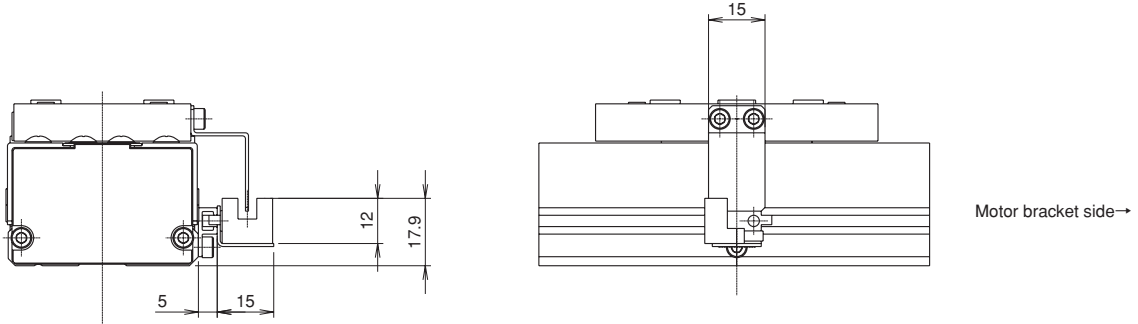


Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A5, A6, A7	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor S: Photo-microsensor K, E: Proximity sensor

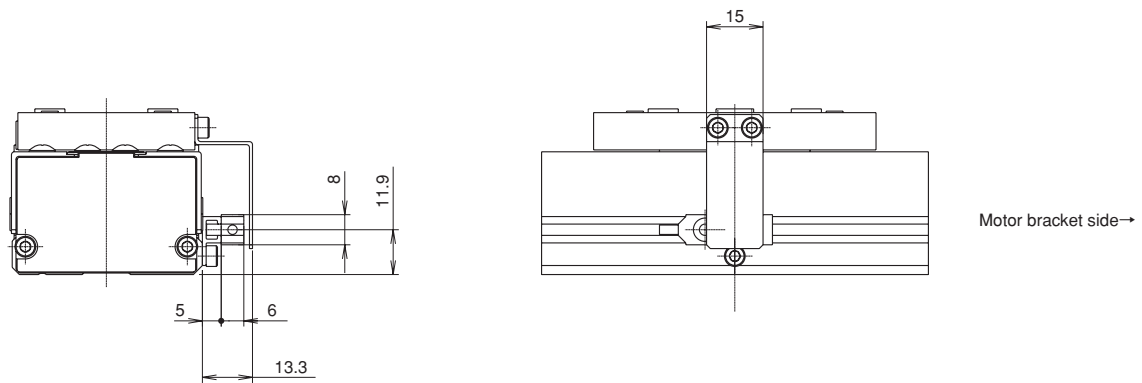
Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● SENSOR

Symbol S (NPN): Photo-microsensor (SUNX)



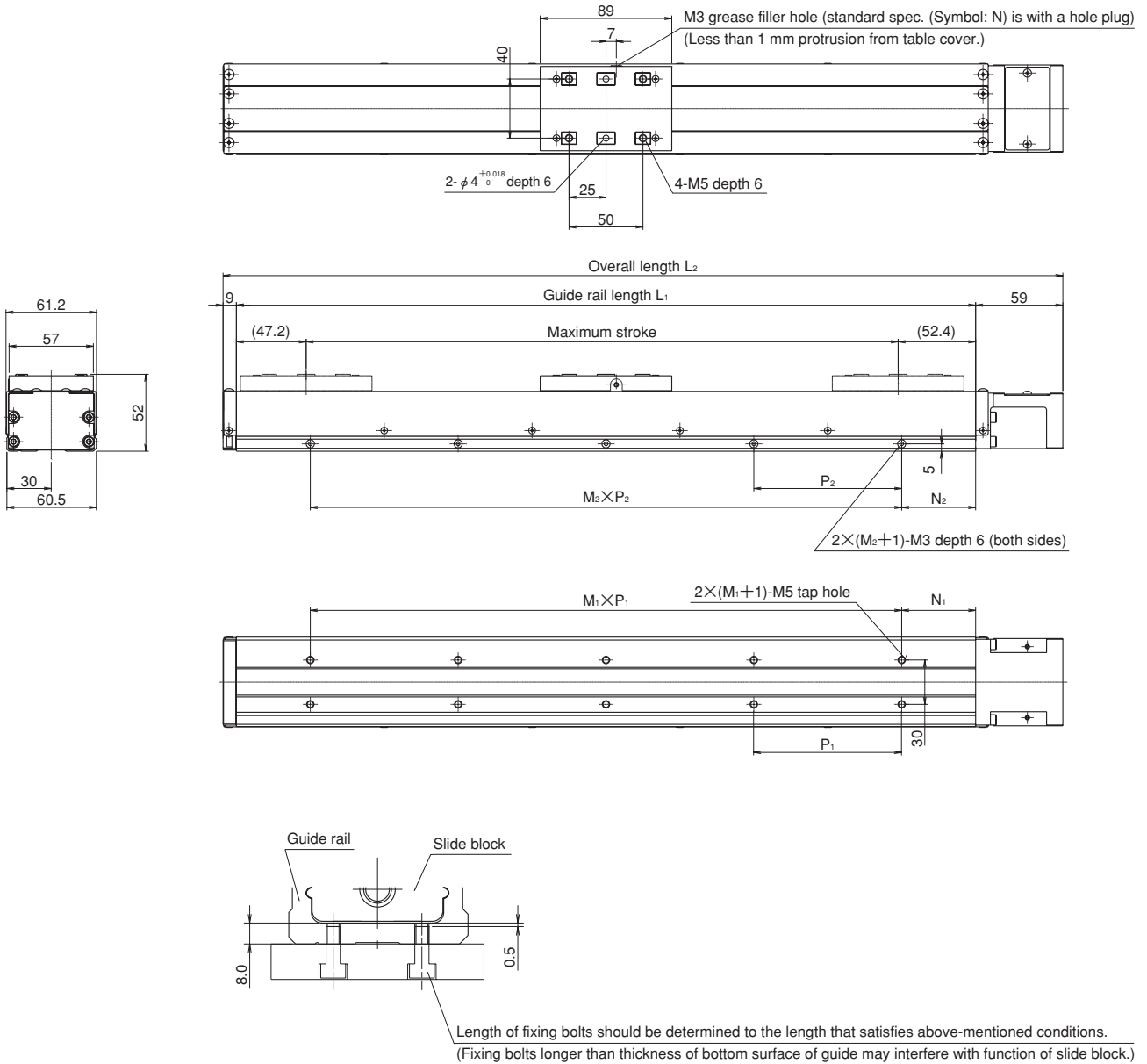
Symbol K (NPN) / E (PNP): Proximity sensor (YAMATAKE)



Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SC30	**	*	***	*
	04: 4mm 05: 5mm 10: 10mm	A: With 1 long block	150, 200, 300, 400, 500, 600, 700, 750	W, U

● FULL-COVER TYPE LONG BLOCK CONFIGURATIONS



Motor bracket configuration	Type of cover	Sensor	Surface treatment	Grease
* *	*	*	*	*
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor M, Y, C, P: Photo-microsensor	N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● FULL-COVER TYPE LONG BLOCK DIMENSIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke
						Long block
						A: 1 block
150	218	25	1×100	25	1×100	50
200	268	50		50		100
300	368		2×100		200	
400	468		3×100		300	
500	568		4×100		400	
600	668		5×100		500	
700	768	6×100	600			
750	818	25	7×100	25	7×100	650

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)	
	Lead			Full-cover type	Mass of table (slide block + table + table cover parts)
	4mm	5mm	10mm	A: With 1 long block	
150	320	400	810	1.9	0.43
200				2.2	
300				2.9	
400				3.5	
500				4.2	
600	240	300	600	4.9	
700	170	210	430	5.5	
750	—	—	380	5.8	

(Note 1) Guide rail length of 750 mm is available only for SE3010.

(Note 2) Mass of full-cover type actuators in the above table includes mass of table.

(Note 3) For long rail configurations, please consult KURODA.

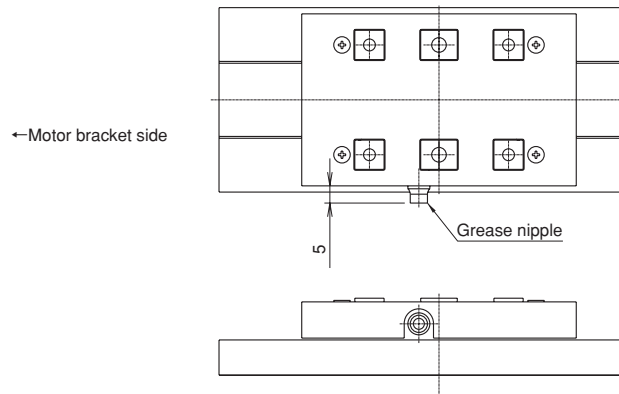
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SC30	**	*	***	*
	04: 4mm 05: 5mm 10: 10mm	A: With 1 long block		150, 200, 300, 400, 500, 600, 700, 750

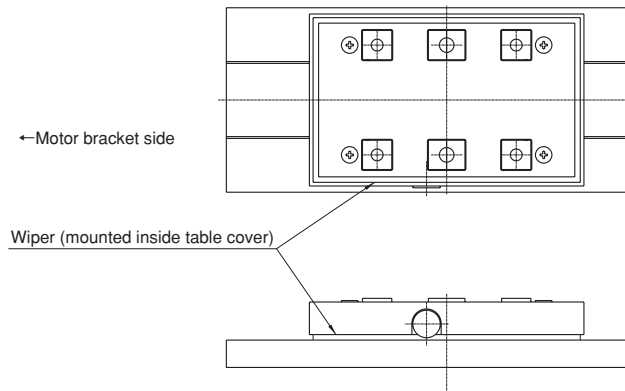
COVER CONFIGURATION

The below-mentioned configurations with grease nipple and/or wiper are available for full-covered series. Standard specification (Symbol: N) has a plug equipped with grease filler hole.

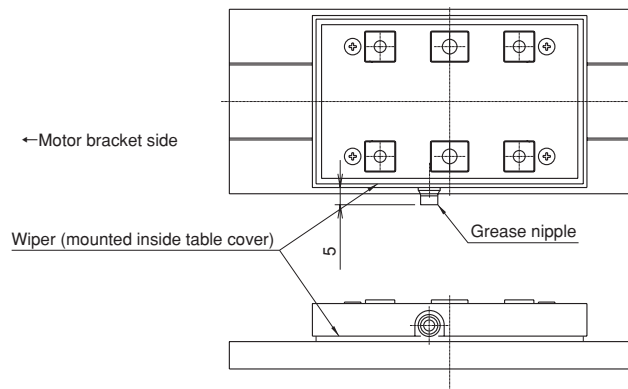
Full-cover type with grease nipple (Symbol: G)



Full-cover type with wiper (Symbol: S)



Full-cover type with grease nipple and wiper (Symbol: D)



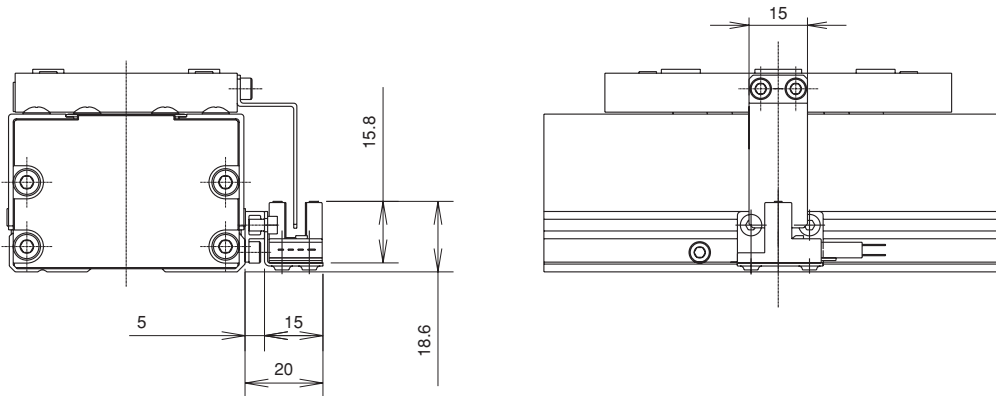
Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, B1, RN, E□, F□	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP):

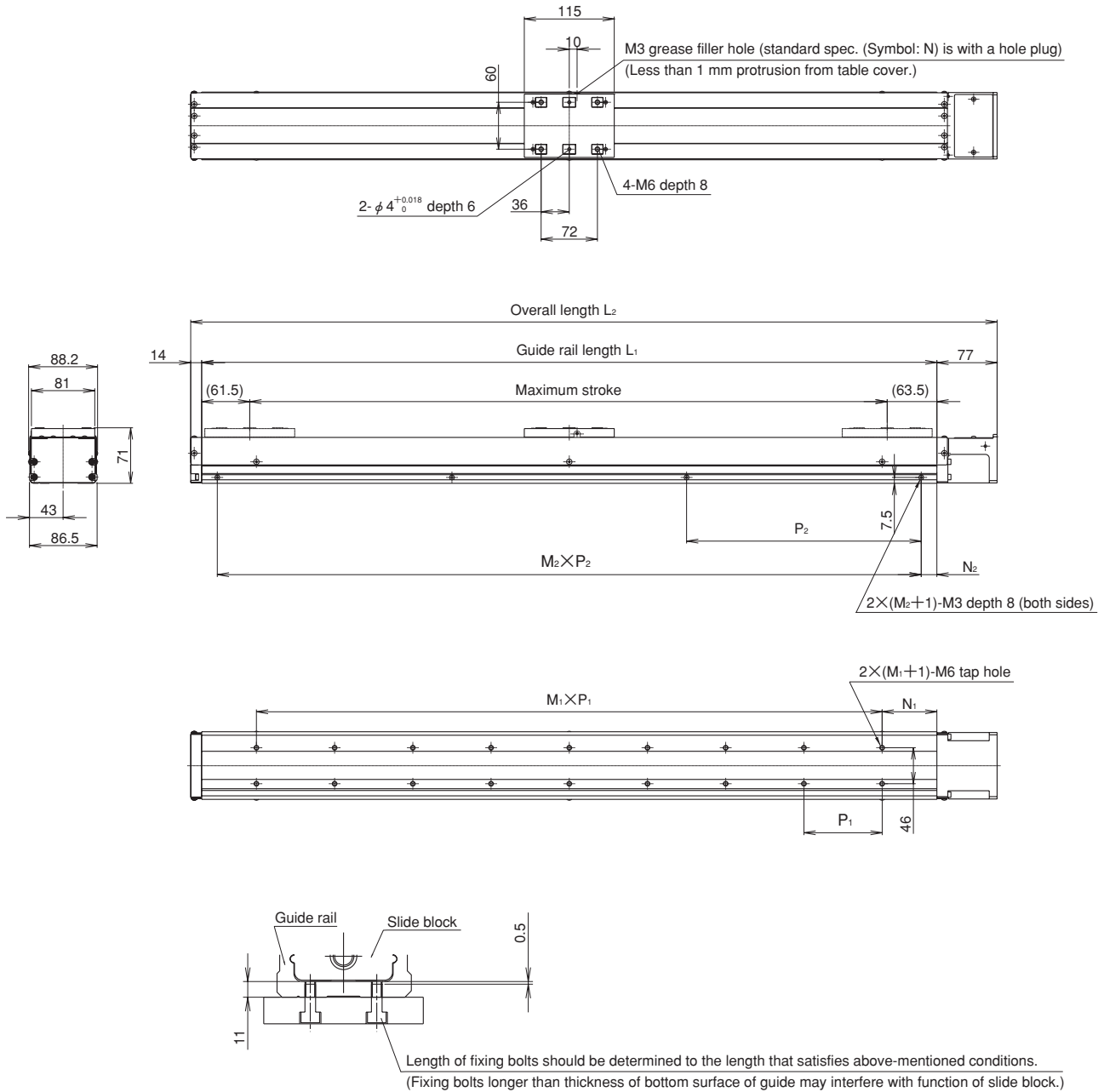
Photo-microsensor (OMRON, SUNX)



Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SC45	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block	540, 640, 740, 840, 940	W, U

● FULL-COVER TYPE LONG BLOCK CONFIGURATIONS



SC series

Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● FULL-COVER TYPE LONG BLOCK CONFIGURATIONS

(Unit: mm)

Guide rail length L_1	Overall length L_2	N_1	$M_1 \times P_1$	N_2	$M_2 \times P_2$	Maximum stroke
						Long block
						1 block
540	631	70	4×100	20	2×250	415
640	731		5×100		2×300	515
740	831		6×100		2×350	615
840	931		7×100		2×400	715
940	1031		8×100		3×300	815

● PERMISSIBLE SPEED / MASS

Guide rail length L_1 (mm)	Permissible speed (mm/s)			Mass (kg)	
	Lead			Full-cover type	Mass of table (slide block + table + table cover parts)
	5mm	10mm	20mm	A: With 1 long block	
540	260	520	1040	9.2	1.27
640				10.5	
740				11.8	
840				13.0	
940	200	410	830	14.3	

(Note 1) Mass of full-cover type actuators in the above table includes mass of table.

(Note 2) For long rail configurations, please consult KURODA.

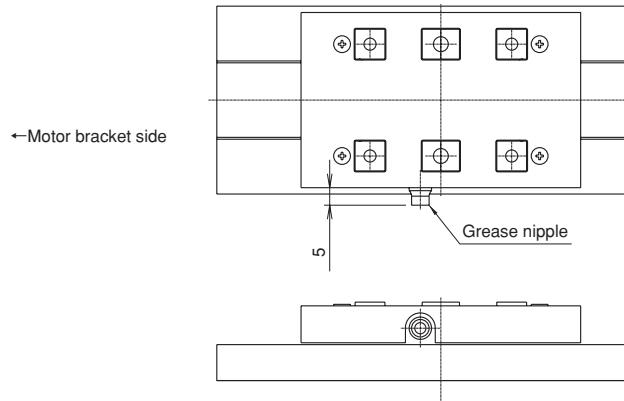
Model No.

Model No.	Lead	Slide block	Guide rail length	Performance grade
SC45	**	*	***	*
	05: 5mm 10: 10mm 20: 20mm	A: With 1 long block		540, 640, 740, 840, 940

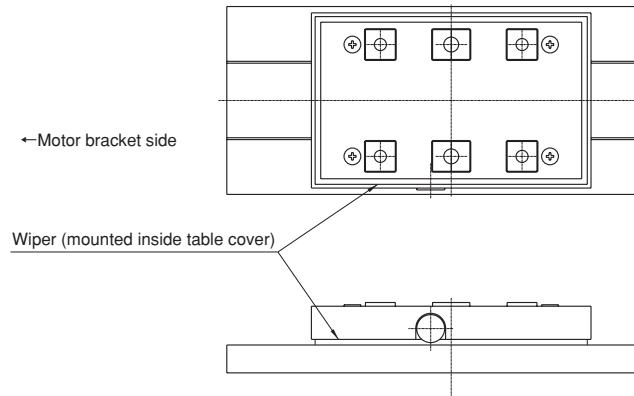
● COVER CONFIGURATION

The below-mentioned configurations with grease nipple and/or wiper are available for full-covered series. Standard specification (Symbol: N) has a plug equipped with grease filler hole.

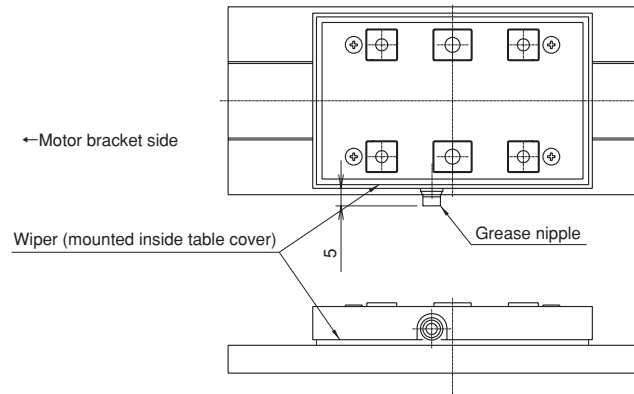
Full-cover type with grease nipple (Symbol: G)



Full-cover type with wiper (Symbol: S)



Full-cover type with grease nipple and wiper (Symbol: D)



SC series

Motor bracket configuration	Type of cover	Sensor
* *	*	*
A0, A1, A2, A3, A4, A5, A6, RN, E□, F□, G□	N: Standard cover G: With grease nipple S: With wiper D: With grease nipple and wiper	N: Without sensor M, Y, C, P: Photo-microsensor

Surface treatment	Grease
*	*
N: Standard treatment L: Anti corrosive black coating	N: Standard grease C: Dust preventive grease

● SENSOR

Symbol C (NPN) / P (PNP), M (NPN) / Y (PNP): Photo-microsensor (OMRON, SUNX)

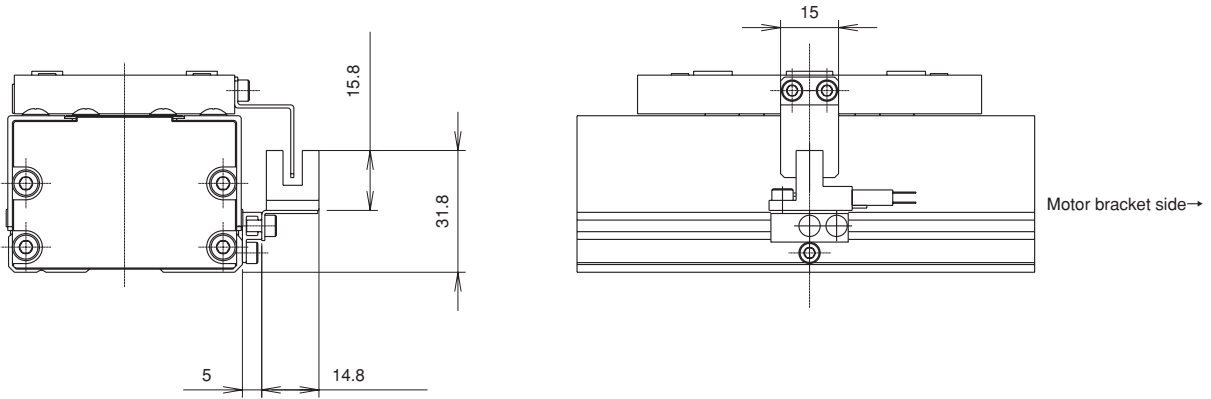


PHOTO-MICROSENSOR/SUNX

● Specifications

Model No.	NPN output type	PM-L24	PM-Y54
	PNP output type	-	PM-Y54P
Sensing range	5mm (fixed)		
Sensing object	0.8X1.8mm opaque object		
Hysteresis	0.05mm or less		
Repeatability	0.03mm or less		
Supply voltage	5 to 24V DC $\pm 10\%$ Ripple P-P 10% or less		
Current consumption	15mA or less		
Output	NPN output type: NPN transistor open collector Maximum sink current : 50mA Applied voltage : 30V DC or less (between output and 0V) Residual voltage : 0.7V or less (at 50mA sink current) 0.4V or less (at 16mA sink current)		
	PNP output type: PNP transistor open collector Maximum sink current : 50mA Applied voltage : 30V DC or less (between output and +V) Residual voltage : 0.7V or less (at 50mA sink current) 0.4V or less (at 16mA sink current)		
Output operation	Incorporated with 2 outputs : Light-ON/Dark-ON		
Response time	Under light received condition : 20 μ s or less Under light shielded condition : 100 μ s or less (Response frequency 1kHz or above)		
Operation indicator	Vermillion LED (lights up under light received condition)		
Ambient illuminance	Fluorescent light : 1000 lx at the light-receiving face		
Ambient temperature	-25 to +55°C : (No dew condensation or icing allowed), Storage: -30 to +80°C:		
Ambient humidity	35 to 85% RH, Storage: 35 to 85% RH		
Voltage withstandability	1000V AC for 1 min. between all supply terminals connected together and enclosure		
Insulation resistance	50M Ω or more with 250V DC megger between all supply terminals connected together and enclosure		
Vibration resistance	10 to 2000Hz frequency, 1.5mm amplitude in X, Y and Z directions for 2 hours each		
Shock resistance	15000mm/s ² acceleration (1500G approx.) in X, Y and Z directions for 3 times each		
Cable	0.09mm ² 4-core cabtyre cable, 1m long		-
Mass	10g approx.		3g approx.
Material	Case	Poly Butylene Terephthalate (PBT)	
	Cover	Polycarbonate	
	Terminal	Solder plated (PM-Y54P only)	

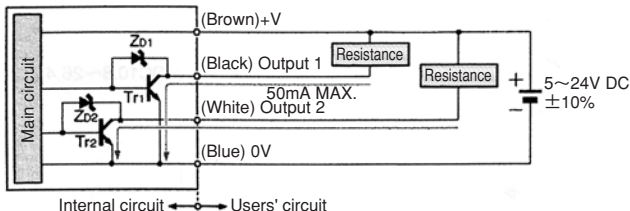
Accessories	Specifications		
	S	M	Y
Sensor Model No.	PM-L24 (NPN) : 3	PM-Y54 (NPN) : 3	PM-Y54P (PNP) : 3
Sensor mounting plate (Note 1)	: 3	: 3	: 3
Sensor rail	: 1	: 1	: 1
Sensor dog (Note 2)	: 1	: 1	: 1
Connector for sensor	-	CN-14 : 3	CN-14 : 3

(Note 1) Sensor mounting plate is applied to SE and SC series.

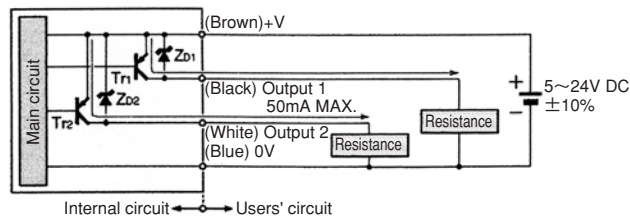
(Note 2) 2 sensor dogs are used for M or Y configuration of SG33□D-150.

● I/O circuit diagram

NPN output type

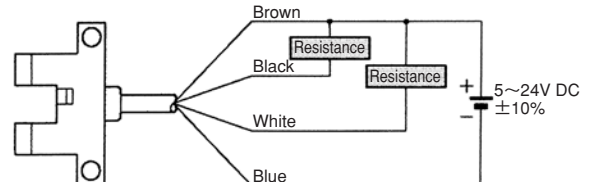


PNP output type

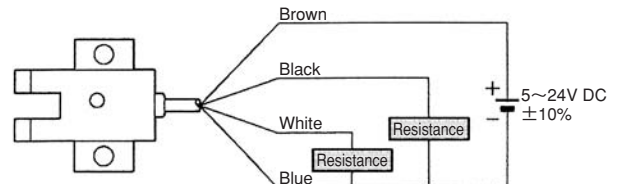


● Wiring diagram

NPN output type



PNP output type



(Note) For detailed information and operating precautions, refer to catalogs and operating instructions supplied by the sensor maker.

PROXIMITY SENSOR/YAMATAKE

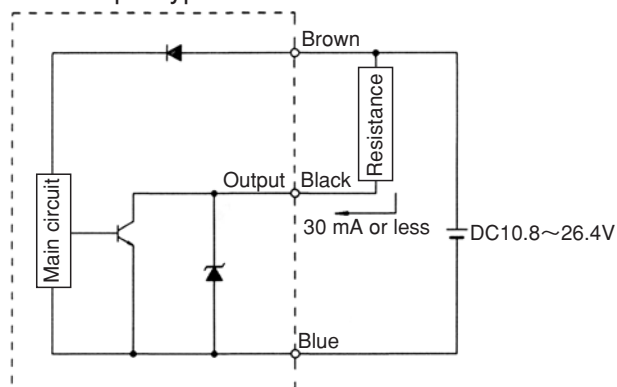
● Specifications

Model No.	NPN output type	APM-D3B1, APM-D3B1F (different-frequency type)
	PNP output type	APM-D3E1, APM-D3E1F (different-frequency type)
Sensing method		High-frequency oscillation type (unshielded type)
Rated supply voltage		DC 12/24V
Rated sensing distance		2.5mm ±15%
Usable sensing distance		0~1.8mm
Sensing object		15×15mm t=1mm Iron
Hysteresis		15% or less in sensing length
Operating voltage range		DC 10.8~26.4V(Ripple 10% or less)
Current consumption		10mA or less
Output type		NPN transistor open collector
		PNP transistor open collector
Operation mode		Normally closed (N.C.)
Control Output	Switching current	30mA or less (resistance load)
	Residual voltage	1V or less (switching current 30mA)
	Output dielectric strength	26.4V
Response frequency		120Hz
Repeatability		0.05mm or less
Temperature characteristics		±15% max. for the range of -10 to +55°C when +25°C is taken as standard temperature in sensing distance
Supply voltage characteristics		±2% max. with 10% voltage fluctuation with rated supply voltage as standard voltage in sensing distance
Operation indicator		Lights up in orange under light received condition
Ambient temperature		-10~+55°C
Ambient temperature at storage		-25~+70°C
Ambient humidity		35~85%RH
Insulation resistance		50MΩ or more (measured by DC 500V insulation ohmmeter)
Voltage withstandability		1000V AC , 50/60Hz for 1 min. between all supply terminals connected together and enclosure
Vibration resistance		10 to 55Hz, 1.5mm amplitude in X, Y, and Z directions for 2 hours each
Shock resistance		500m/s ² in X, Y, and Z directions for 3 times each
Protection		IP67 (IEC529)
Mass		10g approx.
Circuit protection		Surge absorption, reverse connection protection circuit (-S: load short protection)
Connection		Pre-leaded (oil-resistant cord: 2.5 mm O.D., 0.08 mm ² , 3-core, 1 m)
Case material		Polyarylate resin
Tightening torque		0.5N·m (M2.6 screw)

Accessories	Specifications	
	K	E
Sensor Model No.	APM-D3B1 (NPN) : 2 APM-D3B1F (NPN) : 1	APM-D3E1 (PNP) : 2 APM-D3E1F (PNP) : 1
Sensor rail	: 1	: 1
Sensor dog	: 1	: 1

● Wiring diagram

NPN output type



PNP output type

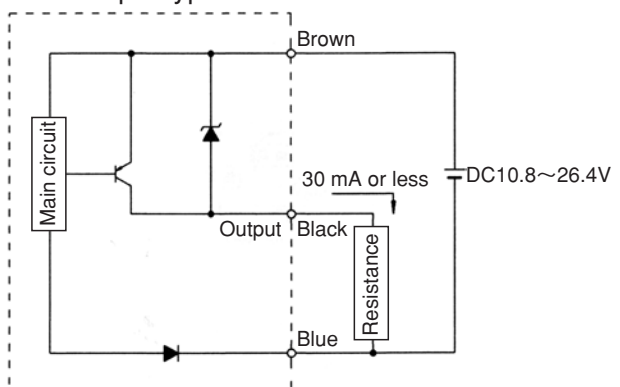


PHOTO-MICROSENSOR/OMRON

● Specifications

Model No.	NPN output type	EE-SX674	EE-SX671
	PNP output type	EE-SX674P	EE-SX671P
Sensing range	5mm (slot width)		
Sensing object	Opaque object 2 x 0.8mm or more		
Hysteresis	0.025mm or less		
Light source (peak emission wavelength)	GaAs IRED (940 nm)		
Operation indicator	Lights up at light-received (Red LED)		
Supply voltage	5 to 24V DC ± 10% Ripple P-P 10% or less		
Current consumption	NPN type: 35mA or less, PNP type: 30mA or less		
Output	NPN output type: NPN transistor open collector Output : 5 to 24V DC 100mA or less Residual voltage : 0.8V or less (at 100mA load current), 0.4V or less (at 40mA load current) OFF-state current 0.5mA or less		
	PNP output type : PNP transistor open collector Output : 5 to 24V DC 50mA or less Residual voltage : 1.3V or less (at 50mA load current) OFF-state current 0.5mA or less		
Response frequency	1kHz or above (3kHz in average)		
Ambient illuminance	Fluorescent light : 1000 lx at the light-receiving face		
Ambient temperature	Operation: -25 to +55°C, Storage: -30 to +80°C (no dew condensation or icing allowed)		
Ambient humidity	Operation: 5 to 85% RH, Storage: 5 to 95% RH (no dew condensation or icing allowed)		
Vibration resistance	20 to 2000Hz (100m/s ² peaked acceleration), 1.5mm amplitude in X, Y and Z directions for 2 hours each (4min. cycle)		
Shock resistance	500m/s ² in X, Y and Z directions for 3 times each		
Protection	IP50 IEC60529		
Connection	Connector (available for direct soldering)		
Mass	3g approx.		
Material	Case	Poly Butylene Terephthalate (PBT)	
	Cover		
	Terminal	Polycarbonate	

Accessories	Specifications			
	C	P	H (Note 2)	J (Note 2)
Sensor Model No.	EE-SX674 (NPN) : 3	EE-SX674P (PNP) : 3	EE-SX671 (NPN) : 3	EE-SX671P (PNP) : 3
Connector for sensor	EE-1001: 3	EE-1001: 3	EE-1001: 3	EE-1001: 3
Sensor rail	: 1	: 1	: 1	: 1
Sensor dog (Note 3)	: 1	: 1	: 1	: 1
Sensor mounting plate (Note 1)	: 3	: 3		

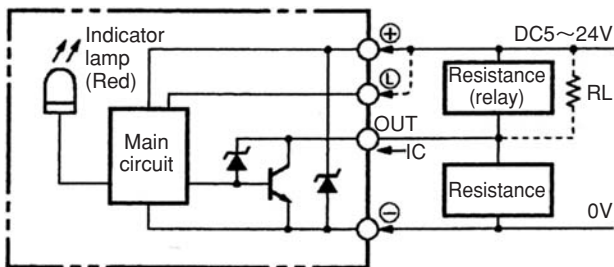
(Note 1) Sensor mounting plate is applied to SE and SC series.

(Note 2) If H or J configuration is used for the model without cover in SG33 series, a sensor mounting plate is attached in addition to the above-mentioned accessories.

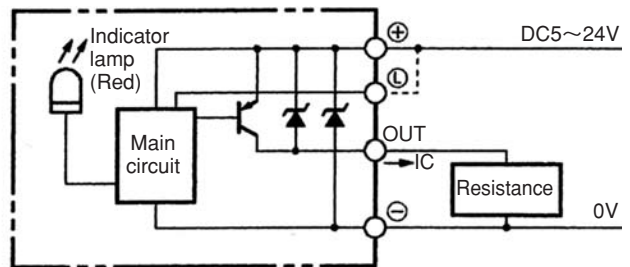
(Note 3) 2 sensor dogs are used for M or Y configuration of SG33□D-150.

● I/O circuit diagram

NPN output type



PNP output type



(Note) For detailed information and operating precautions, refer to catalogs and operating instructions supplied by the sensor maker.

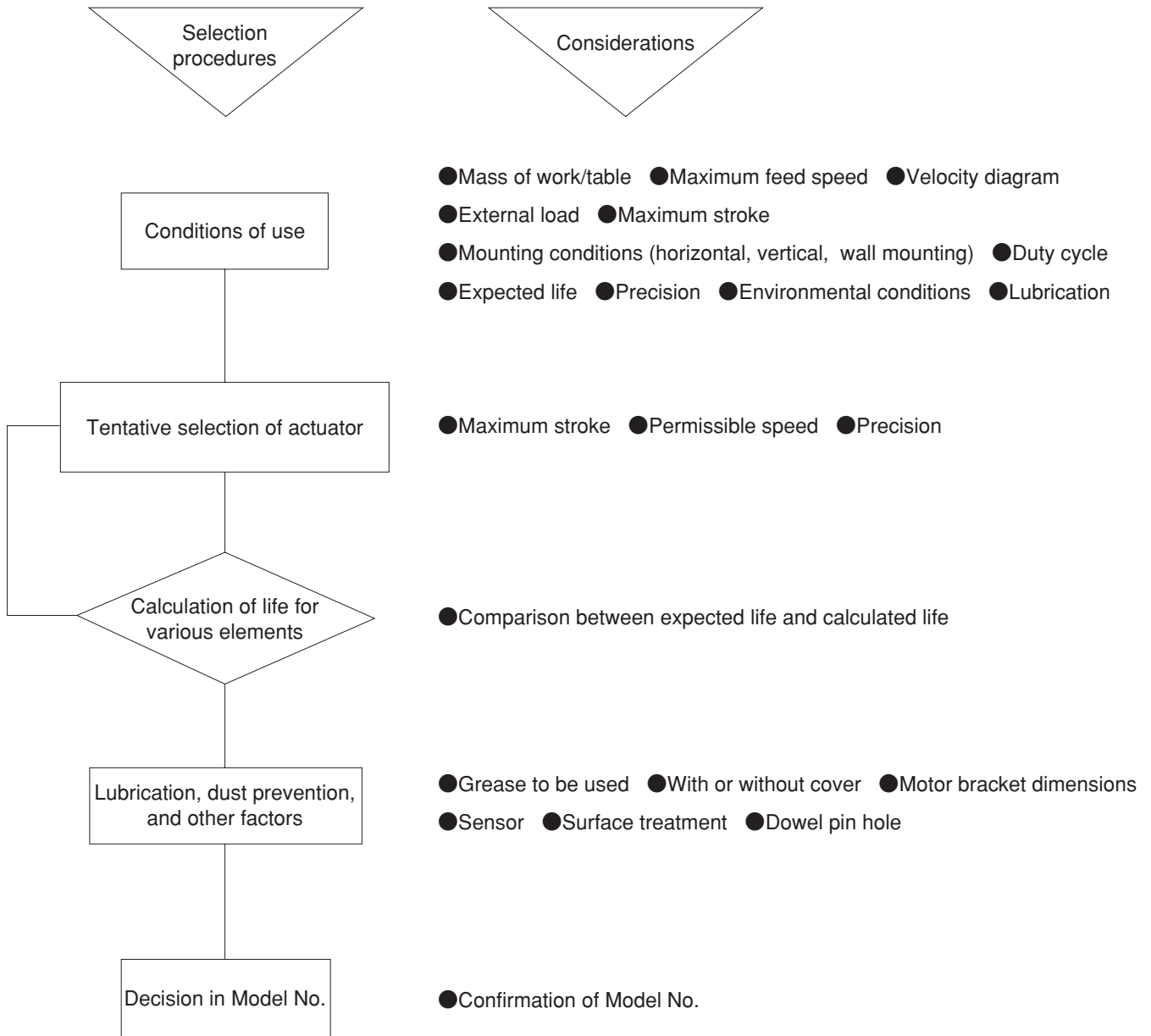
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BALLSCREW ACTUATOR SELECTION GUIDE

Similar to ball screw selections, there is no instant way of selecting appropriate ballscrew actuators for various purposes. The following is an example of general procedures in actuator selection, with some considerations to be made on each step and pages to refer to.



LIFE EXPECTANCY

The shortest life expectancy of among guid-rail, ballscrew and support bearing can be defined as the life expectancy of ballscrew actuators, SE, SG, and SC series.

The following formula is used to calculate the life expectancy.

LIFE EXPECTANCY OF GUIDE

Calculate the life expectancy of guide using the following formula:

$$L_G = \left(\frac{f_c \cdot C}{f_w \cdot P_T} \right)^3 \cdot 50 \text{ ————— Formula (1)}$$

L_G : Life expectancy operational length (km)

f_c : Contact factor (see Table 1)

f_w : Load factor (see Table 2)

C : Basic dynamic load rating (N)

P_T : Calculated load per block (N)

Calculation of P_T

To calculate the life expectancy using Formula (1), you need to obtain the calculated load per block (P_T) in consideration of actual moment load.

If the acceleration is high or short-stroke operation is conducted, calculate P_T in consideration of acceleration. This acceleration calculation is made for a mass loaded on SG, SE, and SC.

Obtain the calculated load in uniform motion, accelerated motion, and decelerated motion, and its average figure is used as P_T .

For the calculation of P_T , select a calculation formula according to the installation conditions.

If acceleration needs not to be considered,

$P_T = P_{TC}$ (See Formula (2), (5) and (8)) can be used for calculation. However, you can calculate only the approximate value in this formula, therefore it is recommended that you calculate the life expectancy with an ample margin.

Table 1 Contact factor (f_c)

Number of blocks to be used in contact, when single axis module is used.	Contact factor (f_c)
1	0.1
2	0.81

Table 2 Load factor (f_w)

Operating condition		Load factor (f_w)
Vibration and shock	Speed	
Zero	15m/min or less	1.0~1.5
Small	60m/min or less	1.0~2.0
Large	60m/min or more	2.0~3.5

Table 3 Moment equivalent factor

	Ep(E2p)	Ey(E2p)	Er(E2r)
SG20**A	2.25×10^{-1}	1.89×10^{-1}	7.84×10^{-2}
SG20**B	3.98×10^{-2}	3.34×10^{-2}	3.92×10^{-2}
SG26**A	1.51×10^{-1}	1.27×10^{-1}	5.88×10^{-2}
SG26**B	2.72×10^{-2}	2.28×10^{-2}	2.94×10^{-2}
SG33**A	1.26×10^{-1}	1.06×10^{-1}	4.55×10^{-2}
SG33**B	2.20×10^{-2}	1.84×10^{-2}	2.27×10^{-2}
SG33**C	2.31×10^{-1}	1.94×10^{-1}	4.55×10^{-2}
SG33**D	3.09×10^{-2}	2.59×10^{-2}	2.27×10^{-2}
SG46**A	8.39×10^{-2}	7.04×10^{-2}	3.17×10^{-2}
SG46**B	1.56×10^{-2}	1.31×10^{-2}	1.59×10^{-2}
SG46**C	1.39×10^{-1}	1.17×10^{-1}	3.17×10^{-2}
SG46**D	2.15×10^{-2}	1.18×10^{-2}	1.59×10^{-2}
SG55**A	6.80×10^{-2}	5.71×10^{-2}	2.74×10^{-2}
SG55**B	1.35×10^{-2}	1.14×10^{-2}	1.37×10^{-2}
SE15**A	2.70×10^{-1}	2.45×10^{-1}	9.64×10^{-2}
SE15**B	4.50×10^{-2}	3.80×10^{-2}	4.82×10^{-2}
SE23**A	1.52×10^{-1}	1.37×10^{-1}	5.22×10^{-2}
SE23**B	2.54×10^{-2}	2.29×10^{-2}	2.61×10^{-2}
SE30**A	1.17×10^{-1}	9.83×10^{-2}	4.54×10^{-2}
SE30**B	1.95×10^{-2}	1.64×10^{-2}	2.27×10^{-2}
SE45**A	8.39×10^{-2}	7.04×10^{-2}	3.17×10^{-2}
SE45**B	1.56×10^{-2}	1.31×10^{-2}	1.59×10^{-2}
SE45**C	1.26×10^{-1}	1.06×10^{-1}	3.17×10^{-2}
SE45**D	2.10×10^{-2}	1.76×10^{-2}	1.59×10^{-2}
SC23**A	1.52×10^{-1}	1.37×10^{-1}	5.22×10^{-2}
SC30**A	1.17×10^{-1}	9.83×10^{-2}	4.54×10^{-2}
SC45**A	8.39×10^{-2}	7.04×10^{-2}	3.17×10^{-2}

(Note) The specifications of a model with two blocks show factors when the two blocks are used in contact.

● P_T in the case of Horizontal Movement (Horizontal Installation)

① For uniform motion (P_{Tc})

$$P_{Tc} = \frac{1}{n} \cdot W + E_p \cdot M_{pL} + E_y \cdot M_{yL} + E_r \cdot M_{rL} \text{——Formula (2)}$$

② For accelerated motion (P_{Ta})

$$P_{Ta} = \frac{1}{n} \cdot W + E_p (M_{pL} + m \cdot a_a \cdot Z) + E_y (M_{yL} + m \cdot a_a \cdot X) + E_r \cdot M_{rL} \text{——Formula (3)}$$

If item $(M_{pL} + m \cdot \alpha_a \cdot Z)$ or $(M_{yL} + m \cdot \alpha_a \cdot X)$ is a negative value, the value should be set to 0.

③ For decelerated motion (P_{Td})

$$P_{Td} = \frac{1}{n} \cdot W + E_p (M_{pL} + m \cdot \alpha_d \cdot Z) + E_y (M_{yL} + m \cdot \alpha_d \cdot X) + E_r \cdot M_{rL} \text{——Formula (4)}$$

If item $(M_{pL} + m \cdot \alpha_d \cdot Z)$ or $(M_{yL} + m \cdot \alpha_d \cdot X)$ is a negative value, the value should be set to 0.

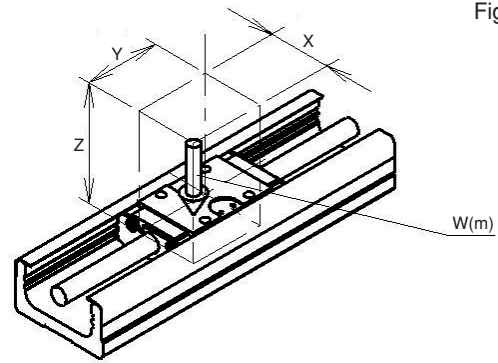


Figure 1

If a load is applied from a different direction other than W (m) in this figure, contact KURODA.

P_{Tc} : Calculated load per block in uniform motion (N)

P_{Ta} : Calculated load per block in accelerated motion (N)

P_{Td} : Calculated load per block in decelerated motion (N)

n : Number of block of SG / SE / SC

W : Load (N)

m : Load mass (kg)

α_a : Acceleration in accelerated motion (m/sec²)

α_d : Acceleration in decelerated motion (m/sec²) (with a minus sign)

X : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)

Y : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)

Z : Distance from center of SG / SE / SC ballscrew to center of gravity of loaded mass (mm)

E_p : Moment equivalent factor in pitching direction (see Table 3)

E_y : Moment equivalent factor in yawing direction (see Table 3)

E_r : Moment equivalent factor in rolling direction (see Table 3)

M_{pL} : Load moment in pitching direction (N·mm)

$$M_{pL} = W \cdot Y$$

M_{yL} : Load moment in yawing direction (N·mm)

$$M_{yL} = 0 \text{ (The load moment is zero under this usage.)}$$

M_{rL} : Load moment in rolling direction (N·mm)

$$M_{rL} = W \cdot X$$

(Note) For the moment directions, see Pages 3, 53 and 91.

● P_T in the Case of Horizontal Movement (Wall Installation)

① For uniform motion (P_{Tc})

$$P_{Tc} = \frac{1}{1.19 \cdot n} \cdot W + E_p \cdot M_{pL} + E_y \cdot M_{yL} + E_r \cdot M_{rL} \text{——Formula (5)}$$

② For accelerated motion (P_{Ta})

$$P_{Ta} = \frac{1}{1.19 \cdot n} \cdot W + E_p (M_{pL} + m \cdot a_a \cdot Z) + E_y (M_{yL} + m \cdot a_a \cdot X) + E_r \cdot M_{rL} \text{——Formula (6)}$$

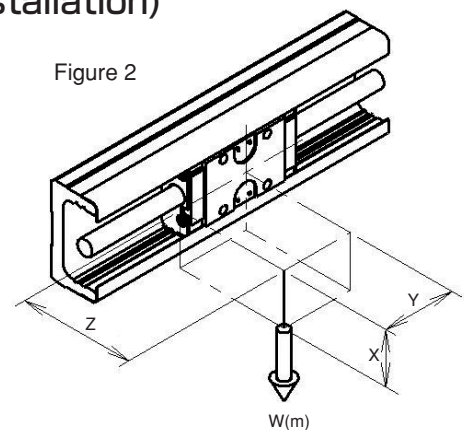
If item $(M_{pL} + m \cdot a_a \cdot Z)$ or $(M_{yL} + m \cdot a_a \cdot X)$ is a negative value, the value should be set to 0.

③ For decelerated motion (P_{Td})

$$P_{Td} = \frac{1}{1.19 \cdot n} \cdot W + E_p (M_{pL} + m \cdot \alpha_d \cdot Z) + E_y (M_{yL} + m \cdot \alpha_d \cdot X) + E_r \cdot M_{rL} \text{——Formula (7)}$$

If item $(M_{pL} + m \cdot \alpha_d \cdot Z)$ or $(M_{yL} + m \cdot \alpha_d \cdot X)$ is a negative value, the value should be set to 0.

Figure 2



If load is applied from a different direction other than W (m), contact KURODA.

P_{Tc} : Calculated load per block in uniform motion (N)

P_{Ta} : Calculated load per block in accelerated motion (N)

P_{Td} : Calculated load per block in decelerated motion (N)

n : Number of block of SG / SE / SC

W : Load (N)

m : Load mass (kg)

α_a : Acceleration in accelerated motion (m/sec²)

α_d : Acceleration in decelerated motion (m/sec²) (with a minus sign)

X : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)

Y : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)

Z : Distance from center of SG / SE / SC ballscrew to center of gravity of loaded mass (mm)

E_p : Moment equivalent factor in pitching direction (see Table 3)

E_y : Moment equivalent factor in yawing direction (see Table 3)

E_r : Moment equivalent factor in rolling direction (see Table 3)

M_{pL} : Load moment in pitching direction (N·mm)

$$M_{pL} = 0 \text{ (The load moment is zero under this usage.)}$$

M_{yL} : Load moment in yawing direction (N·mm)

$$M_{yL} = W \cdot Y$$

M_{rL} : Load moment in rolling direction (N·mm)

$$M_{rL} = W \cdot Z$$

(Note) For the moment directions, see Pages 3, 53 and 91.

● P_T in the Case of Vertical Movement

① For uniform motion (P_{TC})

$$P_{TC} = E_p \cdot M_{pL} + E_y \cdot M_{yL} + E_r \cdot M_{rL} \text{ — Formula (8)}$$

② For accelerated motion (P_{Ta})

$$P_{Ta} = E_p (M_{pL} + m \cdot a_a \cdot Z) + E_y (M_{yL} + m \cdot a_a \cdot X) + E_r \cdot M_{rL} \text{ — Formula (9)}$$

If item $(M_{pL} + m \cdot a_a \cdot Z)$ or $(M_{yL} + m \cdot a_a \cdot X)$ is a negative value, the value should be set to 0.

③ For decelerated motion (P_{Td})

$$P_{Td} = E_p (M_{pL} + m \cdot a_d \cdot Z) + E_y (M_{yL} + m \cdot a_d \cdot X) + E_r \cdot M_{rL} \text{ — Formula (10)}$$

If item $(M_{pL} + m \cdot a_d \cdot Z)$ or $(M_{yL} + m \cdot a_d \cdot X)$ is a negative value, the value should be set to 0.

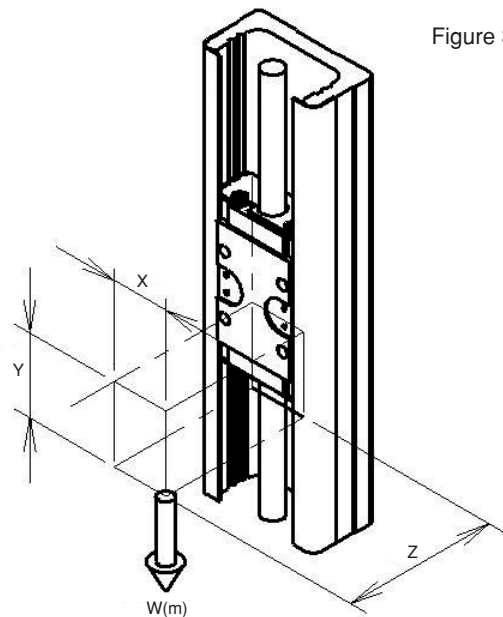


Figure 3

If load is applied from a different direction other than $W(m)$ in this figure, contact KURODA.

P_{TC} : Calculated load per block in uniform motion (N)

P_{Ta} : Calculated load per block in accelerated motion (N)

P_{Td} : Calculated load per block in decelerated motion (N)

n : Number of block of SG / SE / SC

W : Load (N)

m : Load mass (kg)

a_a : Acceleration in accelerated motion (m/sec²)

a_d : Acceleration in decelerated motion (m/sec²) (with a minus sign)

X : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)

Y : Distance from center of SG / SE / SC to center of gravity of loaded mass (mm)

Z : Distance from center of SG / SE / SC ballscrew to center of gravity of loaded mass (mm)

E_p : Moment equivalent factor in pitching direction (see Table 3)

E_y : Moment equivalent factor in yawing direction (see Table 3)

E_r : Moment equivalent factor in rolling direction (see Table 3)

M_{pL} : Load moment in pitching direction (N·mm)

$$M_{pL} = W \cdot Z$$

M_{yL} : Load moment in yawing direction (N·mm)

$$M_{rL} = W \cdot X$$

M_{rL} : Load moment in rolling direction (N·mm)

$$M_{yL} = 0 \text{ (The load moment is zero under this usage.)}$$

(Note) For the moment directions, see Pages 3, 53 and 91.

● Using one of the above calculation formulas according to your usage, calculate average load in each motion to obtain calculated load per block (P_T).

$$P_T = \sqrt[3]{\frac{1}{(S1+S2+S3)} (P_{Ta}^3 \cdot S1 + P_{TC}^3 \cdot S2 + P_{Td}^3 \cdot S3)} \text{ — Formula (11)}$$

P_T : Calculated load per block (N)

$S1$: Traveling distance in accelerated motion (mm) (see Figure 4)

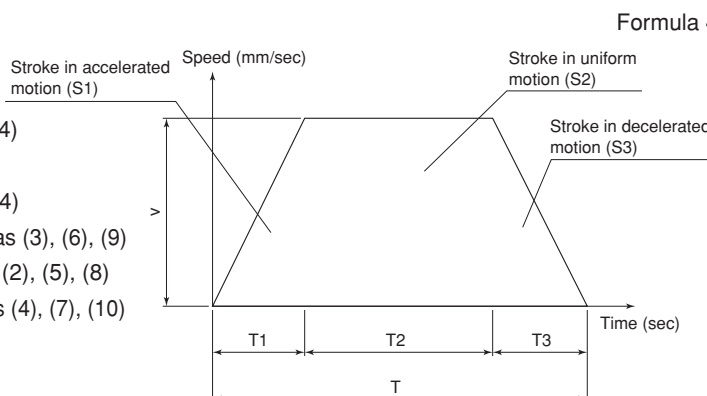
$S2$: Traveling distance in uniform motion (mm) (see Figure 4)

$S3$: Traveling distance in decelerated motion (mm) (see Figure 4)

P_{Ta} : Calculated load per block in accelerated motion (N) - Formulas (3), (6), (9)

P_{TC} : Calculated load per block in uniform motion (N) - Formulas (2), (5), (8)

P_{Td} : Calculated load per block in decelerated motion (N) - Formulas (4), (7), (10)



Formula 4

● LIFE EXPECTANCIES OF BALL SCREW AND SUPPORT BEARING

The life expectancies of the ball screw and the support bearing can be calculated using the following common calculation formula shown as below. Therefore, compare the dynamic load ratings of the ball screw and the support bearing and substitute a smaller value in the formula for calculation.

$$L_a = \left(\frac{1}{f_w} \cdot \frac{C_a \text{ or } C_b}{P_a} \right)^3 \cdot \ell \text{ ————— Formula (12)}$$

L_a : Life expectancy operational length (km)

f_w : Load factor (see Table 2)

C_a : Basic dynamic load rating of ball screw (N)

C_b : Basic dynamic load rating of support bearing (N)

P_a : Axial load (N)

ℓ : Ball screw lead (mm)

● Calculation of P_a

To calculate the life expectancy using Formula (6), calculate P_a in consideration of acceleration. Calculate the axial load in uniform, accelerated, and decelerated motions and its average figure is used as P_a .

● In the Case of Horizontal Movement

① For uniform motion (P_{ac})

$$P_{ac} = m \cdot W + F + F_b \cdot n \text{ ————— Formula (13)}$$

② For accelerated motion (P_{aa})

$$P_{aa} = m \cdot W + F + f_b \cdot n + (m + m_b \cdot n) \alpha_a \text{ ————— Formula (14)}$$

③ For decelerated motion (P_{ad})

$$P_{ad} = m \cdot W + F + f_b \cdot n - (m + m_b \cdot n) \alpha_d \text{ ————— Formula (15)}$$

P_{ac} : Axial load rating in uniform motion (N)

P_{aa} : Axial load rating in accelerated motion (N)

P_{ad} : Axial load rating in decelerated motion (N)

μ : Friction factor (0.006)

W : Load on block (N)

F : External force (load) in axial direction (N)

f_b : Slide resistance per block (N) (see Table 4)

n : Number of blocks of SG / SE

m : Load mass (kg)

m_b : Block mass of SG / SE (kg)

g : Gravitational acceleration (9.8 m / sec²)

α_a : Acceleration in accelerated motion (m / sec²)

α_d : Acceleration in decelerated motion (m / sec²)

● In the Case of Vertical Movement

① For uniform motion (P_{ac})

$$P_{ac} = (m + m_b \cdot n) g + F + f_b \cdot n \text{ ————— Formula (16)}$$

② For accelerated motion (P_{aa})

$$P_{aa} = (m + m_b \cdot n) \cdot (g + \alpha_a) + F + f_b \cdot n_a \text{ ————— Formula (17)}$$

③ For decelerated motion (P_{ad})

$$P_{ad} = (m + m_b \cdot n) \cdot (g - \alpha_d) + F + f_b \cdot n_d \text{ ————— Formula (18)}$$

● Using one of the above calculation formulas according to your usage, calculate an average axial load (P_a).

$$P_a = \sqrt[3]{\frac{1}{(S1+S2+S3)} (P_{aa}^3 \cdot S1 + P_{ac}^3 \cdot S2 + P_{ad}^3 \cdot S3)} \text{ ————— Formula (19)}$$

P_a : Average axial load (N)

$S1$: Traveling distance in accelerated motion (mm) (see Figure 4)

$S2$: Traveling distance in uniform motion (mm) (see Figure 4)

$S3$: Traveling distance in decelerated motion (mm) (see Figure 4)

P_{aa} : Axial load in accelerated motion (N) - Formulas (14), (17)

P_{ac} : Axial load in uniform motion (N) - Formulas (13), (16)

P_{ad} : Axial load in decelerated motion (N) - Formulas (15), (18)

Table 4 Slide resistance per block (f_b) (seal resistance)
(Unit: N)

Model No.	Accuracy grade	
	H	P
SG20	2.3	4.9
SG26	5.4	9.8
SG33	4.4	10.2
SG46	7.4	13.3
SG55	9	16

(Unit: N)

Model No.	Accuracy grade
	U/W
SE15	2.0
SE23, SC23	2.5
SE30, SC30	2.5
SE45, SC45	7.5

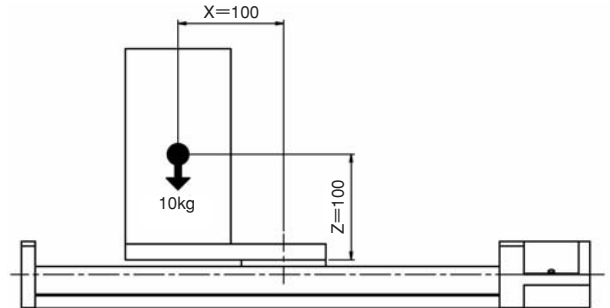
EXAMPLE OF BALLSCREW ACTUATOR SELECTION

● Linear motion robot - X-axis

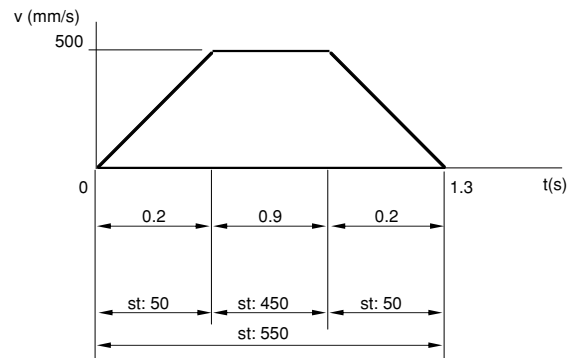
<Specifications>

Mass of work and table: M	10kg
Load distribution	See right side diagram.
Maximum stroke: st	550mm
Fast-feed speed: v	500mm/s
Acceleration/deceleration time constant: t	0.2 s
Maximum motor speed	6000min ⁻¹
Orientating orientation	Horizontal
Repeated positioning accuracy	±0.01 mm or less
Expected life	30,000h

Load distribution diagram



Duty cycle model diagram



① Tentatively select SE4510A-740W-A1NN-NN in SE series, based on the conditions such as stroke and speed.

② Calculation of life expectancy

②-1. Calculating life expectancy of guide

Considering the usage with moment being loaded, average load and life expectancy were calculated in accordance with "LIFE EXPECTANCY OF GUIDE" on page 111, and they resulted in 1,274 N and 39,030 hours, respectively. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

②-2. Calculating expected life of ball screw and support bearings

Average axial load and life expectancy were calculated in accordance with "LIFE EXPECTANCIES OF BALL SCREW AND SUPPORT BEARING" on page 114, and the axial load resulted in 14.9 N and expected life of both ball screw and support bearing in over a million hours. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

③ Results of the selection

The above calculation results of life expectancies confirmed that the tentatively selected model would satisfy the required specifications. Since there is no other particular specification to be further considered, the model is selected officially.

Selected model of ballscrew actuator: SE4510A-740W-A1NN-NN

If longer life expectancy than the calculated life is preferred, make re-calculation after changing specifications, such as upgrading model size or adding extra slide block.

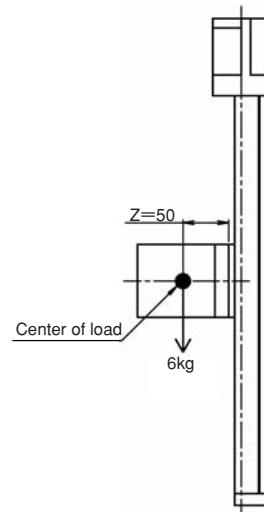
EXAMPLE OF BALLSCREW ACTUATOR SELECTION

● Lift - Z-axis

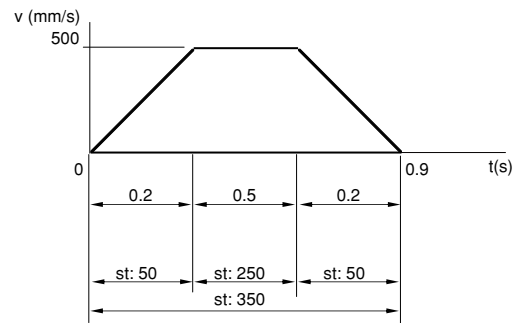
<Specifications>

Mass of work and table: M	6kg
Load distribution	See right side diagram.
Maximum stroke: st	350mm
Fast-feed speed: v	500mm/s
Acceleration/deceleration time constant: t	0.2 s
Maximum motor speed	6000min ⁻¹
Orientating orientation	Vertical
Repeated positioning accuracy	±0.003 mm or less
Life expectancy	40,000h

Load distribution diagram



Duty cycle model diagram



① Tentative selection of ballscrew actuator

Tentatively select SG3310A-500H-A0NN-NN in SG series, based on the conditions such as strokes and speed.

② Calculation of life expectancy

②-1. Calculating life expectancy of guide

Considering the usage with moment being loaded, average load and life expectancy were calculated in accordance with "LIFE EXPECTANCY OF GUIDE" on page 111, and they resulted in 805 N and 17,166 hours, respectively. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

②-2. Calculating expected life of ball screw and support bearing

Average axial load and life expectancy were calculated in accordance with "LIFE EXPECTANCIES OF BALL SCREW AND SUPPORT BEARING" on page 114, and the axial load resulted in 60N and expected life of ball screw and support bearing in 44,202 and 353,620 hours, respectively. The load coefficient for the above calculation was determined to be 2, based on the conditions of use.

③ Results of the selection

According to the above results of life expectancies, the life of the guide does not satisfy the life expectancy requirement. Since the ball screw and support bearing have satisfactory life expectancies, make re-calculation after changing the block on the guide. Leaving the guide rail length and required stroke as they are, change the model to SG3310D-500H-A0NN-NN.

④ Re-calculation of life

As in the previous step, average load and life expectancy were calculated in accordance with "LIFE EXPECTANCY OF GUIDE" on page 111, and they resulted in 198 N (load per block) and 146,740 hours, respectively.

⑤ Results of the re-selection

The results of re-calculation of life expectancy of the guide confirmed that the selected model would satisfy required hours of life expectancy.

BALLSCREW ACTUATOR SPECIFICATION DATA SHEET (SAMPLE)

Company Name	XYZ Industries, Co., Ltd.	Date	SAMPLE
Department	Stage design dept.	Contact personnel	
Address		Tel • Fax	
Name of equipment/machine used		Location of use	Work transfer
Drawing/conceptual drawing attached?	<input type="checkbox"/> Yes pieces of pages	<input type="checkbox"/> No	

Conditions of Use (Either unit system may be used.)

Mass of work and table	10 kg			
Operating orientation	<input checked="" type="checkbox"/> Horizontal	<input type="checkbox"/> Vertical	<input type="checkbox"/> Wall installation	<input type="checkbox"/> Other
Maximum table speed	1000 mm/s	Maximum table stroke		550 mm
Mount/support method	<input checked="" type="checkbox"/> Fixed - support (standard)	<input type="checkbox"/> Fixed - fixed (semi-fixed)	<input type="checkbox"/> Fixed - free	<input type="checkbox"/> Support - support
Moving conditions	Oscillation	<input type="checkbox"/> Yes	<input checked="" type="checkbox"/> No	Range of oscillation _____ m m
Vibration impact level	No impact			
Expected life	20,000 hours or above			

Operating conditions (Select either Case A or B below and describe the operating conditions)
 Case A (when axial load and revolving speed can be classified into several patterns) - Please attach a separate document if your descriptions do not fit in the following table.

No. of patterns	Axial load	Revolving speed	Hours or ratio of use
1			
2			
3			

Case B (when largely impacted by inertial force) - Please attach a separate document if your descriptions do not fit in the following table.

No. of patterns	Strokes	Table speed	Acceleration time	Constant-speed time	Deceleration time
1	550	1000	0.2	0.35	0.2
2					
3					

Load distribution (see below) X = 0 Y = 100 Z = 100

Horizontal 	Vertical 	Wall installation
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Lubrication	Grease (brand)	Unless otherwise specified, Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) will be used as lubricant.						
Environmental conditions	Temp.	Dust	Humidity	Gas	Liquid	Clean room	Vacuum	Others
	23°C	No dust	%	No gas	In			
Name of motor					Parallel motor mounting	<input type="checkbox"/> Required	<input checked="" type="checkbox"/> Not required	
Actuator quantity per a machine	2			Quantity for prototype				
Quantity for mass production	6		Change control		<input type="checkbox"/> Yes		<input checked="" type="checkbox"/> No	

Ball screw actuator specifications

Size	Lead	Slide block	Guide rail length	Precision grade
Dust-preventive cover	Sensor	Surface treatment		

Additional description/request

KURODA office	Contact personnel
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Technical Data

BALLSCREW ACTUATOR SPECIFICATION DATA SHEET

Company Name		Date	
Department		Contact personnel	
Address		Tel • Fax	
Name of equipment/machine used		Location of use	
Drawing/conceptual drawing attached?	<input type="checkbox"/> Yes	pieces of pages	<input type="checkbox"/> No

Conditions of Use (Either unit system may be used.)

Mass of work and table				
Operating orientation	<input type="checkbox"/> Horizontal	<input type="checkbox"/> Vertical	<input type="checkbox"/> Wall installation	<input type="checkbox"/> Other
Maximum table speed	1000 mm/s	Maximum table stroke		
Mount/support method	<input type="checkbox"/> Fixed - support (standard)	<input type="checkbox"/> Fixed - fixed (semi-fixed)	<input type="checkbox"/> Fixed - free	<input type="checkbox"/> Support - support
Moving conditions	Oscillation	<input type="checkbox"/> Yes	<input type="checkbox"/> No	Range of oscillation m m
Vibration impact level				
Expected life				

Operating conditions (Select either Case A or B below and describe the operating conditions)

Case A (when axial load and revolving speed can be classified into several patterns) - Please attach a separate document if your descriptions do not fit in the following table.

No. of patterns	Axial load	Revolving speed	Hours or ratio of use
1			
2			
3			

Case B (when largely impacted by inertial force) - Please attach a separate document if your descriptions do not fit in the following table.

No. of patterns	Strokes	Table speed	Acceleration time	Constant-speed time	Deceleration time
1					
2					
3					

Load distribution (see below) X = Y = Z =

Horizontal		Vertical		Wall installation	
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Lubrication	Grease (brand)	Unless otherwise specified, Multemp PS No.2 Grease (KYODO YUSHI CO., LTD.) will be used as lubricant.						
Environmental conditions	Temp.	Dust	Humidity	Gas	Liquid	Clean room	Vacuum	Others
Name of motor					Parallel motor mounting	<input type="checkbox"/> Required	<input type="checkbox"/> Not required	
Actuator quantity per a machine					Quantity for prototype			
Quantity for mass production					Change control	<input type="checkbox"/> Yes	<input type="checkbox"/> No	

Ballscrew actuator specifications

Size	Lead	Slide block	Guide rail length	Precision grade
Dust-preventive cover	Sensor	Surface treatment		

Additional description/request

KURODA office		Contact personnel	

Technical Data

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